



Development and Evaluation of a General Drag Model for Gas-Solid Flows via Physics-Informed Deep Machine Learning

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*Knight Foundation School of Computing and Information Sciences

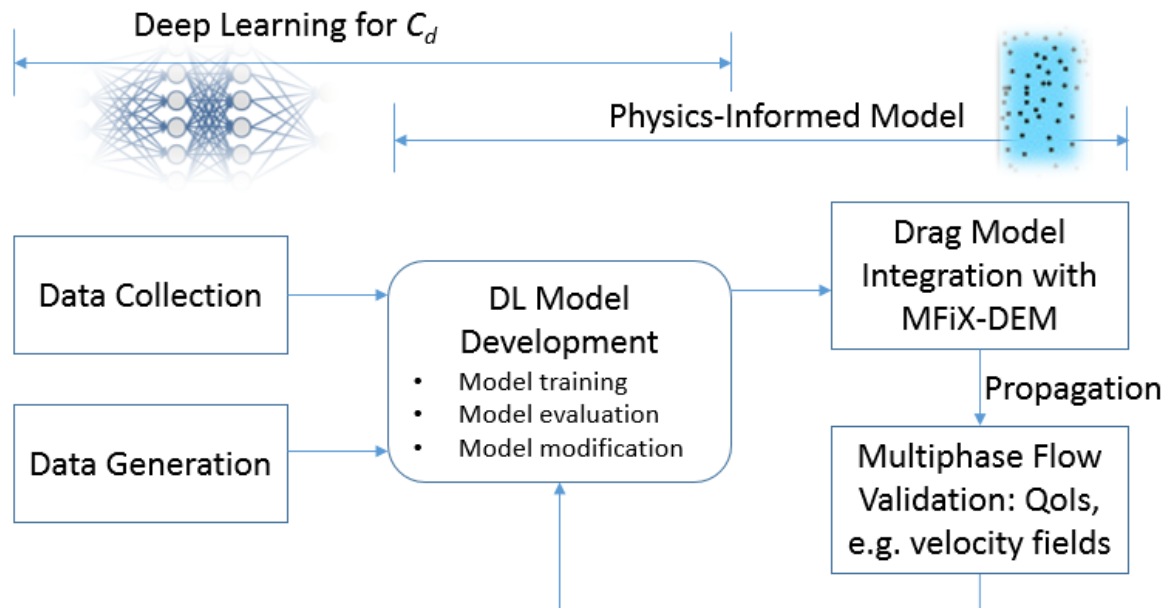
Florida International University, Miami

Agenda

- Project Objective
- Project Status
- Technical Progress
 - Background/Motivation for the Project
 - Data collection
 - Features considered
 - Gated DNN modeling
 - Integration with MFiX
 - CFD validation with single particle
 - Assemblies of particles
 - CFD validation with Fluidized bed
- Conclusions

Project Objective

The overall objective of this project is to develop, test, and validate a general drag model for multiphase flows in assemblies of non-spherical particles by a physics-informed deep machine learning (PIDML) approach using artificial neural network (ANN).



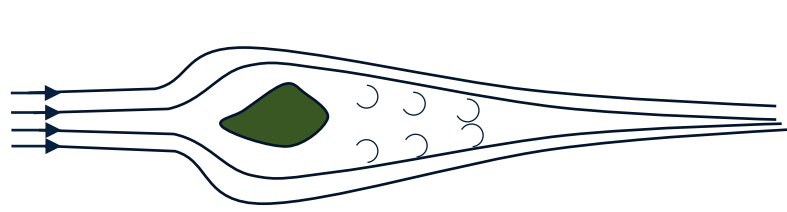
CFD Software



Project Status

Task Name	Assigned Resources	Year 1				Year 2				Year 3			
		Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4
Task 1.0 - Project Management and Planning	PI												
Task 2.0 - Data Collection and Generation	Team												
Subtask 2.1 Data Collection	Team												
Milestone A													
Subtask 2.2 Data Generation	Co-PI												
Milestone B													
Decision Point 1	Team												
Task 3.0 - ANN Model Development	Co-PI												
Subtask 3.1 ANN Model Training & Test	Co-PI												
Milestone C													
Subtask 3.2 ANN Algorithm Evaluation	Team												
Milestone D													
Decision Point 2	Team												
Task 4.0 - Drag Model Integration	Team												
Milestone E													
Decision Point 3	Team												
Task 5.0 - Multiphase Flow CFD Validation	Team												
Subtask 5.1 Multiphase Flow Validation	PI												
Milestone F													
Subtask 5.2 ANN Model Modification	Co-PI												
Milestone G													

