Predictive Self-Healing Seals for Gas Transmission

Project Number FE0031876

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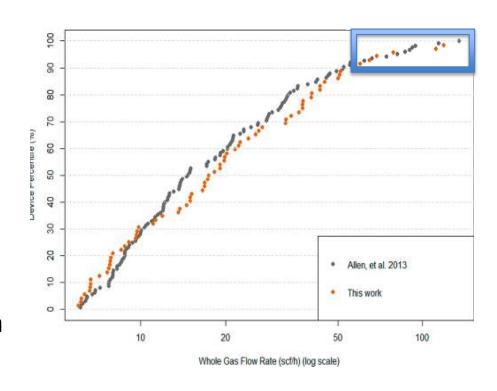
BSchool of Petroleum Engineering

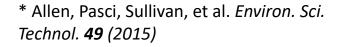
The University of Tulsa



Methane Release from Damaged Systems

- Allen et al.* observed a significant number of anomalous methane releases in pneumatic actuators.
- This project targets 80% reduction of leak rate in those damaged systems.
- Release from damaged systems in the Allen study accounted for 14 million cubic feet of methane/year.
- Milestone goal would reflect a reduction in release by 11 million cubic feet/year for the systems in Allen paper.

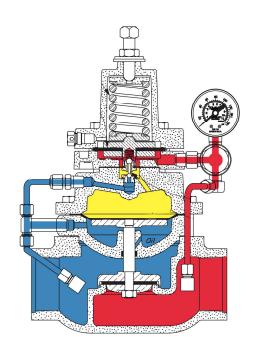






Pneumatic Controllers/Actuators

- Various models, but diaphragms are in large number of devices
- Damage can lead to direct venting of natural gas
- Proposed approach is intended to be direct retrofit
- Approach allows for "active" repair
 - Increases healing approach scope
 - Enables repair of large scale damage

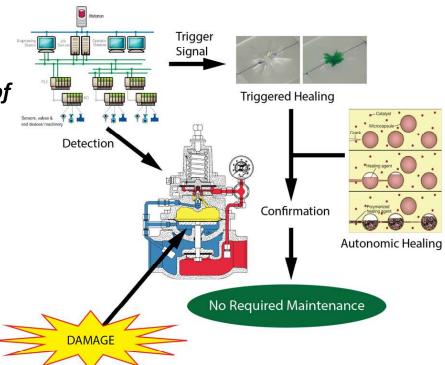




Self-Healing Diaphragm

Demonstrate automatic detection and repair of a pneumatic actuator in a pilot scale facility

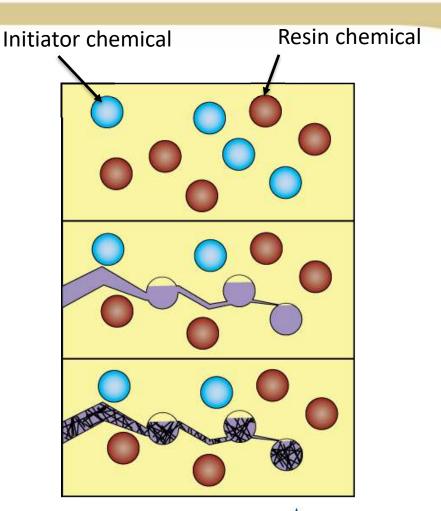
- Synthesize self-healing system
- Develop detection model
- Build and validate pilot scale test stand





Synthesize Self-Healing Membrane

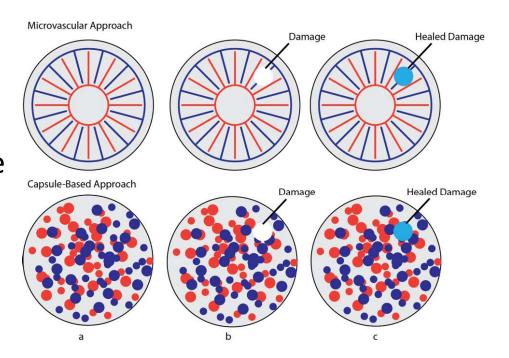
- Synthesize self-healing membrane material
- Confirm self-repair in laboratory setting
- Integrate system into commercial pneumatic actuator (PA)
- Confirm self-repair in commercial PA.





