

Solvent Model Validation Hierarchy

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CAK RIDGE











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Solvent model validation framework to optimize CO₂ capture

Absorber column with commercial packing and intensified packing device for intrastage cooling



Intensified device for intrastage cooling to control absorber column temperature profile



Absorber columns have complex multiscale, multiphysics dynamics.

Intrastage cooling using a nonoptimized intensified device can increase CO_2 capture efficiency by 5–25%, with almost 40% reduction in column size.

We have developed an integrated approach for process optimization.



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3

Multi-pronged approach to validate solvent models





CFD model & simulations Overall optimization strategy





Geometric parametrization in 2D and 3D



Carbon Capture Simulation for Industry Impact

3D simulation framework



Preliminary indicative 3D simulation results





2-inch columns for higher-fidelity validation data

Fluid-Structure Interface (FSI) setup Packing Prototype Performance (PPP) setup



To measure solvent flow behavior on column material of construction



To characterize specific geometry performance for validation data



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3D printed column, with
full-size packing structures,
for rapid prototyping & testing
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Dry pressure distribution for the 2-inch column



8-inch column for model scaling testing



Two 3D-printed intensified device sections

Current focus is on enhanced instrumentation to provide highfidelity boundary conditions and performance data for simulations







Solvent properties measurements improve simulation accuracy

We have a wide range of capabilities to measure specific **solvent interaction** with our specific packing **materials of construction** to improve simulation accuracy.



Scaling sequence and capabilities



Scale-up sequence – intensified-device sections

Objective: provide high-fidelity performance data sufficient to support process models, CFD, ML–ROM surrogates



Highlights

Unique capabilities

- Special treatment of solvent layer incorporating IDAES framework for MEA chemistry, heat transfer, and transport properties for direct CFD simulation of solvent wetting, thermodynamics, and CO₂ absorption
- Additive manufacturing for prototype packing fabrication and testing for process intensification
- Experimentation at multiple scales for scale-up validation

Because of the complexities of the solvent-packing interaction, scaling up of an optimized process is facilitated by the application of machine learning.



MACHINE LEARNING FOR ACCELERATING CFD AND DESIGN OPTIMIZATION



Machine learning for CFD

- CFD is critical for the fundamental understanding, to inform process and system level modeling.
- Need local information on transport phenomena to understand driving forces
- Can be incorporated into design optimization
 to optimize the device

Simulation time is a bottleneck that impedes high-level modeling.

Machine learning surrogates, such as Deep Fluids (DF) and MeshGraphNets (MGN), can reduce the computational burden of timeconsuming simulations.



Fast Surrogates for CFD Simulation Model

Machine learning surrogates to speed up computational fluid dynamics (CFD) simulations



CCSI² ML for CFD





DeepFluids / DeeperFluids (DF)

During prediction, the ML model uses the first frame to predict subsequent frames.

Input A single frame

Encoding

The frame is mapped to a feature vector (embedding) in latent space.

Forward Pass

Predict the next embedding.

Decoding

Embeddings are mapped back to the physical space.



https://github.com/CCSI-Toolset/DeeperFluids

arXiv:2112.11656



MeshGraphNets (MGN)

Input

A *mesh* within the original frame

Encoding E

Each node and edge has its own embedding.

Message Passing M

Neighboring edges and nodes exchange info to update embeddings.

Decoding D

Updated embeddings are decoded, which represent the gradient in physical space.

Forward pass *F* Via forward Euler

CCSI²



https://github.com/CCSI-Toolset/MGN arXiv:2304.00338

CCSI² ML for CFD

| | DeeperFluids (DF) | MeshGraphNets+ (MGN) | | |
|-----------------|---|---|--|--|
| Representation | Treats data as an image For structured grids | Treats data as a graph For unstructured meshes | | |
| Physics | Physics constraints are difficult to incorporate after compression into images and latent spaces. Dynamics is learned within latent space . | Node dynamics is learned through interactions with other nodes via message passing , making it easier to impose physics constraints. Dynamics is learned within the physical space . | | |
| Accuracy | DF will be less accurate than MGN , but should still be visually acceptable . | MGN should yield much higher accuracy, but at the expense of higher computational resources. | | |
| Transferability | DF needs to be retrained to predict for new meshes/packings. | MGN learns the physics independent of mesh shape and can transfer well to new meshes/packings. | | |
| Speed-up | DF favors speed over accuracy and transferability; up to 5000x faster than CFD. | MGN favors accuracy and transferability over speed; currently up to 200x* faster than CFD. | | |