Motivation

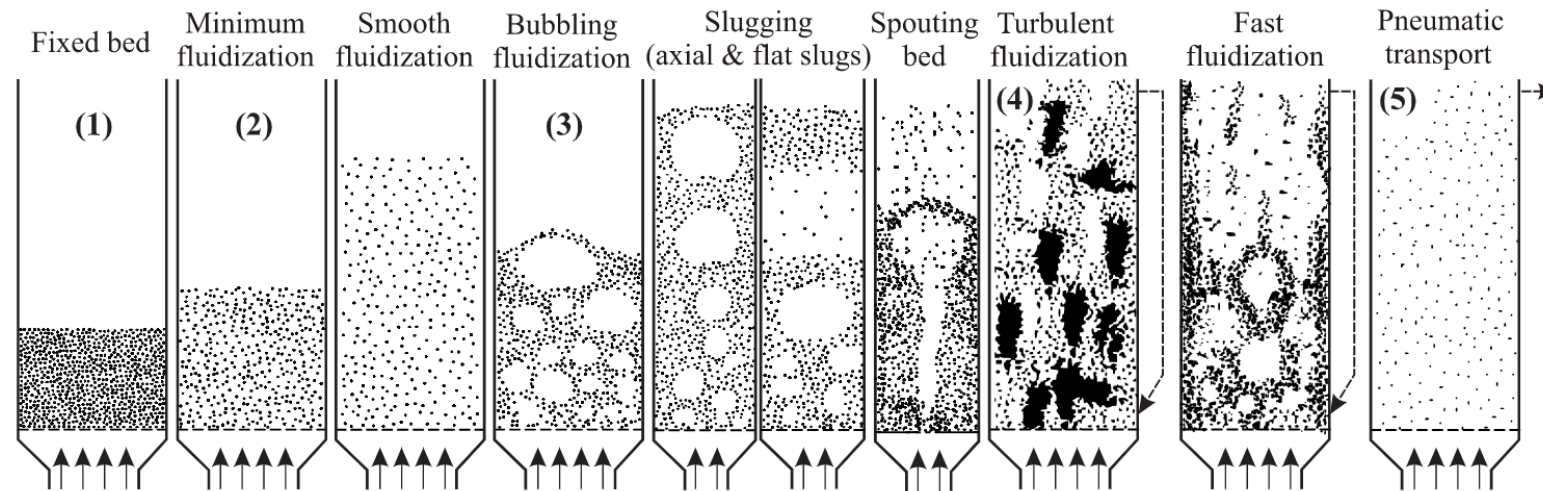


$$\text{Drag force } (F_D) = \frac{1}{2} \rho_g |V_r|^2 A_p C_D$$

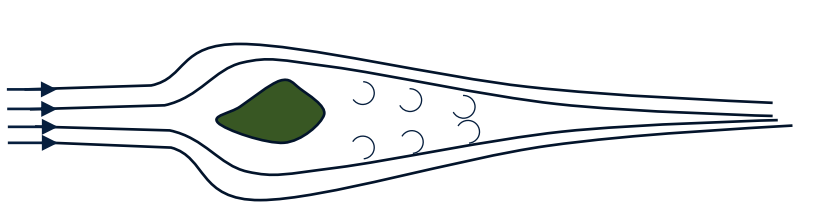


$$\rho_g \frac{DV}{Dt} = -\nabla p + \nabla \vec{\tau} + \vec{F}_D$$

1. Energy industry
 - Gasifiers
 - Combustion
2. Food industry
3. Chemical process

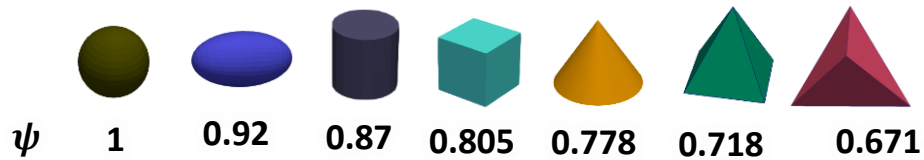


Motivation



$$\text{Drag force } (F_D) = \frac{1}{2} \rho_g |V_r|^2 A_p C_D$$

$$\rho_g \frac{DV}{Dt} = -\nabla p + \nabla \vec{\tau} + \vec{F}_D$$

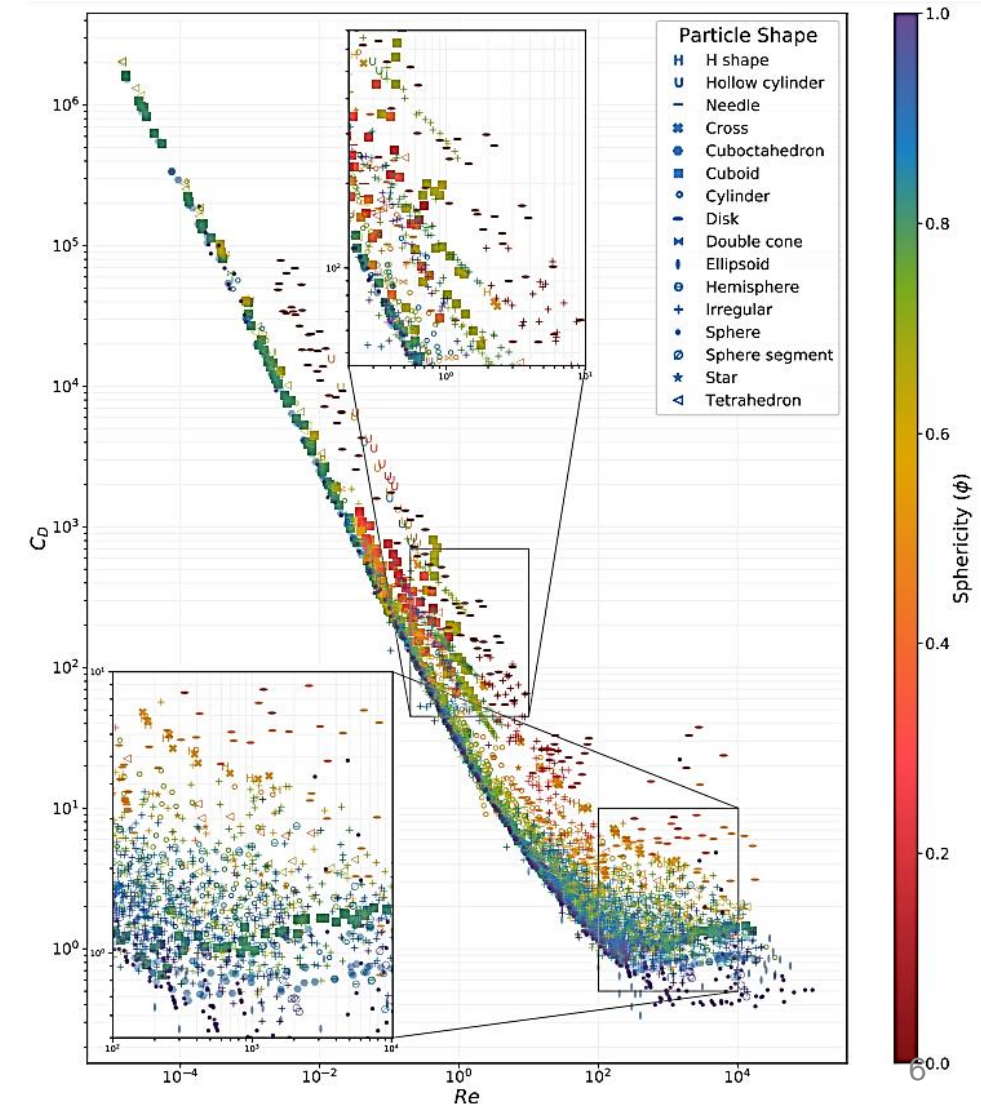


- The drag coefficient primarily depends on
 - Shape
 - Reynold number
- The variations are highly non-linear
- Single correlation cannot cover all the particles
- Requires more sophisticated modelling such as Neural network

Cube



Spheroid



Current State-of-Art

$$C_D = \frac{24}{Re} (1 + 8.1716 \exp(-4.0655\psi) * Re^{0.0964+0.5565\psi} + 73.69 * Re * \frac{\exp(-5.0748 \psi)}{Re + 5.378 \exp(6.2122 \psi)}) \quad \psi > 0.67$$

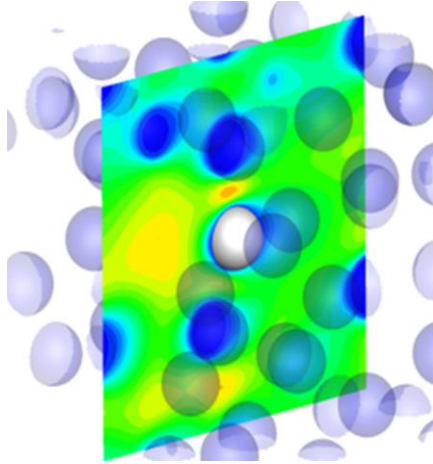
- Haider & Levenspiel (1989)
- Yow et al. (2005)
- Hölzer & Sommerfeld (2008)
- He & Tafti (2019)
- Yan et al. (2019)

$$C_D = \frac{a_1}{Re} + \frac{b_1}{\sqrt{Re}} + c_1$$

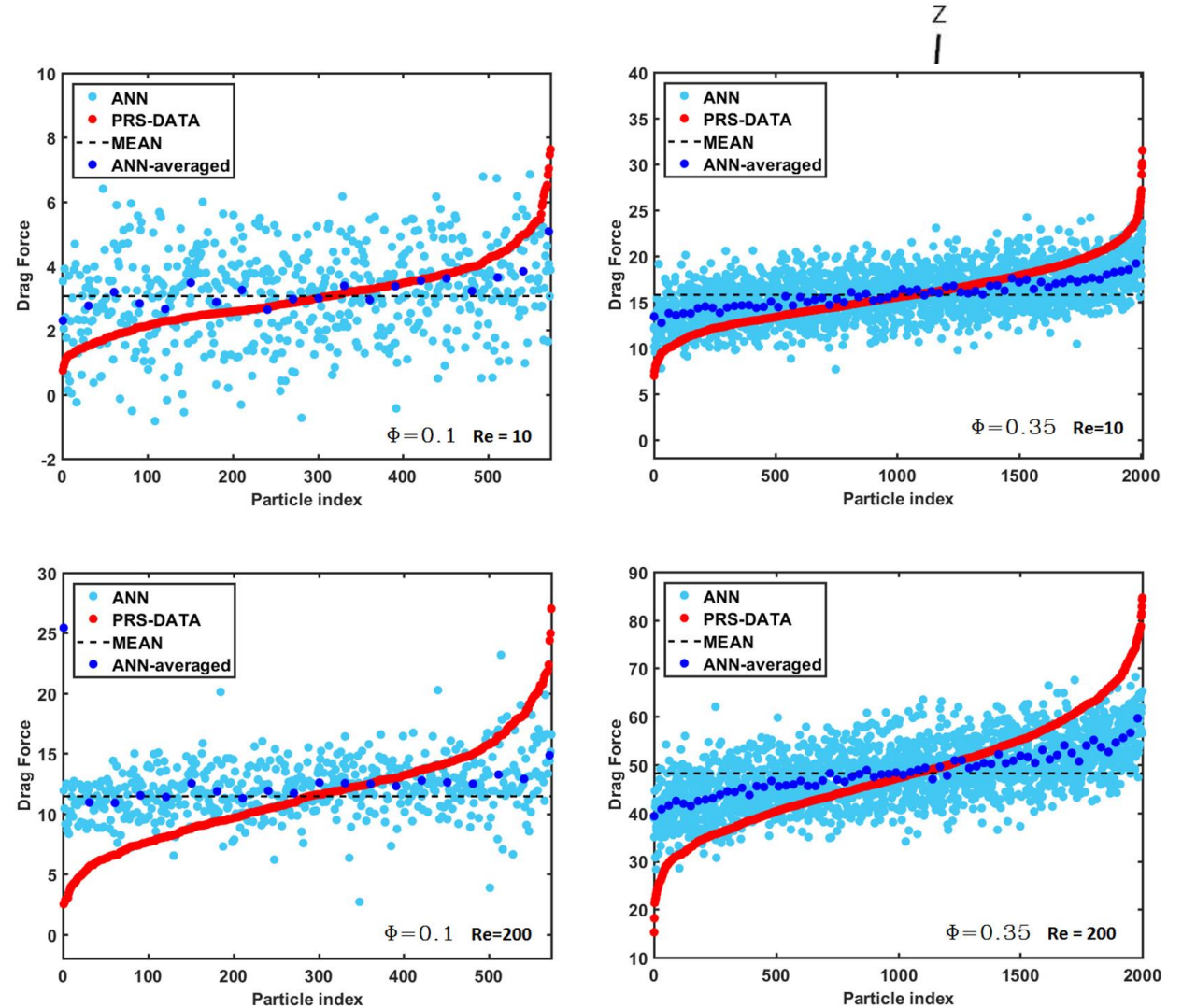
$$C_D = \frac{8}{Re} \frac{1}{\sqrt{\psi_{||}}} + \frac{16}{Re} \frac{1}{\sqrt{\psi}} + \frac{3}{\sqrt{Re}} \frac{1}{\psi^{3/4}} + 0.421^{0.4(-\log \psi)^{0.2}} \frac{1}{\psi_{\perp}}$$

Current State-of-Art

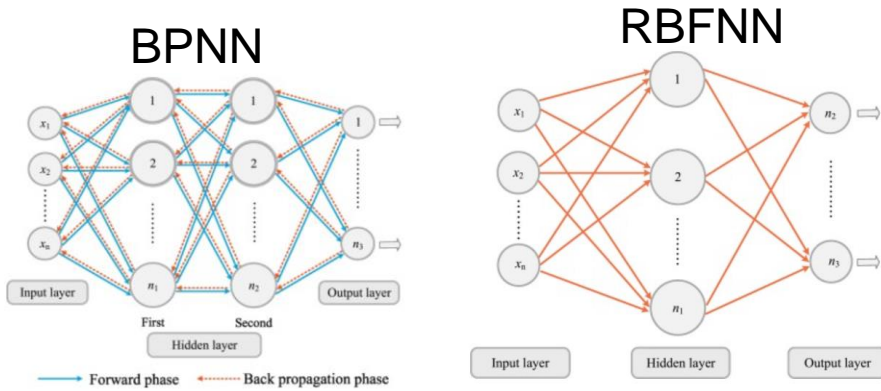
Nearest Particles' location



- Haider & Levenspiel (1989)
- Yow et al. (2005)
- Hölzer & Sommerfeld (2008)
- He & Tafti (2019)
- Yan et al. (2019)