Membrane Processing/Synthesis

- Two approaches
 - Capsule-based repair
 - Microvascular networks
- Initial focus is polyurethane membrane systems
- Siloxane or acrylic-based healing chemistries are initial targets

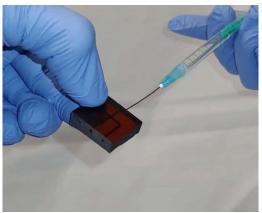




Microvascular Systems

- Based on depolymerization of PLA or other lost-wax approaches
- Channel positive is printed via rapid prototype
- Membrane is cast around positive
- Channels are evacuated to provide circulatory system
- Healing chemistry is circulated in channels
- Monolithic and multilayered systems will be investigated

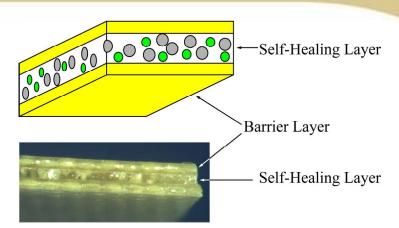


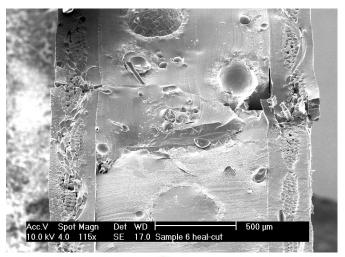




Capsule-based approaches

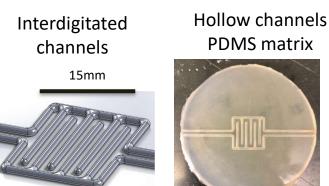
- Based on reactive monomer encapsulation
- Effective for small-scale damage
- Could be combined with microvascular approach for multi-scale repair
- Monolithic and multi-layer systems will be perused

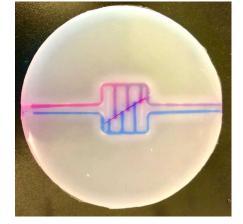






Self-healing Performance



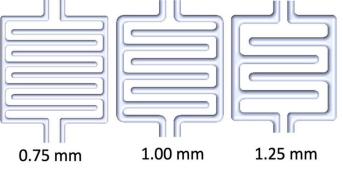


Dyed water in channels

0.75 mm

Dimensions 60mm diameter 5mm thick





1.00 mm

Modification of channels contained within 15mm by 15mm central square

> Varying channel diameter



1.25 mm



Damage Types and Test Procedure

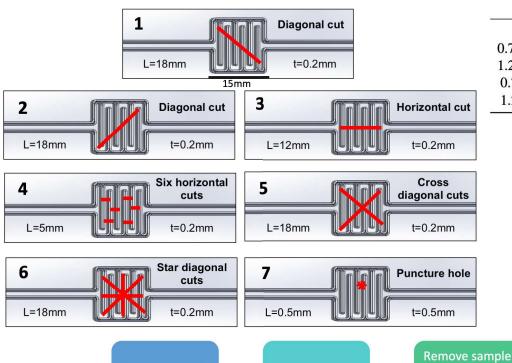
from pressure

test cell and

inject with

PDMS healing

chemistries

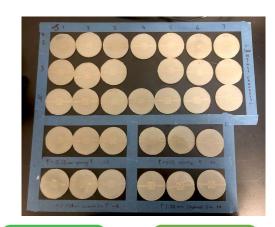


Run through

pressure tests 1

2, and 3

Type of sample	Number of samples	Damage type(s) applied
Original Design	21	1-7
0.75mm channel diameter	3	1
1.25mm channel diameter	3	1
0.75mm channel spacing	3	1
1.25mm channel spacing	3	1



