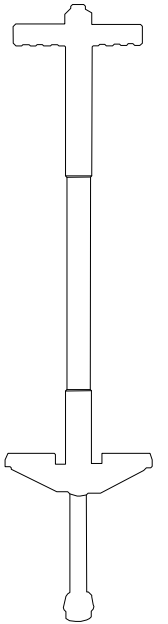
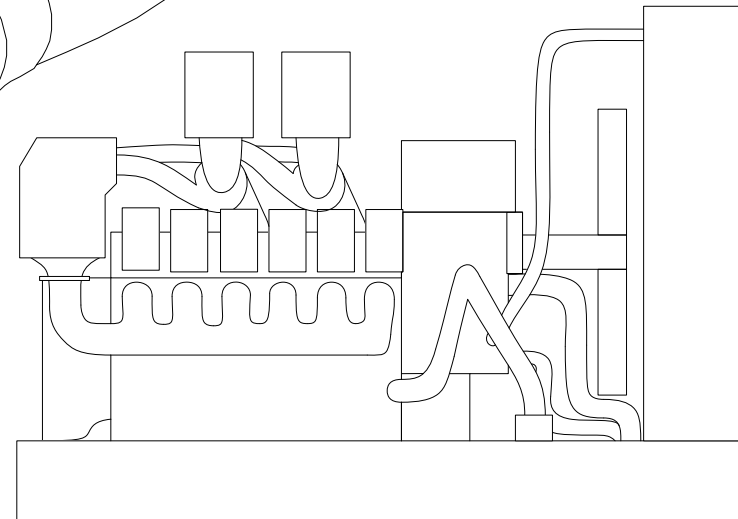
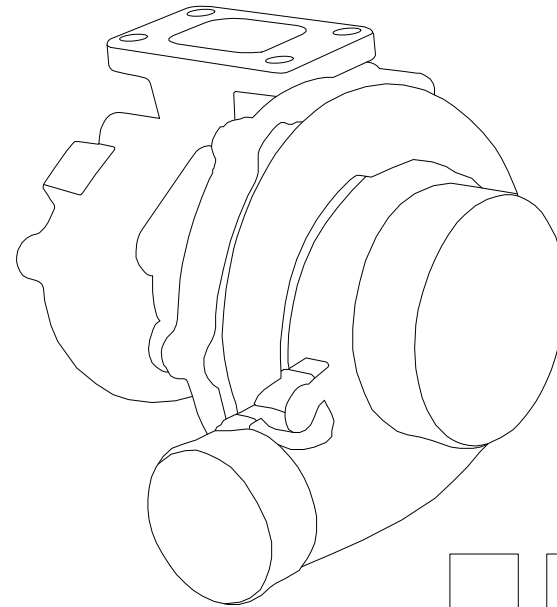


Paths to Control Viability

Factors adding to the challenge of controlling a system

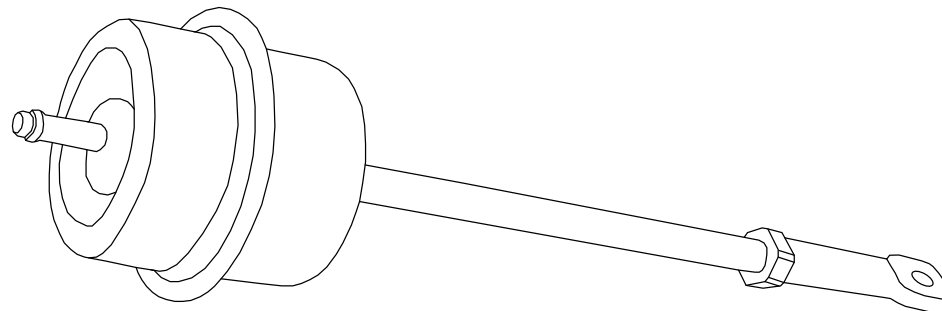
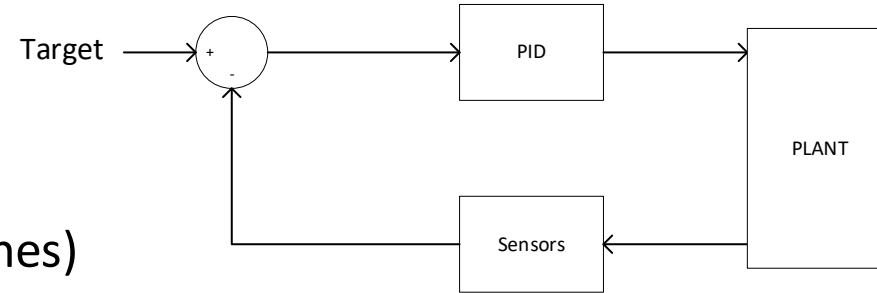
- **Device Complexity**
 - Interrelation of control variables
 - Many, potentially conflicting, control actuators
 - Non-linear behavior
 - Complex equipment damage characteristics
 - Personal safety concerns
- **Device Response Time**
 - Quickly reacting controls
 - Quickly reacting system
 - System response time similar to control response time
 - Required time to reach damage thresholds
- **Device Durability**
 - Proximity to damage thresholds
 - Overload capability



Paths to Control Viability

Available Control Tools

- Controller Topologies
 - Simple PID (feedback)
 - State-Space controllers
 - Prediction or feed-forward tables
 - Non-linear control systems (such as state machines)
 - Model Predictive Control
- Design Decisions
 - Integrated safety stops or features
 - Operating well below design capability
 - Self-regulation
 - Secondary control