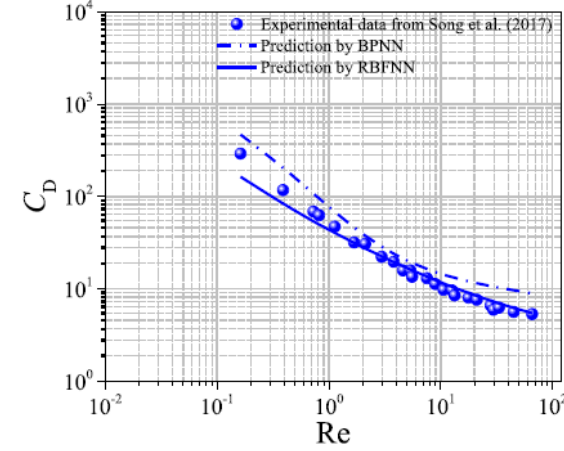


Current State-of-Art

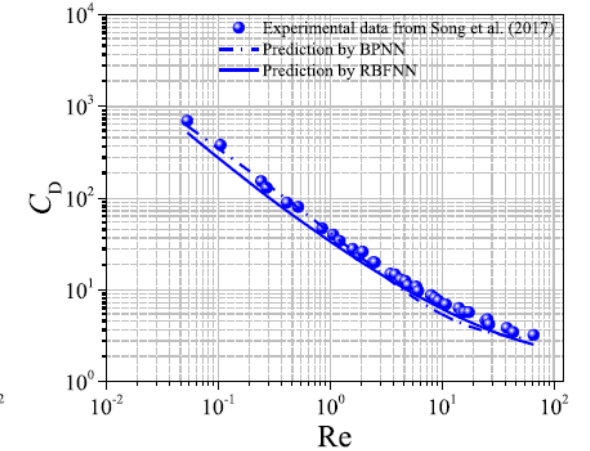


$$\lg C_D = A_0 + A_1 \lg \text{Re} + A_2 (\lg \text{Re})^2 + A_3 (\lg \text{Re})^3 + A_4 (\lg \text{Re})^4$$

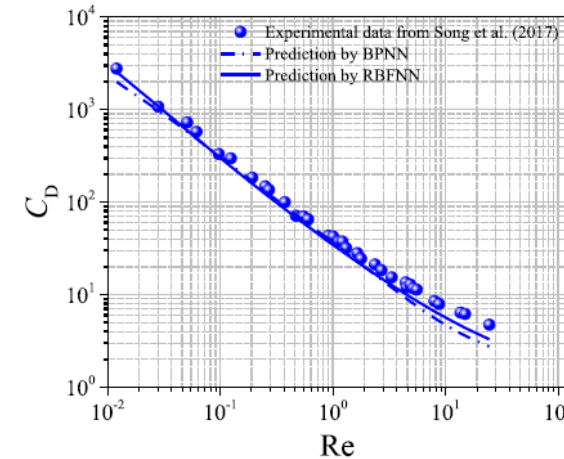
- Haider & Levenspiel (1989)
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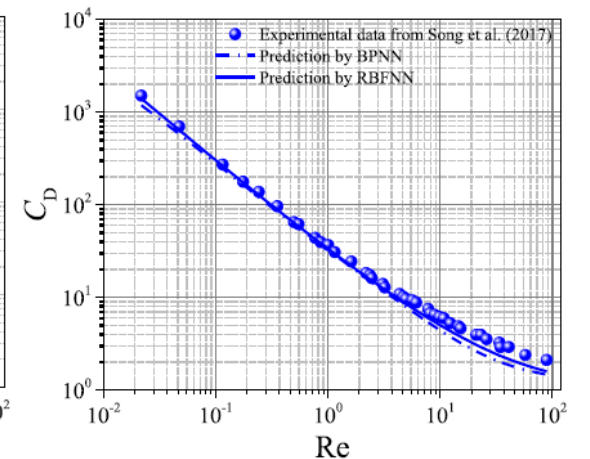
(a) $\phi = 0.471$



(b) $\phi = 0.640$



(c) $\phi = 0.697$



(d) $\phi = 0.756$

Knowledge gap: A drag model which can effectively discriminate shape of the particles and easy to apply in the current MFiX framework

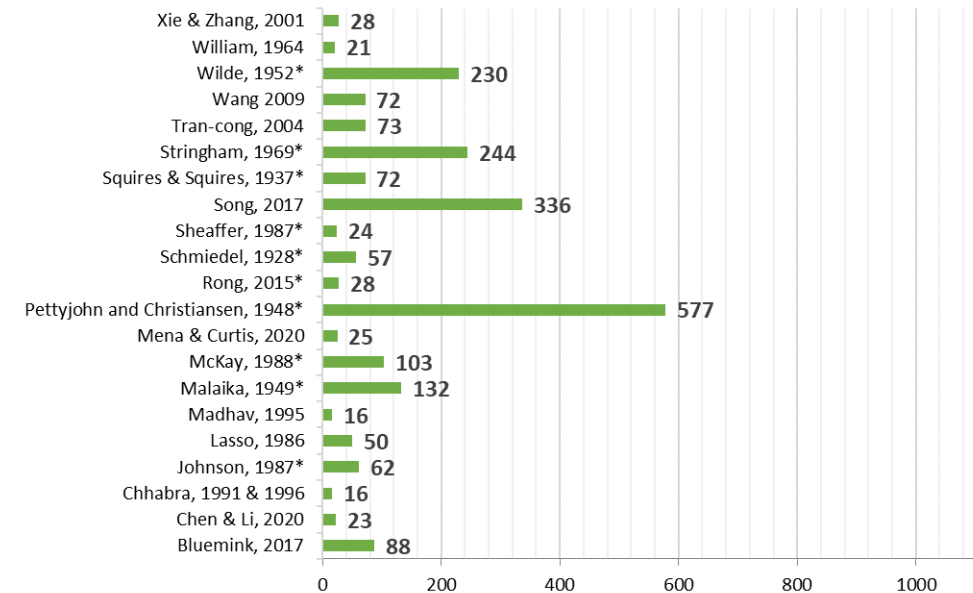
Data Collected

Digitalized several more papers/reports

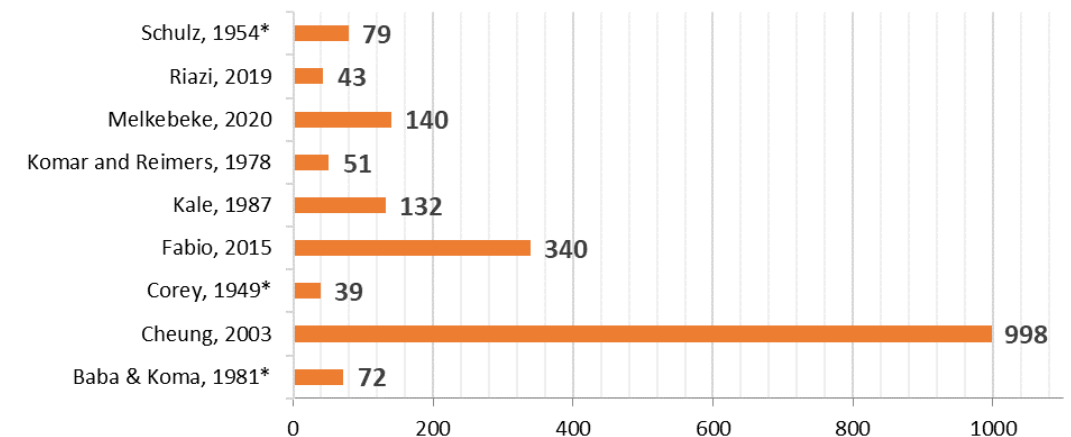
(> 4K data points)

- Created a combined spreadsheet with data of drag coefficients at identified features
- Performed preliminary data analysis of feature importance and feature correlation
- Conducted a systematic experimental analysis on various data configurations

* Particle shape and settling velocity are retrieved from David, 2017. Other parameters including Re and Cd are calculated ourselves to be consistent with other data



Regular-shaped Particles (Total: 2277)



Irregular-shaped Particles (Total: 1894)