After seven hours, place sample back in pressure test cell

Re-run through pressure tests 1, 2, and 3



Damage sample

and load sample

into pressure

test cell

Visual Self-healing Confirmation

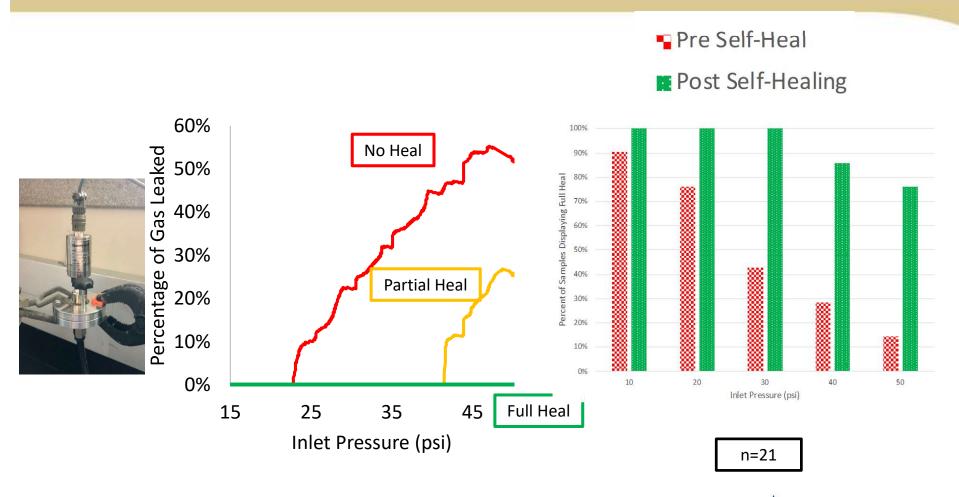


Through thickness damage

Healing completed

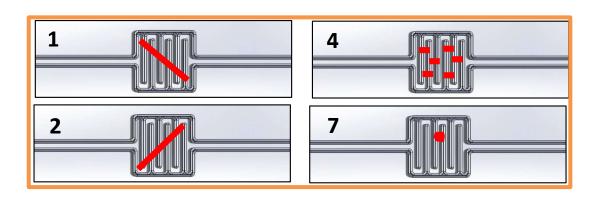


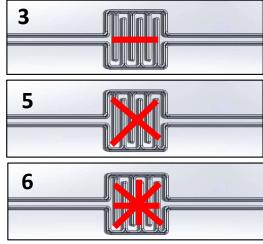
Pressure Test Results





Damage Modes Results



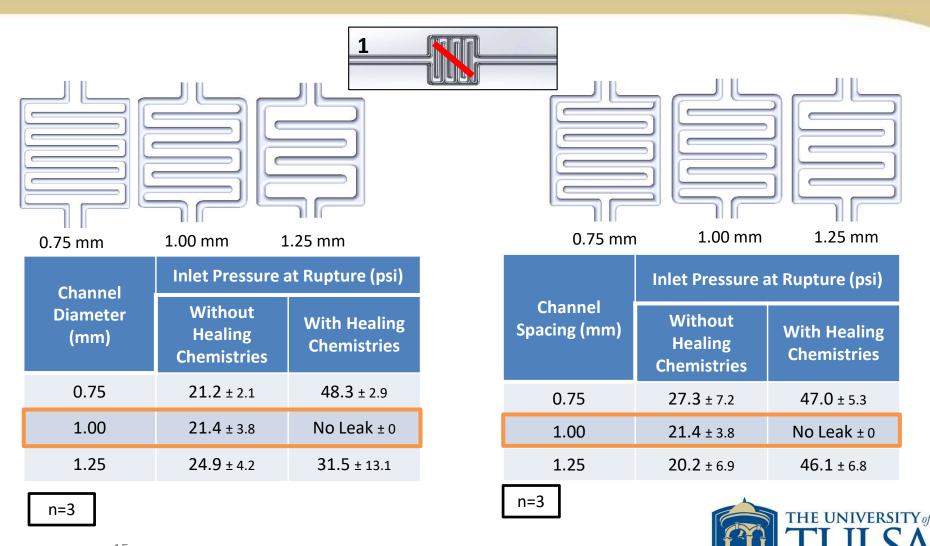


	Sample	1	2	3	4	5	6	7
]	No HC Leak Pressure	21.4 ± 3.8	40.0 ± 4.9	21.6 ± 6.1	42.0 ± 9.0	30.7 ± 17.3	12.3 ± 11.3	No Leak
	HC Leak Pressure	No Leak ± 0	No Leak ± 0	49.6 ± 0.7	No Leak ± 0	45.3 ± 8.2	47.6 ± 4.1	No Leak

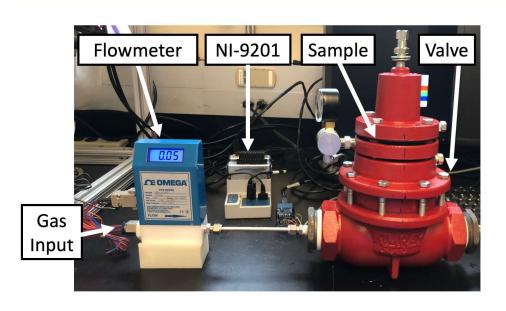
n=3



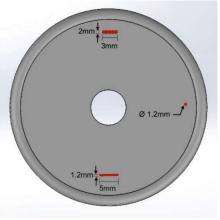
Varying Channel Diameter and Spacing Results



Commercial System

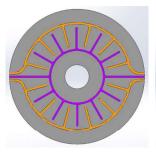


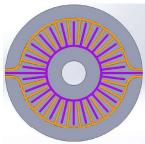




(a) Silicone rubber diaphragm.

(b) Damage types.







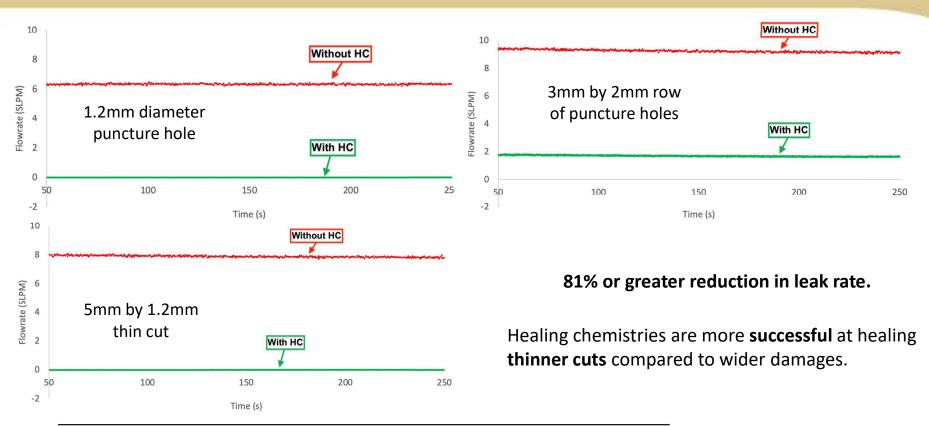








Leak Rate Results



Damage	Before Healing Chemistries	After Healing Chemistries	Leak Rate Reduction
1.2mm by 1.2mm	6.32 ± 0.01	0.05 ± 0.00	100%
3mm by 2mm	9.36 ± 0.06	1.75 ± 0.02	81%
5mm by 1.2mm	7.94 ± 0.00	0.05 ± 0.02	100%