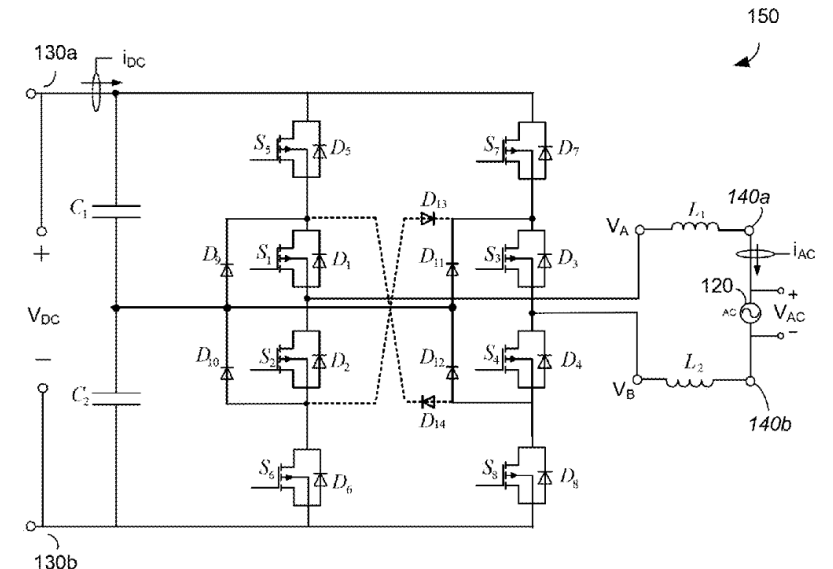
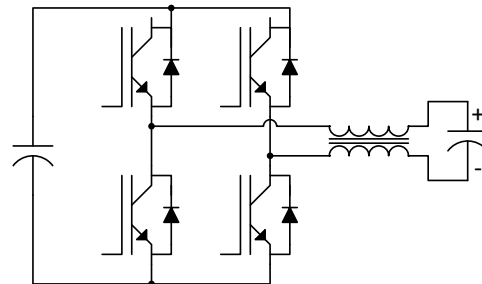
Paths to Control Viability

Examples

- Controlling internal combustion engine speed
 - Lawn Mower
 - Simple engine; loose requirements
 - Generator
 - Simple Engine
 - Spark Ignited
 - Turbocharged



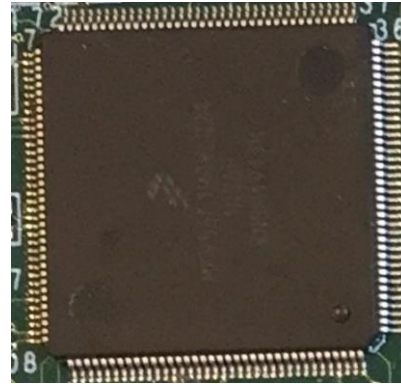
- Controlling power electronics
 - Simple H-bridge inverter
 - 3-level converter
 - Multi-level resonant converter



Paths to Control Viability

Practical considerations

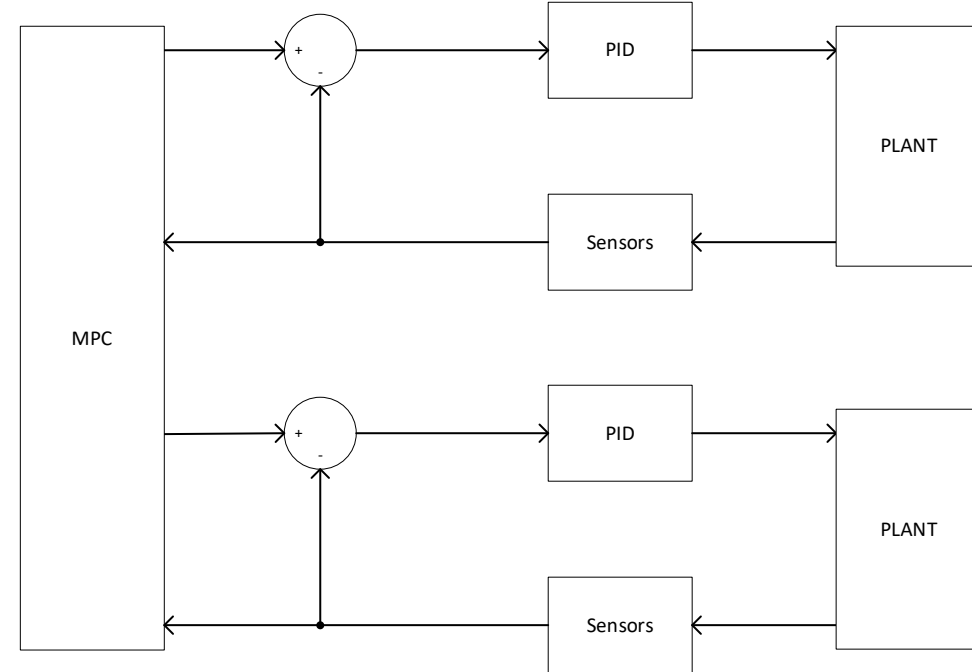
- Hardware
 - Processor
 - Operating system
 - Connections to system
- Cycle Time
 - Control system update rate
 - Feedback update rate
- Delay in feedback
 - Sampling delay
 - Measurement delay
- Actuator
 - Available effort
 - Wear and tear
 - Response time



Paths to Control Viability

Summary

- MPC
 - Greatly expands control capability
 - Often reduces actuator effort
 - Requires large computing resources
 - Is seldom able to react quickly
- Simple controllers
 - Control limited to simple, linear systems
 - Can operate on low-end hardware
 - Very quick



Combining both strategies can provide excellent control for complex systems.

Paths to Control Viability

QUESTIONS?