Features for Neural Network

- Reynold number (Re)
- Sphericity (ψ)
- Fixed Crosswise Sphericity (ψ_{\perp})
- Fixed Lengthwise Sphericity (ψ_{\parallel})
- Aspect ratio (AR)
- Density Ratio



$$Re = \frac{\rho_g V_r D}{\mu}$$

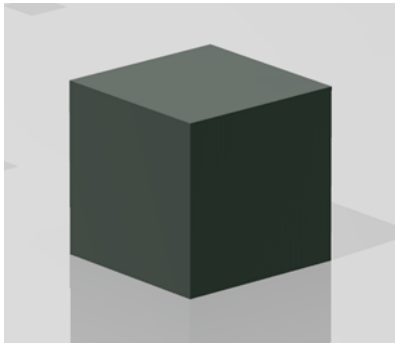
$$\psi = \frac{\pi D^2}{\text{Surface area of the particle } (A_s)}$$

$$\psi_{\perp} = \frac{0.25\pi D^2}{\text{Projected area of the particle perpendicular to the flow}}$$

$$\psi_{\parallel} = \frac{0.25\pi D^2}{0.5A_s - \text{Mean longitudinal projected area}}$$

$$AR = \frac{\text{Longest side}}{\text{Smallest side}}$$

Particle Orientation Study

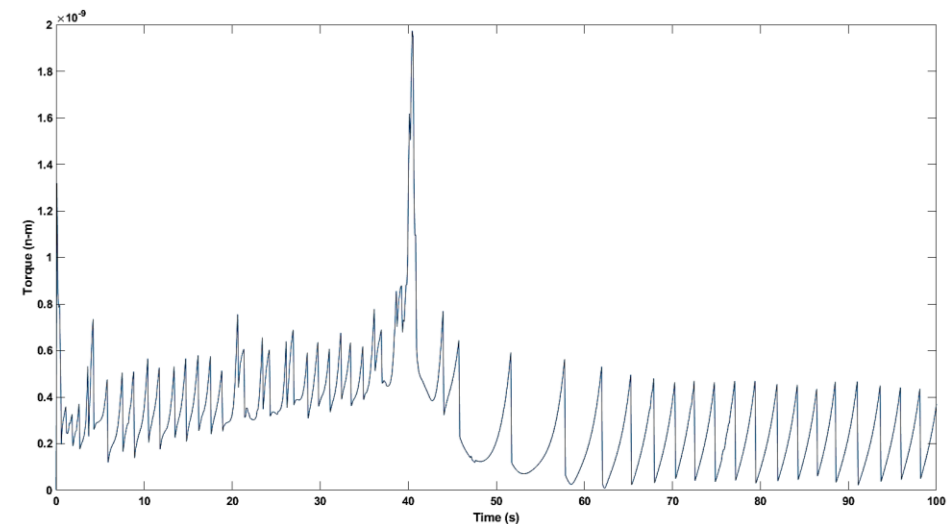
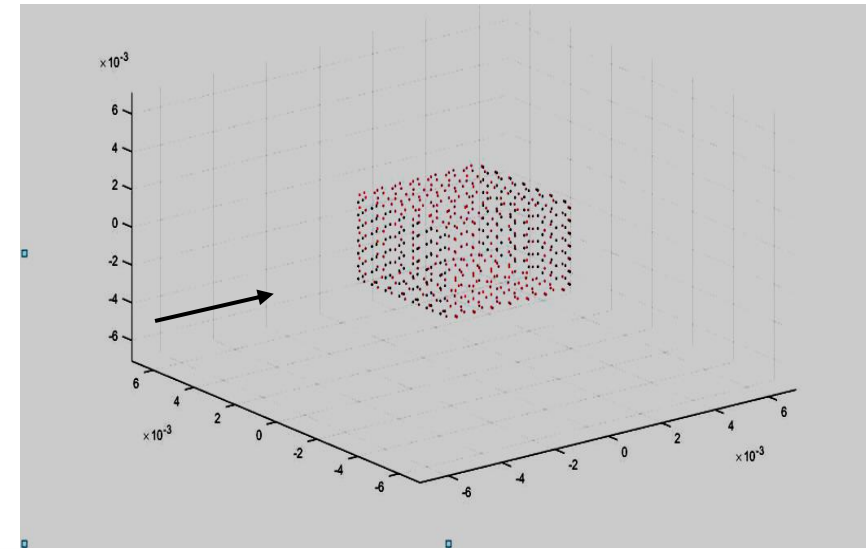


Methodology and Assumptions

1. Panel method to solve aerodynamics
2. Low Reynolds number
3. Flow leaves particle smoothly

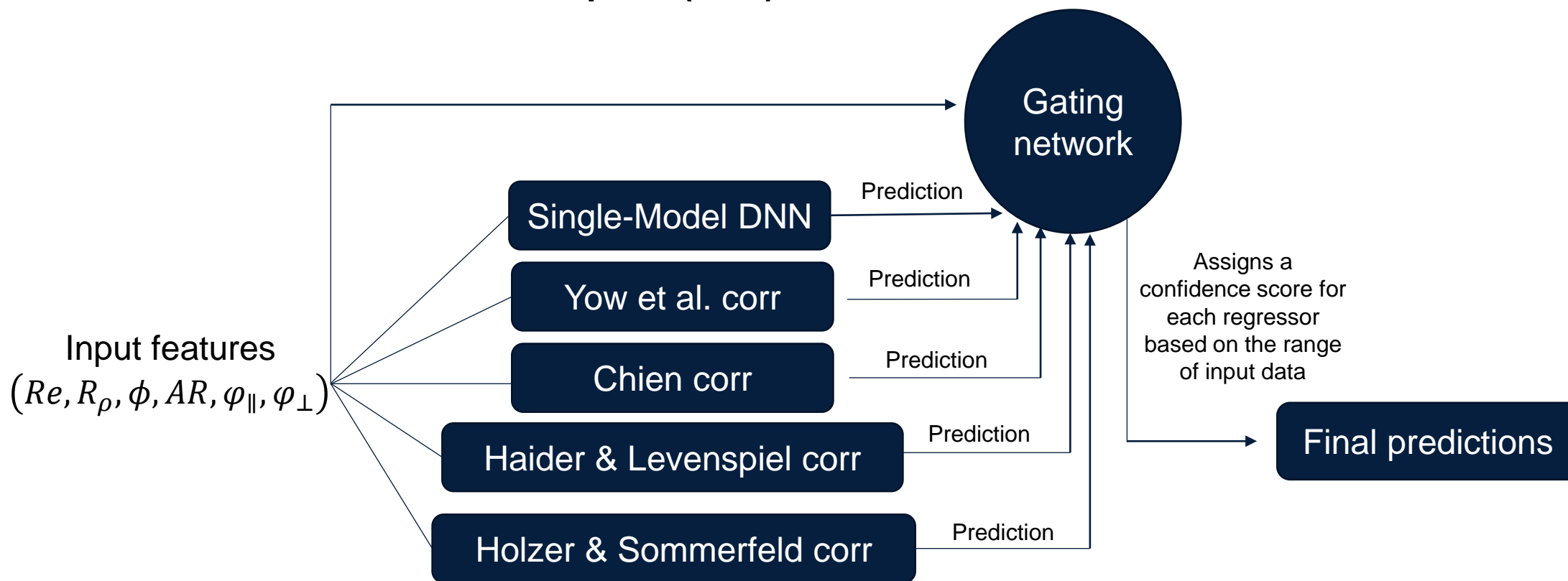
Observations

1. Particle density impacts the orientations
2. Low sphericity particles fluctuates



Drag Coefficient Correlation-aided Deep Neural Network (DCC-DNN)

Mixture of Experts (MoE) Architecture



RMSE	MRAE	R^2
25.98	17.05	0.8569

Agenda

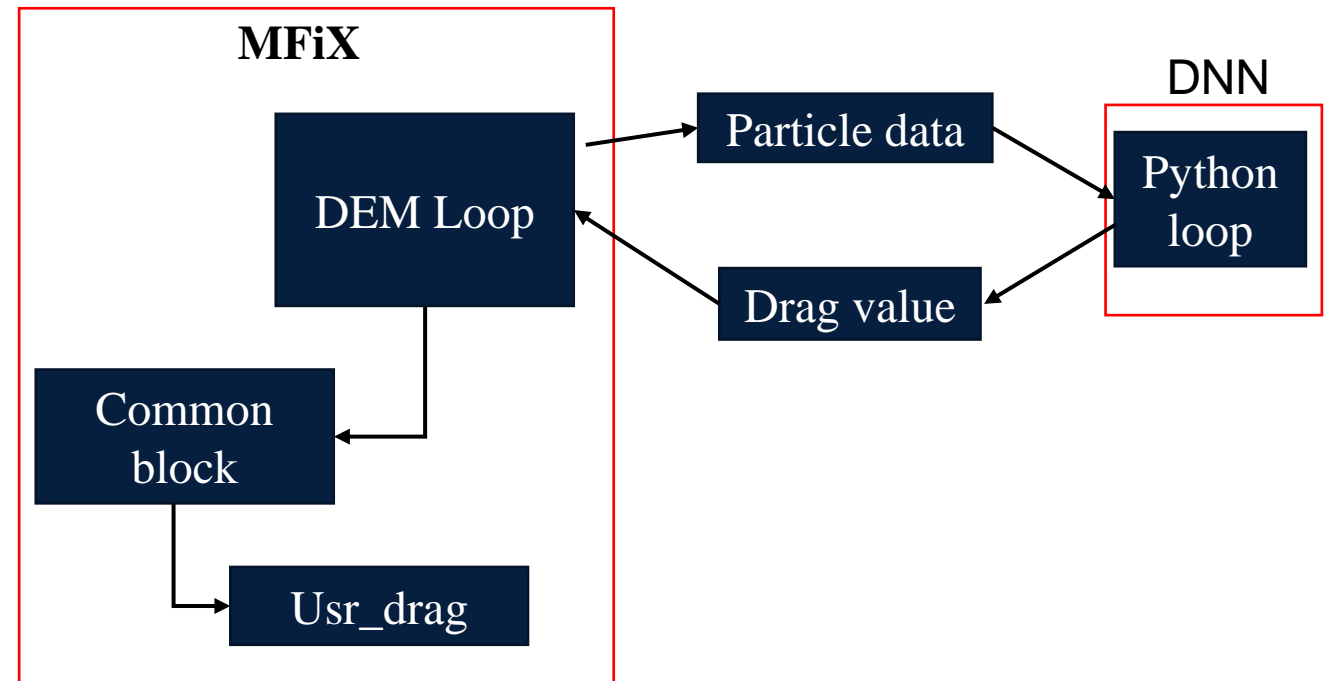
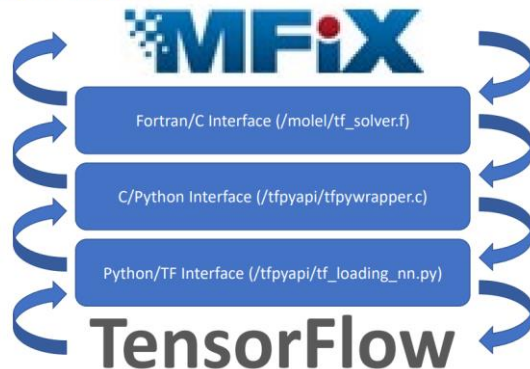
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Integration with CFD (MFiX)

1. MFiX is written on Fortran
2. Neural network model is written on Python
3. Available wrappers cannot work with advance libraries such as Pytorch.