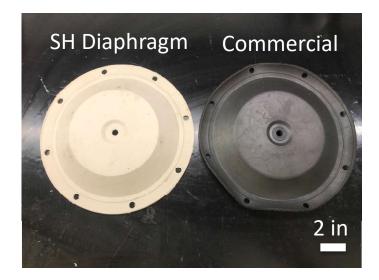


Large Scale Diaphragm Production



3D Printed Mold





Successful manufacture of a full-scale motor diaphragm with embedded microvascular network.



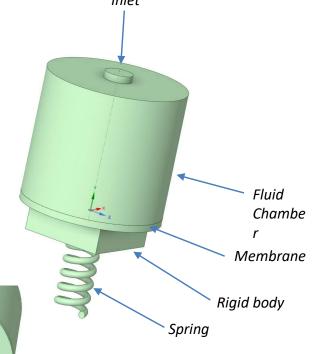
Physics-Based Model Setup

 A three-dimensional high-fidelity numerical model was used to generate a synthetic dataset for the operation of a pneumatic actuator

Methane is injected at the inlet.

Pressure buildup in the chamber depresses the me

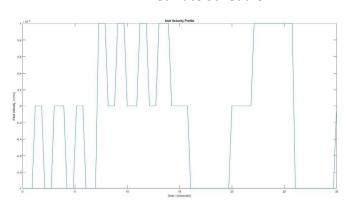
Leaks are modelled as tiny pressure outlets at the k



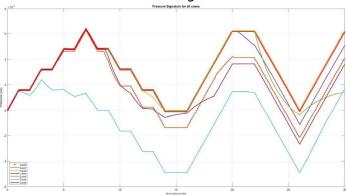


Overview of Dataset

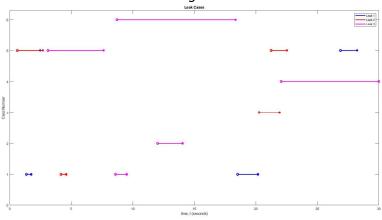
Inlet Rate Schedule



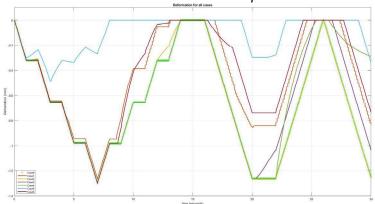
Pressure Signals



Leak logs

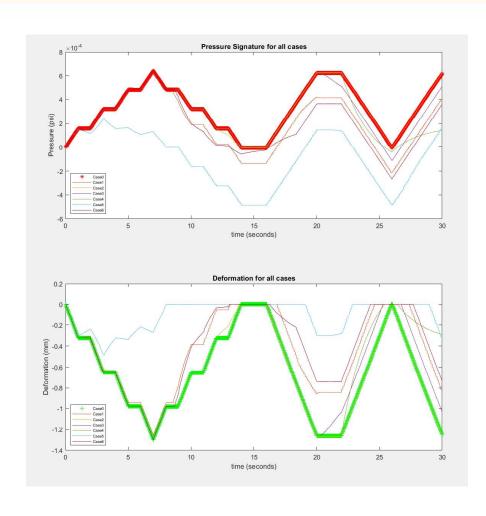


Membrane's Vertical Displacement





Review of Dataset



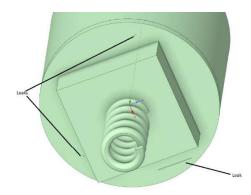
- The complete dataset is comprised of N=10,500 entries
- Each data entry is the tuple $d_i = \{t_i, v_i, P_i, y_i, L_i\}$
- L_i is an integer indicator of rupture status



Statistical Methods

- The dataset enables a supervised learning approach
- The response variable Y is a probability of rupture class (0 to 3)
 - 0 unruptured
 - 1 circular rupture of diameter 0.1mm on diaphragm edge
 - 2 circular rupture of 0.1mm near spring-rod attachment,
 and
 - 3 tear of length 2mm.
- The features used as predictors at any instant are:

$$\mathbf{x} \coloneqq \left\{ P_i, y_i, \dot{P}_i \coloneqq \frac{P_{i+1} - P_i}{t_{i+1} - t_i}, \dot{z}_i \coloneqq \frac{z_{i+1} - z}{t_{i+1} - t_i} \right\}.$$





