2021 DOE/FE Spring R&D Project Review Meeting

Development and Evaluation of a General Drag Model for Gas-Solid Flows via Physics-Informed Deep Machine Learning

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Agenda

- Project Objective
- Project Status
- Technical Progress
 - Background/Motivation for the Project
 - Regular vs. Irregular Shapes
 - Data Collected So Far
 - Data Challenges
 - C_D of Particles of Different Shapes
 - DNN Model Development
 - Performance Summary
- Conclusion
- Plan for the Next Few Months

Project Objective

The overall objective of this project is to develop, test, and validate a general drag model for multiphase flows in assemblies of non-spherical particles by a physics-informed deep machine learning (PIDML) approach using artificial neural network (ANN).



Project Status

Project	Time	line
1 101001		

Task Name	Assigned Resources	Year 1			Year 2					Year 3			
		Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4	Qtr 1	Qtr 2	Qtr 3	Qtr 4
Task 1.0 - Project Management and Planning	PI												
Task 2.0 - Data Collection and Generation	Team												
Subtask 2.1 Data Collection	Team				t								
Milestone A				•									
Subtask 2.2 Data Generation	Co-PI												
Milestone B]			•	•							
Decision Point 1	Team								_				
Task 3.0 - ANN Model Development	Co-PI]											
Subtask 3.1 ANN Model Training & Test	Co-PI								_				
Milestone C						-	•						
Subtask 3.2 ANN Algorithm Evaluation	Team												
Milestone D								-					
Decision Point 2	Team										_		
Task 4.0 - Drag Model Integration	Team]											
Milestone E													
Decision Point 3	Team												
Task 5.0 - Multiphase Flow CFD Validation	Team												
Subtask 5.1 Multiphase Flow Validation	PI]											
Milestone F											-		
Subtask 5.2 ANN Model Modification	Co-PI												
Milestone G													•

Technical Background/Motivation for the Project

Most of existing work considers at most two features (i.e., Reynolds & sphericity)

Drag coefficient also depends on multiple other features such as aspect ratio, lengthwise sphericity, crosswise sphericity, density ratio, etc.

Traditional correlation-based methods have drawbacks:

- Limited number of features
- Limited feature range
- Limited to specific experimental conditions

Neural network can efficiently consider the effects of all these features and predict drag coefficient with high accuracy.

Regular vs. Irregular Shaped Particles

Regular shaped particles:

 A particle of geometric parameters such as volume and surface area that can be mathematically determined

Irregular shaped particles:

• An arbitrary random particle whose geometric parameters cannot be precisely calculated

¹Dioguardi, F., D. Mele, and P. Dellino. "A new one-equation model of fluid drag for irregularly shaped particles valid over a wide range of Reynolds number." Journal of Geophysical Research: Solid Earth 123, no. 1 (2018): 144-156.



Regular-shaped Particles

Data Collected So Far

Digitalized several more papers/reports (> 4K data points)

- Created a combined spreadsheet with data of drag coefficients at identified features
- Performed preliminary data analysis of feature importance and feature correlation
- Conducted a systematic experimental analysis on various data configurations

* Particle shape and settling velocity are retrieved from David, 2017. Other parameters including Re and Cd are calculated ourselves to be consistant with other data



Feature Generation

$$C_{D} = f\left(Re, R_{\rho}, \varphi, AR, \varphi_{\parallel}, \varphi_{\perp}\right)$$
Flow property
$$\begin{cases} Re: \text{Reynolds number} \\ R_{\rho}: \text{Density ratio between fluid} \\ \text{and particle} \end{cases}$$
Particle geometry
$$\begin{cases} \varphi: \text{Sphericity} \\ AR: \text{Aspect ratio} \end{cases}$$
Settling direction
$$\begin{cases} \varphi_{\parallel}: \text{Lengthwise} \\ \varphi_{\perp}: \text{Crosswise} \end{cases}$$

$$Re = \frac{\rho_{fluid} u_{particle} d_{particle}}{\mu_{fluid}}$$

$$R_{\rho} = \frac{\rho_{fluid}}{\rho_{particle}}$$

$$\varphi = \frac{A_{volume} e_{quavlent sphere}}{A_{particle}}$$

$$AR = \frac{l_{max}}{l_{min}}$$

$$\varphi_{\parallel} = \frac{A'_{volume} e_{quavlent sphere}}{\frac{A_{particle}}{2} - A'_{lenthwise}}$$

$$\varphi_{\perp} = \frac{A'_{volume} e_{quavlent sphere}}{A'_{Crosswise}}$$

A: Surface area A': Cross-sectional area

Data Challenges

Learning from limited data sets

• The model doesn't generalize well from our training set to unseen set, resulting in overfitting