MFiX – TensorFlow Interface

Making MFiX Talk To TensorFlow



- ~11000 particles cost approximately 5 seconds to complete the DEM loop.
- File writing takes place only once
- CFD of lab scale setup is practical
- Large scale can be time consuming

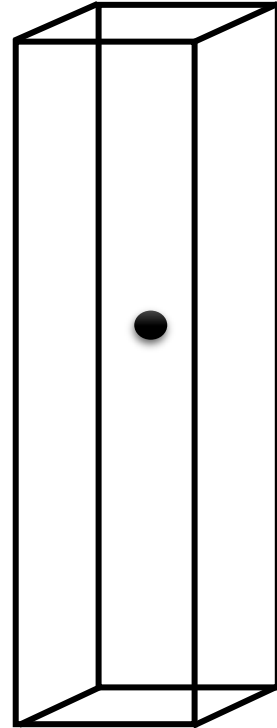
https://www.netl.doe.gov/sites/default/files/2020-11/UCR_HBCU_OMI/Dirk%20VanEssendelft%20Presentation-2020UCRHBCU_Kickoff_MFIXAI_Overview.pdf

CFD Validation

Settling of Single Non-Spherical Particle

1. Non-spherical particle
2. Glycerin and water
3. Al, Ti and Steel
4. Terminal velocity measurement

1. DEM simulation
2. Gravity
3. Particle velocity is monitored



Velocity (m/s)

0.4500
0.4000
0.3500
0.3000
0.2500
0.2000
0.1500
0.1000
0.0500
0.0000



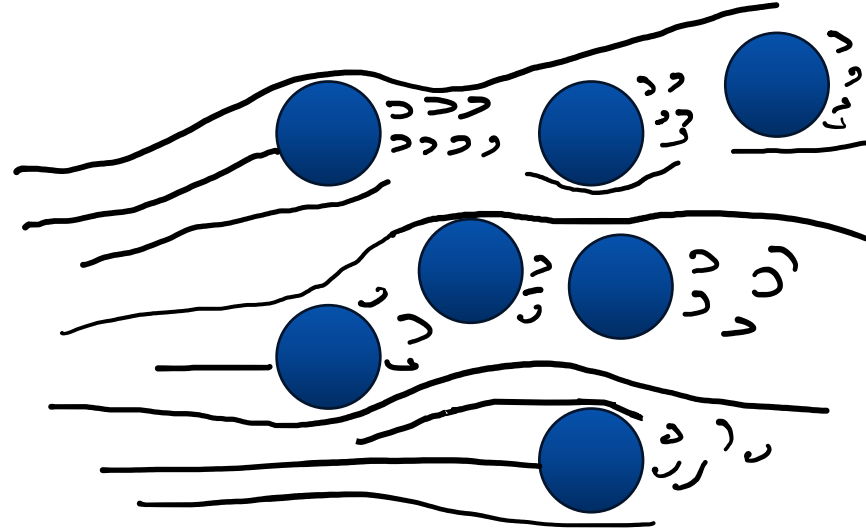
Drag Predictions error < 30 %

Assemblies of particles

Fluidized Bed



Vollmari, K., Jasevičius, R. and Kruggel-Emden, H., 2016. Experimental and numerical study of fluidization and pressure drop of spherical and non-spherical particles in a model scale fluidized bed. *Powder Technology*, 291, pp.506-521.



Sedimentation



<https://physics.aps.org/articles/v10/40>

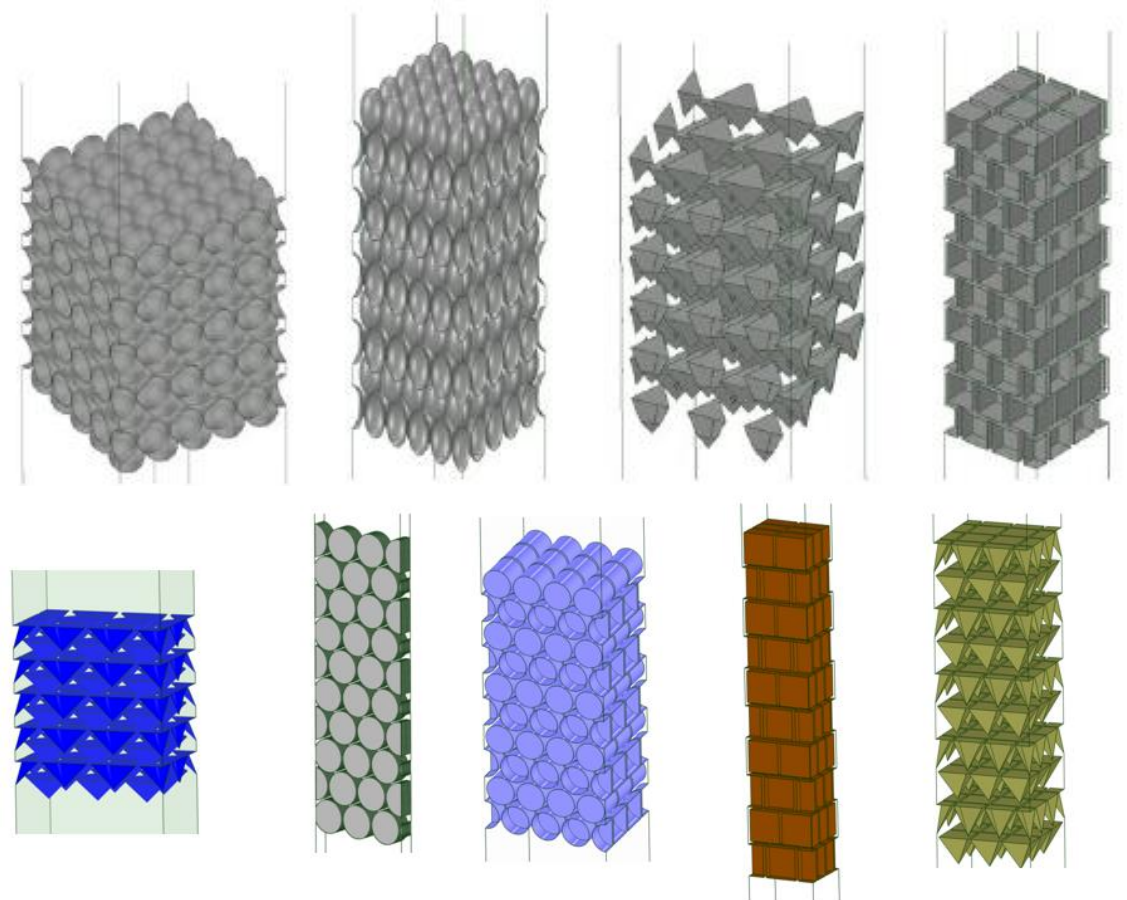
Volcanic debris



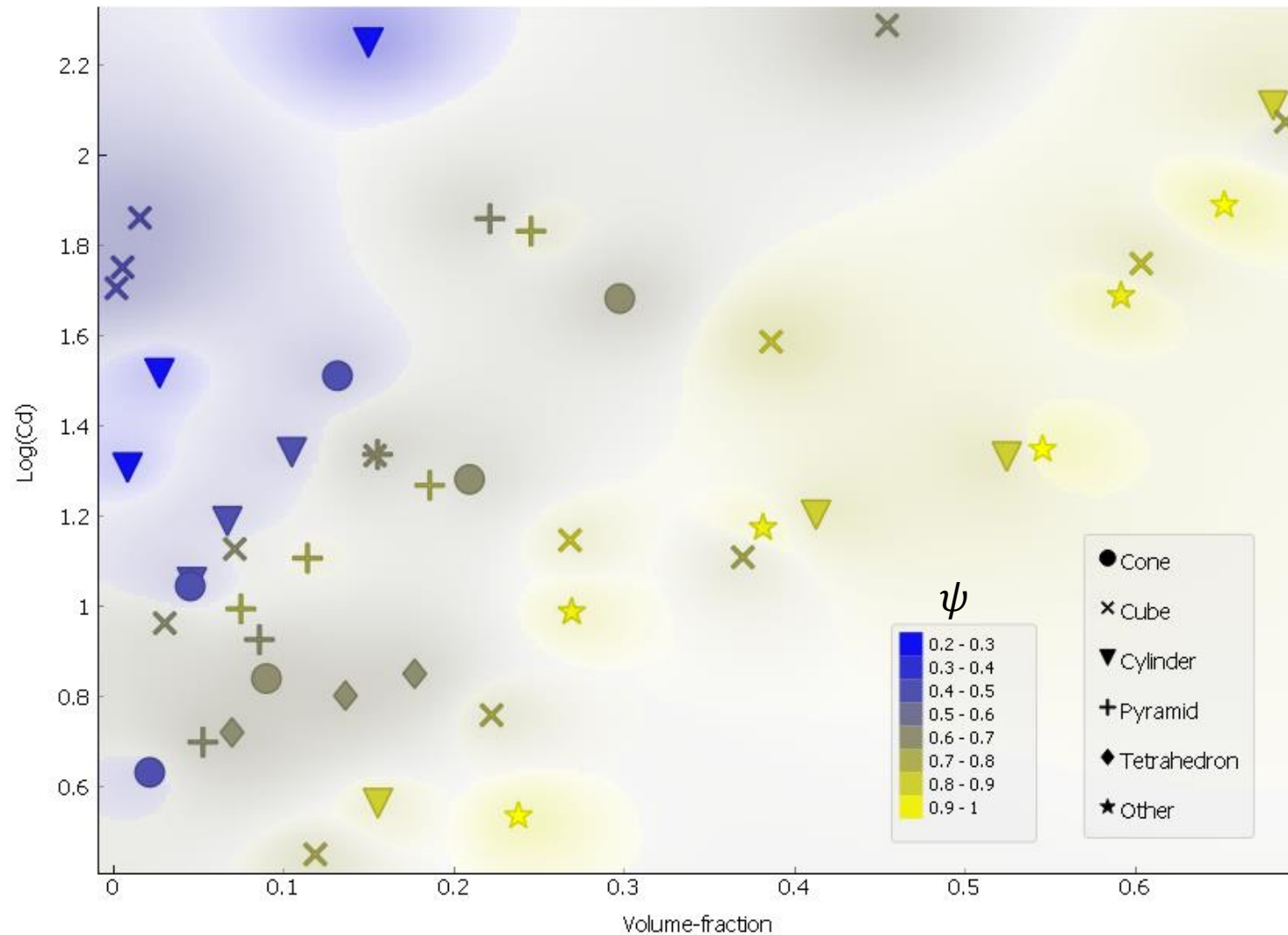
https://volcanoes.usgs.gov/volcanic_ash/ash_gas_vog.html