Statistical Methods

QDA:

$$Pr\left(Y = k \mid X = x\right) = \frac{\pi_k f_k\left(x\right)}{\sum_{l=1}^{K} \pi_l f_l\left(x\right)}$$

$$y = \underset{k \in \{0,1,2,3\}}{\operatorname{argmax}} - \frac{1}{2} \left(x - \mu_k \right)^T \Sigma_k^{-1} \left(x - \mu_k \right) - \frac{1}{2} \log \left| \Sigma_k \right| + \log \pi_k$$

• KNN:

$$\widehat{Y}(x) = \frac{1}{k} \sum_{x_i \in N_k(x)} y_i$$

$$f_{avg}(x) = \frac{1}{B} \sum_{b=1}^{\infty} f^b(x)$$

$$f_{avg}(x) = \frac{1}{B} \sum_{b=1}^{B} f^b(x)$$



Results of Simulation

QDA

> table(qo	da.clas	ss, Le	eak.t	est)
	Leak.te	est		
qda.class	0	1	2	3
0	2716	14	4	22
1	87	52	3	0
2	961	50	64	0
3	711	23	1	542

QDA RESULT						
Classes	Tota	Predicted	Percent			
	- 1	Case	Accuracy (%)			
	Case					
No Leak	4475	2716	60.69			
Leak 1	139	52	37.41			
Leak 2	72	64	88.89			
Leak 3	564	542	96.10			

KNN

> table(k	nn.pre	ed, Le	ak.t	est)
I	eak.te	est		
knn.pred	0	1	2	3
0	4424	35	4	40
1	11	99	3	2
2	4	4	65	0
3	36	1	0	522

	KNN RESULT							
Classes	Total Case	Predicted Case	Percent Accuracy (%)					
No Leak	4475	4424	98.86					
Leak 1	139	99	71.22					
Leak 2	72	65	90.28					
Leak 3	564	522	92.55					

BAGGING

> table(k	oag.pre	ed, Le	ak.t	est)
1	Leak.te	est		
<pre>bag.pred</pre>	0	1	2	3
0	4420	38	3	39
1	17	96	6	2
2	2	4	63	0
3	36	1	0	523

BAGGING RESULT						
Classes	Total Case	Predicted Case	Percent Accuracy (%)			
No Leak	4475	4420	98.77			
Leak 1	139	96	69.06			
Leak 2	72	63	87.50			
Leak 3	564	523	92.73			

Methods	Prediction Accuracy(%)	AUC
QDA	86.91	0.8278
KNN	97.52	0.9439
Decision Tree	96.44	0.9161
Bagging	97.26	0.9412
Random Forest	97.35	0.9434



Ongoing Work

Apply non-dimensional features and augment the data-set with further samples to adequately span the dimensionless parameter space.

Mass Balance

$$(\kappa + Y^*) \frac{\partial P^*}{\partial t^*} + P^* \frac{\partial Y^*}{\partial t^*} = \eta$$

$$Y^* = \frac{y}{y_o}; \quad P^* = \frac{P}{P_o}; \quad t^* = \frac{t}{t_o};$$

$$\kappa = \frac{3H}{2y_o}; \quad \eta = \frac{6t_oZRT}{\pi P_o y_o L^2 M} (q_{in} - q_{leak})$$

Momentum Balance

$$\alpha \frac{\partial^2 Y^*}{\partial X^{*2}} + P^* = \beta \frac{\partial^2 Y^*}{\partial t^{*2}}$$

$$\alpha = \frac{Ty_o}{P_o L x_o^2}; \quad \beta = \frac{\rho y_o}{P_o L t_o^2}$$



Acknowledgments

Research Group:

Mahfujul Khan, PHD

Anna Williams

Peter Lynch

Collaborators:

Rami Younis

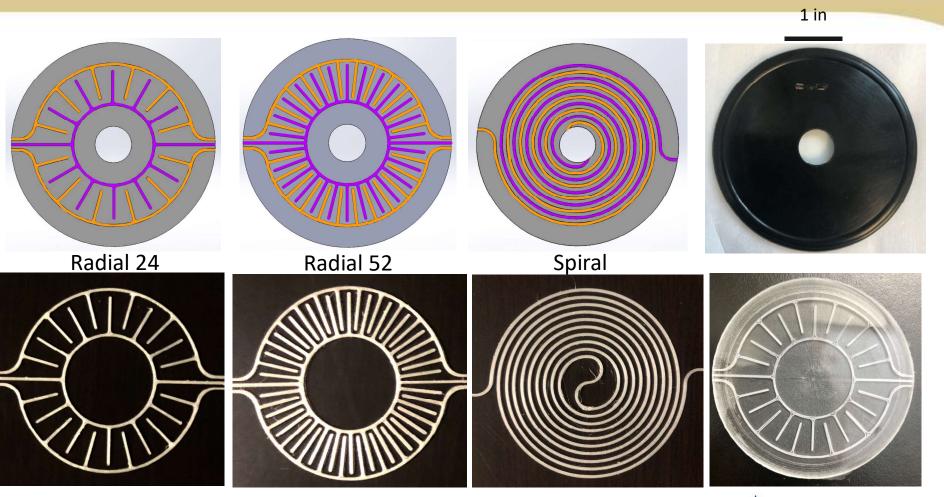
Ahmed Adeyemi

Cem Sarica





Microvascular Network Geometries





Microvascular Network Geometries



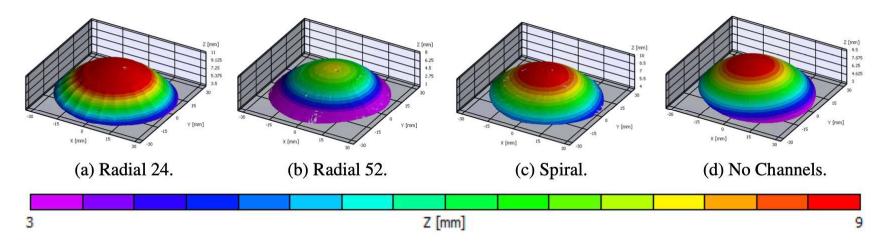
DIC Test Procedure

Load sample into DIC set-up

Initiate 5 fps timed capture within Vic Snap

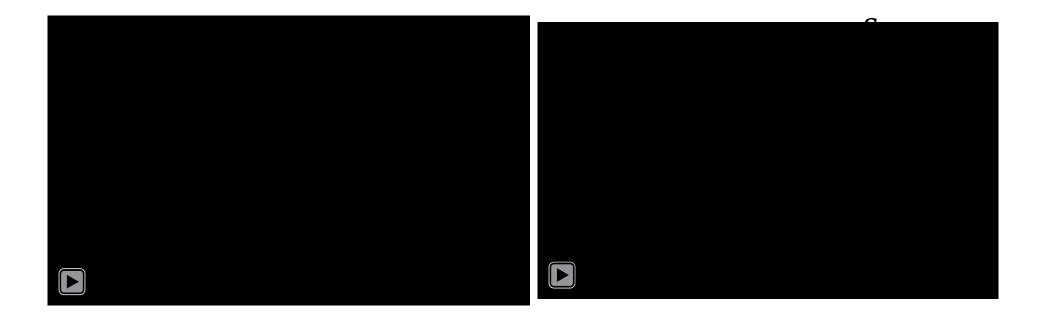
Pressurise system up to 5psi

Analyse images in VIC 3D



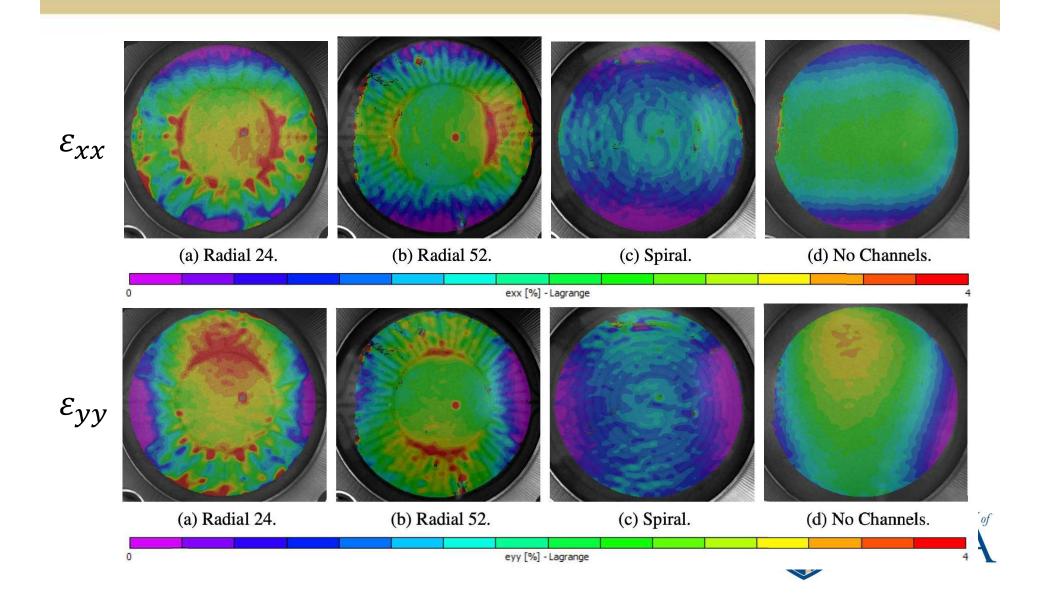


Inflating the Diaphragm

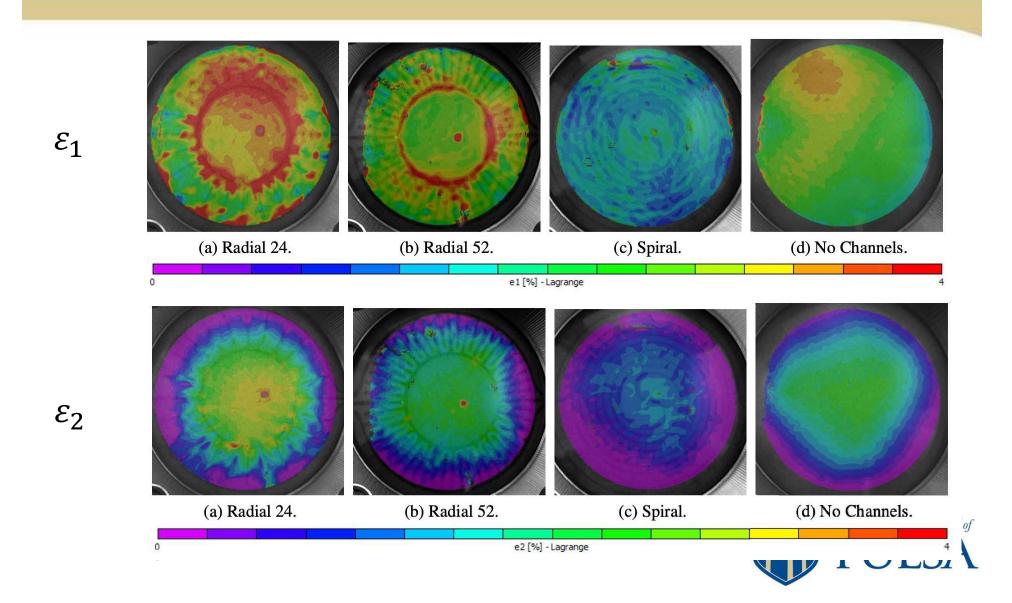




Strain Results for Designs



Strain Results for Designs



Comparison of Maximum Strains