Extreme values

- Results in longer training times
- Less accurate models
- Can spoil and mislead the model training process





C_D of Particles with Different Shapes

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Correlations-Based Drag Model

Yow et al., 2005Chien, 1994Hölzer & Sommerfeld, 2008
$$C_D = \frac{a_1}{Re} + \frac{b_1}{\sqrt{Re}} + c_1$$
 $C_D = \frac{30}{Re} + \frac{67.289}{e^{5.030\varphi}}$ $C_D = \frac{8}{Re} \frac{1}{\sqrt{\varphi_{\parallel}}} + \frac{16}{Re} \frac{1}{\sqrt{\varphi}} + \frac{3}{\sqrt{Re}} \frac{1}{\varphi^{3/4}} + 0.42 \times 10^{0.4(-\log(\varphi))^{0.2}} \frac{1}{\varphi_{\perp}}$ where: $a_1 = 15.21 + \frac{10.82}{\varphi} - \frac{0.14}{\varphi^2}$ Haider & Levenspiel, 1989 $b_1 = 13.41 - \frac{10.64}{\varphi} - \frac{0.06}{\varphi^2}$ $C_D = \frac{24}{Re} \left[1 + e^{2.3288 - 6.4581\varphi + 2.4486\varphi^2}Re^{0.0964 + 0.5565\varphi} \right]$ $c_1 = -8.82 + \frac{5.70}{\varphi} + \frac{0.23}{\varphi^2}$ $+ \frac{Re \times e^{4.905 - 13.8944\varphi + 18.4222\varphi^2 - 10.2599\varphi^3}{Re + 0.07322\varphi^2 + 15.8855\varphi^3}$

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DNN vs. Machine Learning

- Preliminary study and results demonstrate DL/ML models can achieve better performance
- The more data we can feed the model to learn, the better result we obtain

Data: Tran-Cong, 2004; Song, 2017; Kale, 1987; Yow et al, 2005



DNN plus Additional Regularization Methods

Refining/Adjusting the DNN algorithm through model regularization and generalization

- Noise Augmentation
- Dropout Layer
- Mean Absolute Error (MAE) Loss Function
- Exponential Linear Unit (ELU) Activation

Data: Tran-Cong, 2004; Song, 2017; Kale, 1987; Chen & Li, 2020



Experimental Setup

Performance metrics

$$RMSE = \sqrt{\sum_{i=1}^{n} \frac{(\hat{y}_i - y_i)^2}{n}}$$

Three-Fold Cross Validation

• Assessing how well the ML model will generalize to an independent data set

$$MAE = rac{1}{n}\sum_{j=1}^n |y_j - \hat{y_j}|$$



Performance Summary

- Conventional methods may have lower RMSE values, and they are better at accounting for extreme cases
- However, higher MAE values demonstrates the it doesn't generalize well to unseen data
- Our proposed DNN model can predict more robust results compared to traditional methods using MAE metric



Proposed DNN + Correlation-Based Methods

Stacked Generalization -

Learn how to combine the predictions from traditional correlation with proposed DNN

Data: Latest database compiled from 30+ publications



Performance Summary

Data Configuration Key:

- (R) Regular Particles Experimental Drag Data
- (I) Irregular Particles Experimental Drag Data
- (C) Regular Particles Correlation-based Drag Data



Data

Current Project Status 103

Proposed DNN vs. Conventional Drag Model

Performance comparison for particles of low sphericities demonstrate the capability of the proposed DNN



DNN vs. Conventional Drag Model 0.313 < $\phi \le 0.411$

Conclusion

In this work, we have used datasets available in the literature, 4171 samples from 30+ papers, to develop a general drag coefficient model.

Within the investigated parameter range, it is found:

- An improved drag coefficient model was developed by considering more features such as, aspect ratio, lengthwise sphericity, crosswise sphericity, and density ratio.
- DNN model with Stack Generalization ensemble can predict better results compared to traditional methods using RMSE and MAE metric.
- The proposed Stack Generalization technique is proven to achieve better performance, especially when irregular-shaped and low-sphericity particles are included in the dataset.

Plan for the Next Few Months

- Continue to search for more data in the literature and expand the database.
- Perform synthetic data generation to further address the issue of missing values.
- Conduct further experiments to explore the combination of traditional correlation-based methods with DNN model in an ensemble approach.
- Apply more physics-informed methods to the DNN model to improve the performance.

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