Effect of Volume Fractions on Drag

- Experimental studies typically do not report drag of a particle in a group.
- CFD simulations are carried out to generate drag data of particles found in beds.
- Re: 1~500



Effect of Volume Fractions on Drag for $Re = 500$



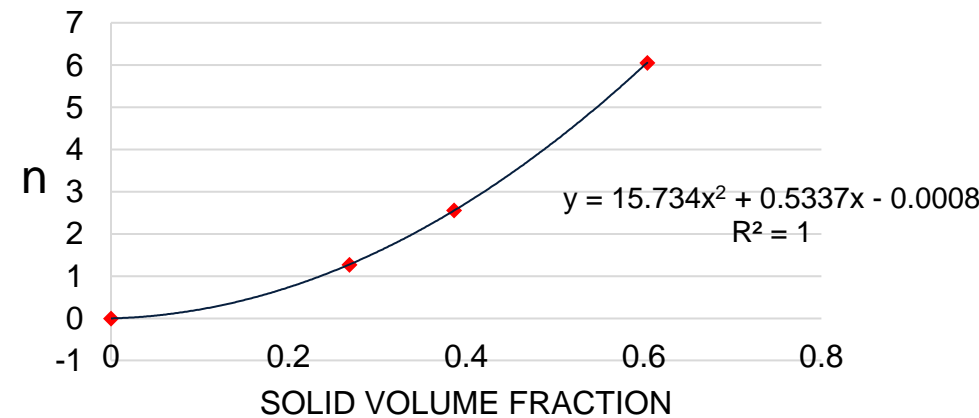
Modelling Volume fraction

$$C_d = C_{d_0}(1 - \epsilon_s)^n$$

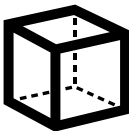
$$C_d = C_{d_0} \phi_v^n$$

$$n \approx f(\phi_v, Re, \psi)$$

For $Re < 10$, $n = -0.0008 + 0.532\phi_v + 15.73\phi_v^2$



	ϕ_v				n		
Re	0.2683	0.3864	0.6038	Single Particle	0.2683	0.3864	0.6038
10	40.57	83.791	365.266	28.0152	0.281444	1.15217	5.089824
100	13.9877	38.582	57.522	3.7008	1.010626	2.465328	5.43816
500	7.6399	12.317	28.357	1.3449	1.32031	2.329059	6.042577
1000	7.5487	12.86072	25.744	1.2051	1.394606	2.489914	6.068513



For $Re > 10$, $n \approx f(\phi_v)$

If $\phi_v \rightarrow 0$, then $n \rightarrow 0$

ϕ_v	0	0.2683	0.3864	0.6038
n	0	1.270517	2.559466	6.056596

$$n = 15.734\phi_v^2 + 0.5337\phi_v - 0.0008$$

Experimental Data

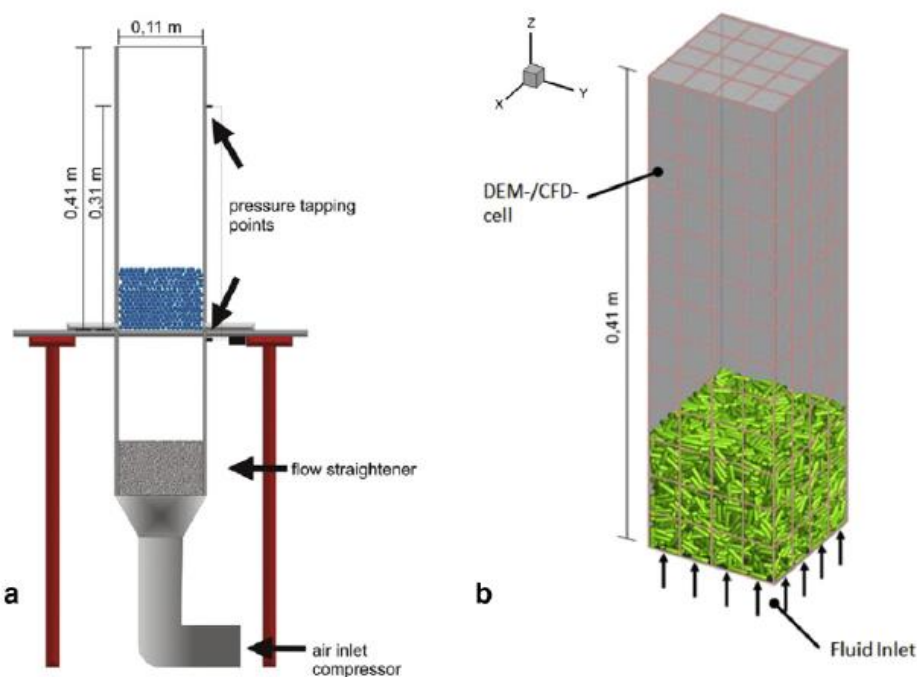







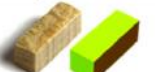



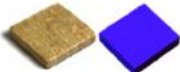



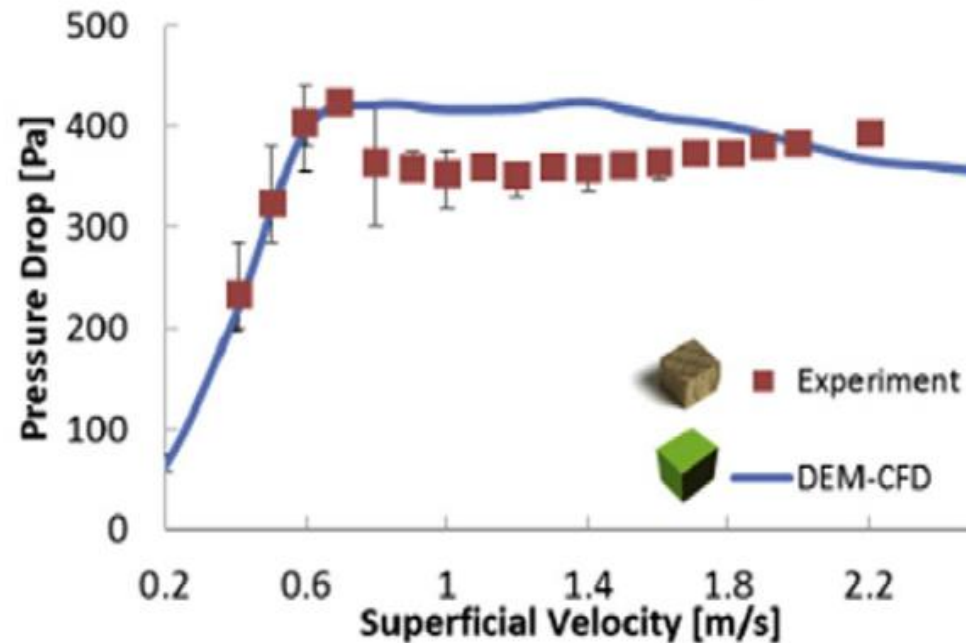
Fig. 2. Experimental (a) and numerical (b) setup and its division into a number of DEM-CFD cells larger than the particle size.

Table 1
Particle properties including the volume equivalent diameter $d_{e-class}$, the particle dimensions, the sphericity ϕ , the particle density ρ_p , the bed height L and the averaged porosity ϵ for the initial, unfluidized setup.