Sample	ϵ_{xx}	ϵ_{yy}	ϵ_{xy}
Radial 24	4.36	4.50	1.46
Radial 52	4.16	3.82	1.11
Spiral	1.93	2.06	0.94
No Channels	2.45	3.26	1.20

Sample	ϵ_1	ϵ_2
Radial 24	4.88	3.18
Radial 52	4.48	2.48
Spiral	2.39	1.41
No Channels	3.42	2.36

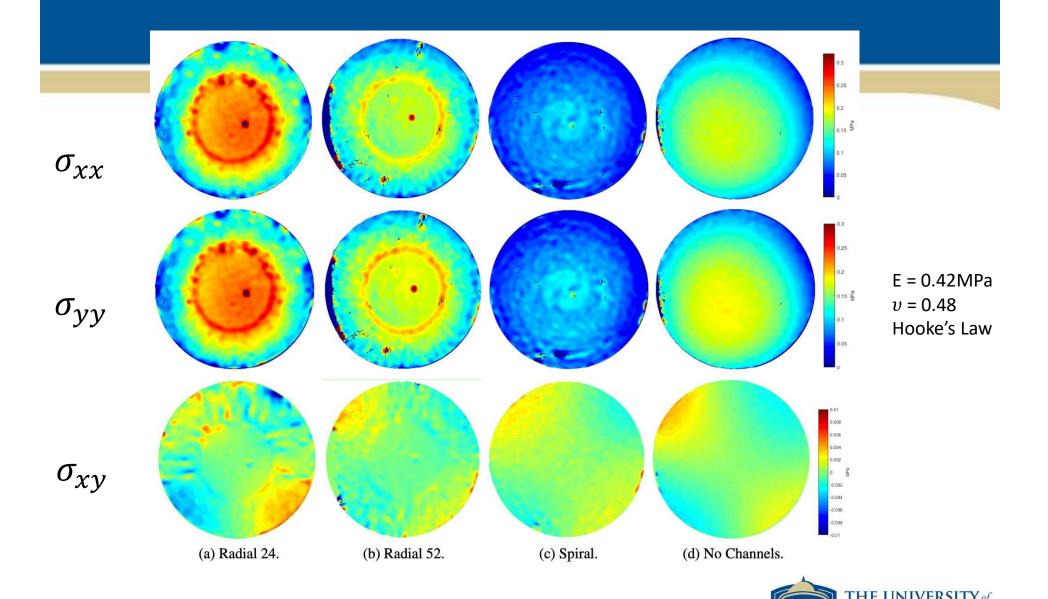
Radial 24 had the highest strains across all directions

Spiral had the lowest strains across all directions

All strain values across all samples are **low** compared to the Elongation at Break (1000%) property of the material

Integration of microchannels into diaphragm materials would not significantly interfere with the integrity of the material.