2D RCM data

- 2 packing configurations (vertical slice of 3D packing)
 - 50 simulations (different inlet velocities)
 - 500 timesteps
 - Velocity, pressure, volume fraction measurements
 - 150K irregularly spaced points (nodes)





Trained on:









https://data.pnnl.gov/group/nodes/dataset/33472

DeeperFluids surrogates

Building on the original surrogates...

| | Error _{IA} | | | | | |
|---------------|---------------------|----------------|----------------|----------------|--------------------|----------------|
| Н | w=20 | 50 | 150 | 200 | 300 | 499 |
| 1024, 512 | 0.33 (0.14) | 0.08 (0.00) | 0.09 (0.00) | 0.10 (0.00) | 0.11 (0.00) | 2.53 (0.26) |
| 128, 128, 128 | 0.64 (0.11) | 0.08 (0.01) | 0.08 (0.00) | 0.07 (0.00) | 0.06 (0.00) | 2.25 (0.18) |

We find better performance

| | | Er | Error _{IA} | | $\mathrm{Error}_{\mathrm{VF}}$ | |
|-------------|---|--------------|---------------------|--------------|--------------------------------|--|
| LIN | s | $L_{\rm RE}$ | RMSE | $L_{\rm RE}$ | RMSE | |
| ARC | 1 | 0.12 | 0.09 | 0.53 | 0.55 | |
| | 6 | 0.15 | 0.14 | 0.51 | 0.53 | |
| LSTM | 1 | 0.12 | 0.06 | 0.56 | 0.54 | |
| | 6 | 0.09 | 0.09 | 0.52 | 0.54 | |
| MLP | 1 | 0.07 | 0.07 | 0.53 | 0.55 | |
| | 6 | 0.08 | 0.12 | 0.49 | 0.52 | |
| Transformer | 1 | 0.08 | 0.04 | 0.53 | 0.55 | |
| | 6 | 0.06 | 0.22 | 0.53 | 0.80 | |



And big speedups!

| LIN | Error _{IA} | $\mathrm{Error}_{\mathrm{VF}}$ | S_W |
|-------------|---------------------|--------------------------------|-------|
| ARC | 0.07(0.00) | 0.49(0.00) | 4800 |
| LSTM | 0.08(0.01) | 0.49(0.01) | 2700 |
| MLP | 0.06 (0.00) | 0.47 (0.00) | 5400 |
| Transformer | 0.08(0.04) | 0.51(0.00) | 4300 |

MeshGraphNets surrogates

Extrapolated velocities + unseen packings



Ground truth, sim 11 (extrapolated velocity, unseen packing)



Predicted, sim 11 (extrapolated velocity, unseen packing)

| Packing | Velocities | Avg. %-error in IA |
|---------|--------------|--------------------|
| Trained | Extrapolated | 9.05 |
| Unseen | Trained | 5.42 |
| Unseen | Interpolated | 2.24 |
| Unseen | Extrapolated | 7.79 |



3D RCM data

Data:

- 50 simulations
- 500 timesteps
 - Velocity, volume fraction, pressure measurements
- 3.1 million nodes (vs. 150K in 2D)
- With patch training, higher-order integration and other enhancements, **MGN training is now feasible**
- Current speed-up over CFD: ~150-185x
 faster with one V100 GPU
 - Targeting 1000x next



https://data.pnnl.gov/group/nodes/dataset/33472



ML + design optimization



ML for design optimization, TRL progression

- ML can accelerate CCS modeling and validation
 - Use some CFD data to train sufficiently accurate + faster ML surrogates
 - Once trained, replace CFD dependence with ML surrogates
- Multiphysics
 - ML transferability: able to update/fine-tune already-trained models to account for additional physics
- Novel packing configurations
 - MGN able to predict well on unseen packings/meshes
- Scaling up
 - MGN able to work on arbitrary domain/mesh sizes
 - Can update/fine-tune already-trained models to account for scale-up effects



Summary

Process-level optimization is facilitated by machine-learning models trained on detailed CFD simulations — experimentally validated at different scales — capturing the effects of design and operating conditions on the absorption performance for a given solvent.

Components

- Sequential Design of Experiments see next talk by Abby Nachtsheim
- Experimental prototype performance fabrication and testing
- Process modeling and optimization
- Computational Fluid Dynamics modeling
- Machine Learning





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BACKUP SLIDES