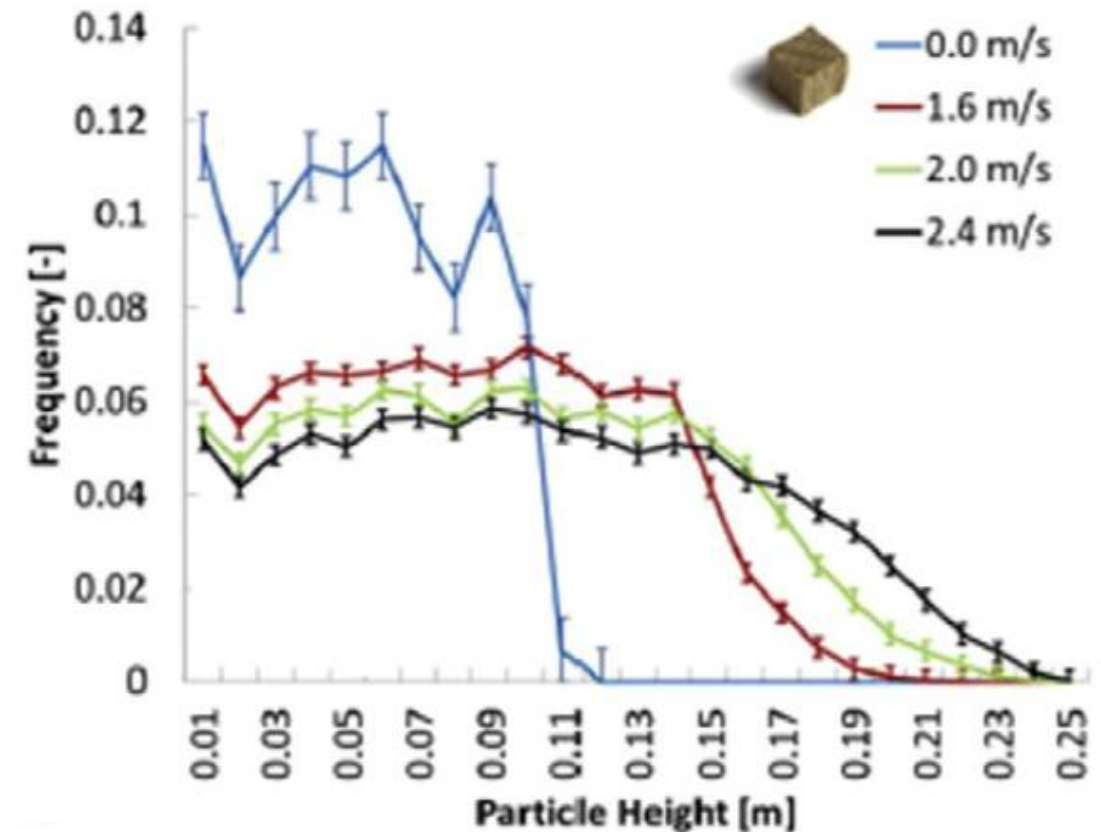
Shape	Sphere		Sphere		Ideal Cylinder		Cube			Cube		
												
$d_{e-class}$ [mm]	7		5		7		5			7		
Size [mm]	7.2		5		6.1 6.2		4.2 4.3 4.5			5.2 6.3 6.3		
ϕ [-]	1.00		1.00		0.87		0.81			0.80		
ρ_p [kg/m ³]	772.5		823.0		708.5		639.7			746.9		
L_b [mm]/ $\bar{\epsilon}$ [-]	95 0.40		88 0.40		98 0.36		98 0.37			103 0.43		
Shape	Elongated Cylinder		Elongated Cuboid		Elongated Cuboid		Plate			Elongated Plate		
												
$d_{e-class}$ [mm]	7		5		7		5			5		
Size [mm]	3.9 14.0		3.0 3.0 7.1		4.2 4.2 11.4		2.0 4.9 6.0			2.0 4.0 8.0		
ϕ [-]	0.75		0.75		0.73		0.71			0.69		
ρ_p [kg/m ³]	764.4		745.6		639.7		754.1			756.6		
L_b [mm]/ $\bar{\epsilon}$ [-]	103 0.44		103 0.42		115 0.40		102 0.43			108 0.46		
Shape	Elongated Cuboid		Plate		Elongated Plate							
												
$d_{e-class}$ [mm]	5		7		7							
Size [mm]	2.0 3.0 11.0		2.2 9.0 9.8		2.0 6.0 14.9							
ϕ [-]	0.64		0.63		0.58							
ρ_p [kg/m ³]	728.1		672.8		721.7							
L_b [mm]/ $\bar{\epsilon}$ [-]	117 0.48		121 0.46		124 0.51							