Comparison of Maximum Stresses

Sample	σ_{xx}	σ_{yy}	σ_{xy}
Radial 24	0.3733	0.3748	0.0126
Radial 52	0.3126	0.3145	0.0136
Spiral	0.2463	0.2549	0.0115
No Channels	0.2829	0.2688	0.0046

All stress values across all samples are **far below** the material's tensile strength of 3.275 MPa.

Radial 24 had the highest stresses across all directions

Spiral had the **lowest** stresses across all directions

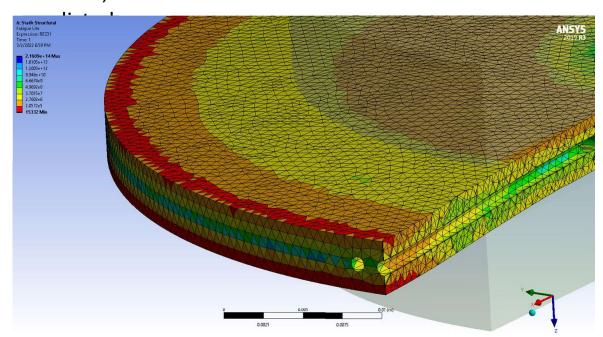
Remain satisfied that the integration of microchannels into diaphragm materials would not significantly interfere with the integrity of the material.



Comparison with FEA Simulations



Both experimental and simulation expect stresses around the channels lower than the yield strength of the material, hence no failure at central channels is



Simulation by Dr. Khan, University of Tulsa

Neo Hookean Elasticity Thomas fatigue model predicts failure at edge clamped zone – again agreeing with the life of the material not being compromised by the addition of channels



Appendix

 These slides will not be discussed during the presentation, but are mandatory.



Benefit to the Program

- Reduction of methane release by at least 80%.
- Insert project benefits statement.
 - See Presentation Guidelines for an example.



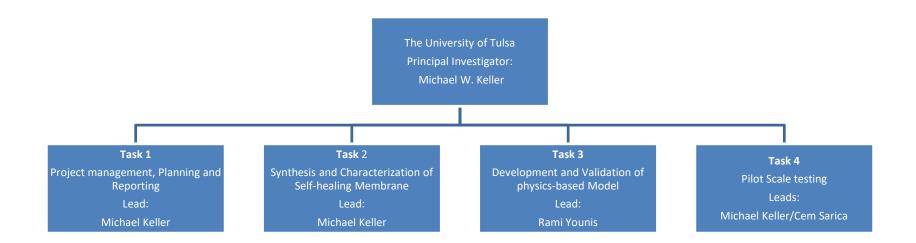
Project Overview

Goals and Objectives

- Demonstrate the ability to automatically repair pneumatic controllers from a wide range of damage.
- Develop appropriate SCADA-based real-time monitoring tools to identify a damaged pneumatic controller
- Develop appropriate SCADA-based tools to determine if self-repair was effective.
- Provide technoeconomic analysis of the proposed system.
- Demonstrate the system in a pilot scale flow loop.



Project Organizational Chart





Gantt Chart

Wee	Teah Subteah Mille stone	CN	Ctont				Quarters						
WBS Task/Subtask/Milestone		G/N	Start	End	1	2 3	4	5 (7	8	9 1	0 11	12
1	Project management and Planning		0	1									
1.1	Revise PMP		0	1									
M1.1.1	Submit Revised PMP		1	1	-								
1.2	Technology Maturation Plan		0	1									
M1.2.1	Submit technology maturation plan		1	1	A								
2	Demonstrate Self-healing of Diaphragm		0	8		-	-						
2.1	Assess self-healing using model system		0	4		-							
M2.1	Complete testing of self-healing diaphragm and controls for at least 1 self-healing system.	G/N	4	4			•						
2.2	Demonstrate self-healing in pneumatic controller		2	8			-		251				
M2.2	Demonstrate reduction of leak rate by at least 80% compared to a non-healing control	G/N	8	8									
3	Demonstrate SCADA-based analytics		0	12		100	-		4.5				
3.1	Develop Physics-based model		0	8	-	-							
M3.1	Demonstrate physics model with sufficient fidelity to detect a 10 scf/h leak		8	8						-			
3.2	Demonstrate leak detection on test stand		6	12								_	
M3.2	Demonstrate the ability to detect a leak rate of at least 10 scf/h		12	12									
4	Assess self-healing and SCADA detection in pilot loop		5	12						1			
4.1	Construct test stand in pilot loop		5	10									
M4.1	Construct and validate pilot scale test stand		10	10								A	
4.2	Demonstrate leak detection via SCADA in pilot plant		5	12								_	
M4.2	Demonstrate the ability to detect a leak rate of at least 10 scf/h	G/N	12	12									
4.3	Demonstrate self-healing in pilot plant		5	12								-	
M4.3	Demonstrate the ability to reduce the leak rate by 80% under simulated operating conditions.	G/N	12	12									



Bibliography

 List peer reviewed publications generated from the project per the format of the examples below.

• None to report