Performance Metrics

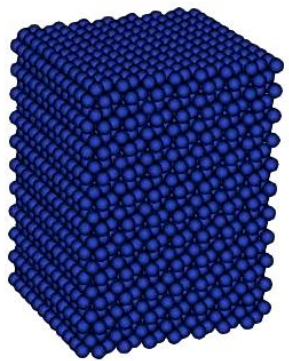
Pressure drop



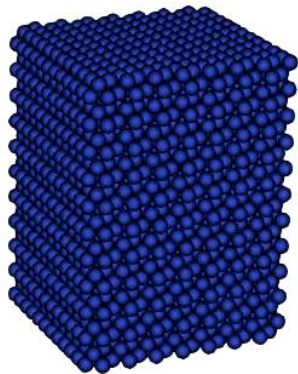
Frequency Distribution



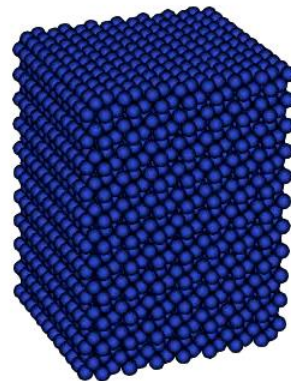
DEM Simulations of Cubic Particles



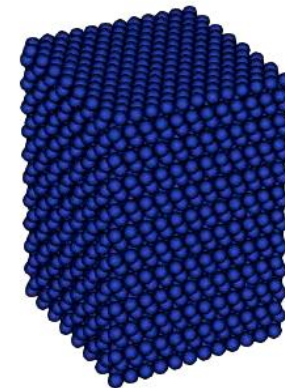
$V_g = 0.7 \text{ m/s}$



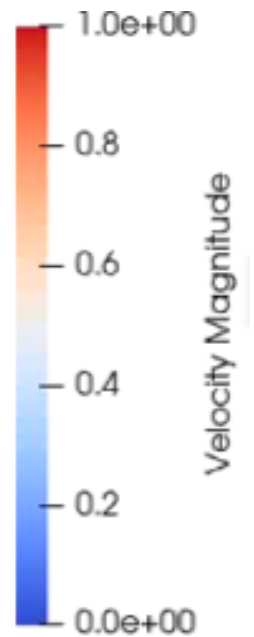
$V_g = 1.2 \text{ m/s}$



$V_g = 1.6 \text{ m/s}$

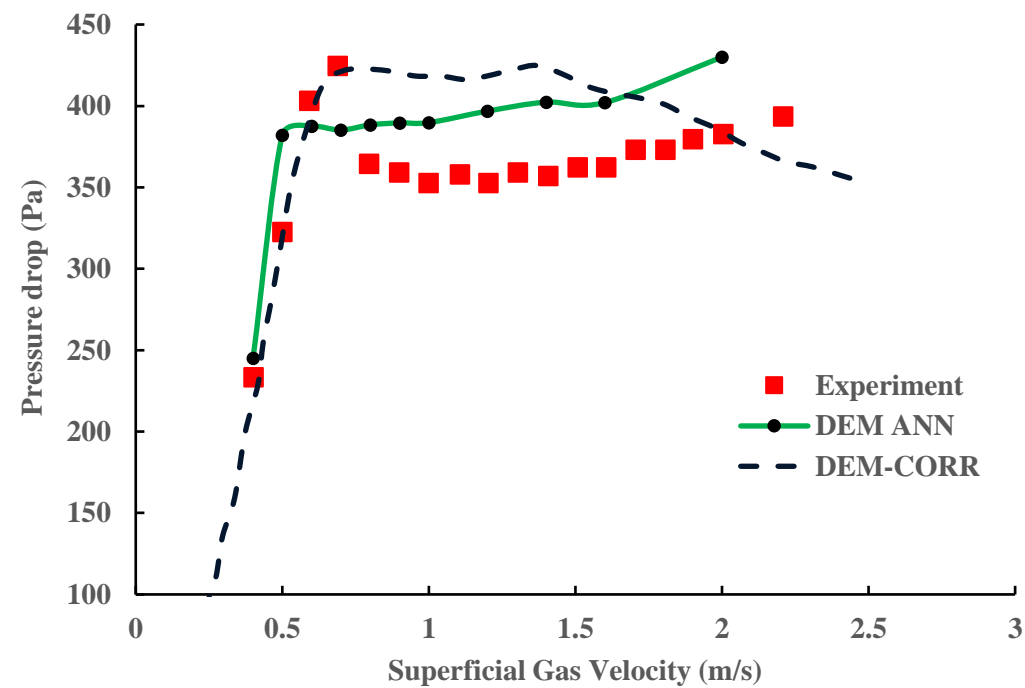


$V_g = 2.4 \text{ m/s}$



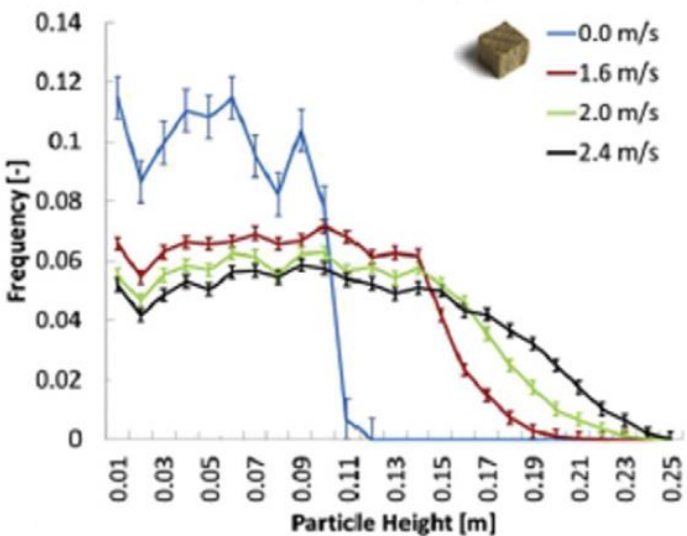
Results

Pressure drop across the bed

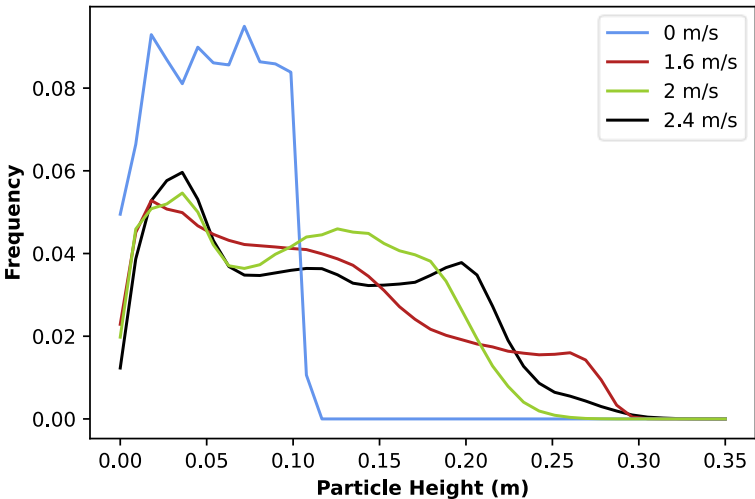


Experiments

Frequency distribution

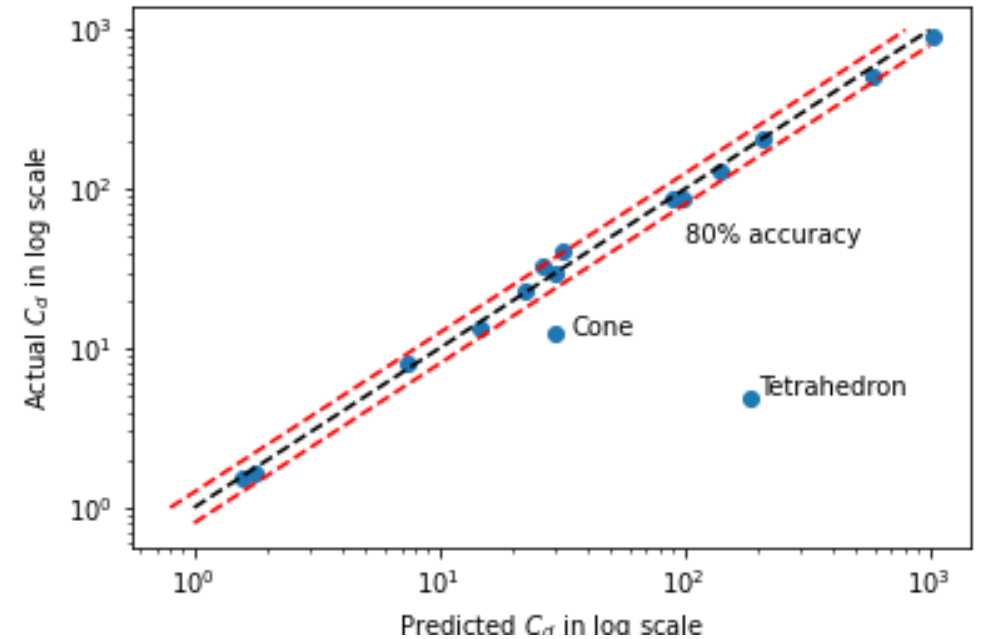
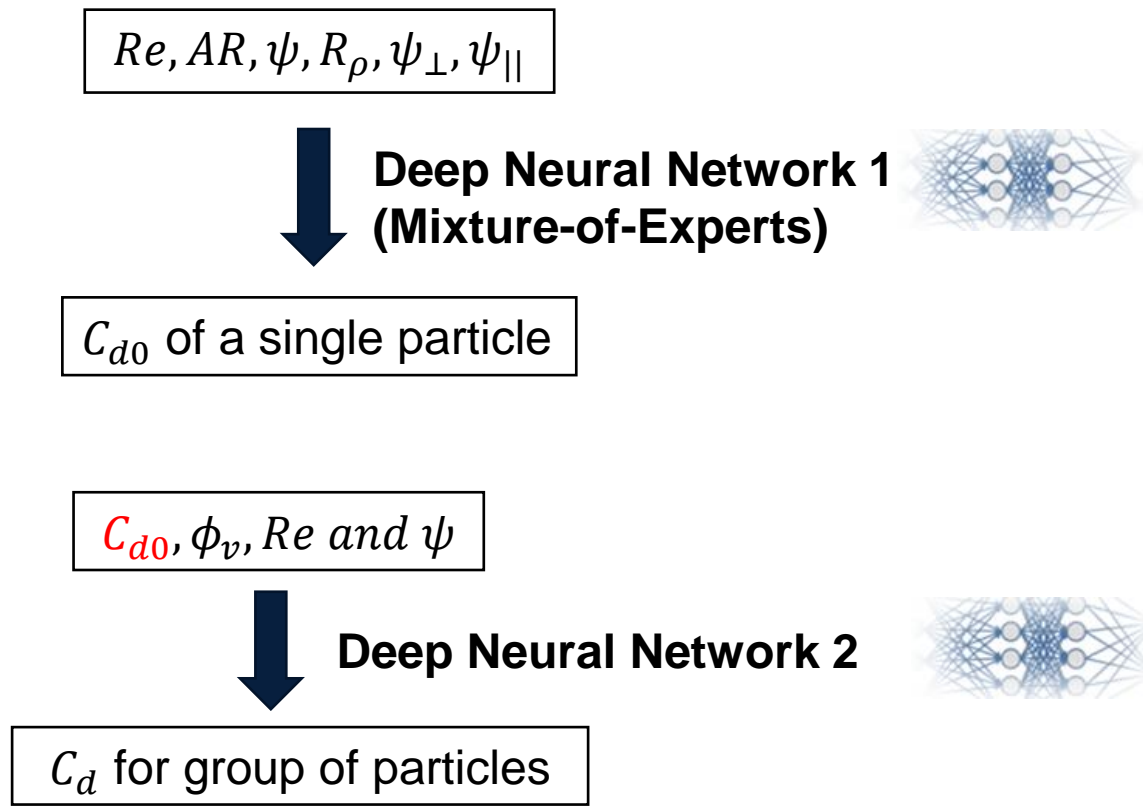


DEM Simulations



Future Task

Modelling Volume Fraction Using Neural Network



Predicted vs. Actual scatter plot

Conclusions

- Drag force on non-spherical particles depends on shape factor, inertia and Reynold number.
- Fixed crosswise and lengthwise sphericity is effective in discriminating the particles.
- Gated DNN model is integrated with MFiX to model particle drag.
- Single particle simulations with new drag model shows excellent predications.
- Solid volume fraction effect can be accounted using Di Felice's equation.
- DEM simulation using new drag model predicted fluidization of cubic particles.
- The pressure drop predictions across the bed are reasonably accurate.
- The pressure drop at the beginning of fluidization is under-estimated.
- The solid volume fraction effect are now accounted in the second level of DNN model.

Acknowledgement

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Program Manager: Dr. Heather Hunter

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Appendix

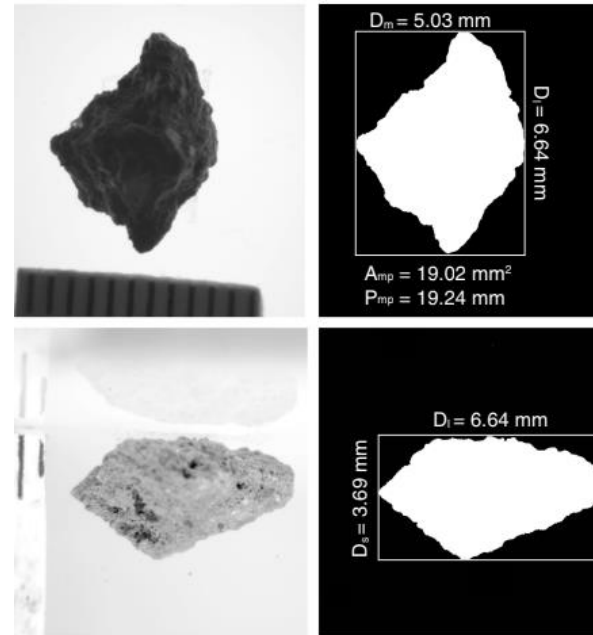
Regular vs. Irregular Shaped Particles

Regular shaped particles:









- A particle of geometric parameters such as volume and surface area that can be mathematically determined

Irregular shaped particles:

- An arbitrary random particle whose geometric parameters cannot be precisely calculated



Irregular-shaped
Particles¹

Particle Shape		Sphericity
	Sphere	1
	Spheroid	0.92
	Cylinder	0.87
	Cube	0.805
	Cone	0.778
	Pyramid	0.718
	Tetrahedron	0.671
	Disk	≈ 0.213

Regular-shaped
Particles

¹Dioguardi, F., D. Mele, and P. Dellino. "A new one-equation model of fluid drag for irregularly shaped particles valid over a wide range of Reynolds number." Journal of Geophysical Research: Solid Earth 123, no. 1 (2018): 144-156.