

Event Modeling Risk Assessment using Linked Diagrams (EMRALD)

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EMERALD Goals and Objectives

Probabilistically determine the who, how, why and when, of events leading to your system failures by simulating real world conditions.

Existing Capabilities

- Solve engine
- Specialized coupling 1-way and 2-way (with flooding simulation Neutrino)
- Demonstrations of nuclear power plant scenarios

Potential for multiple industries

- Electric grid
- Hydro
- Oil and gas

What is needed (TCF work)

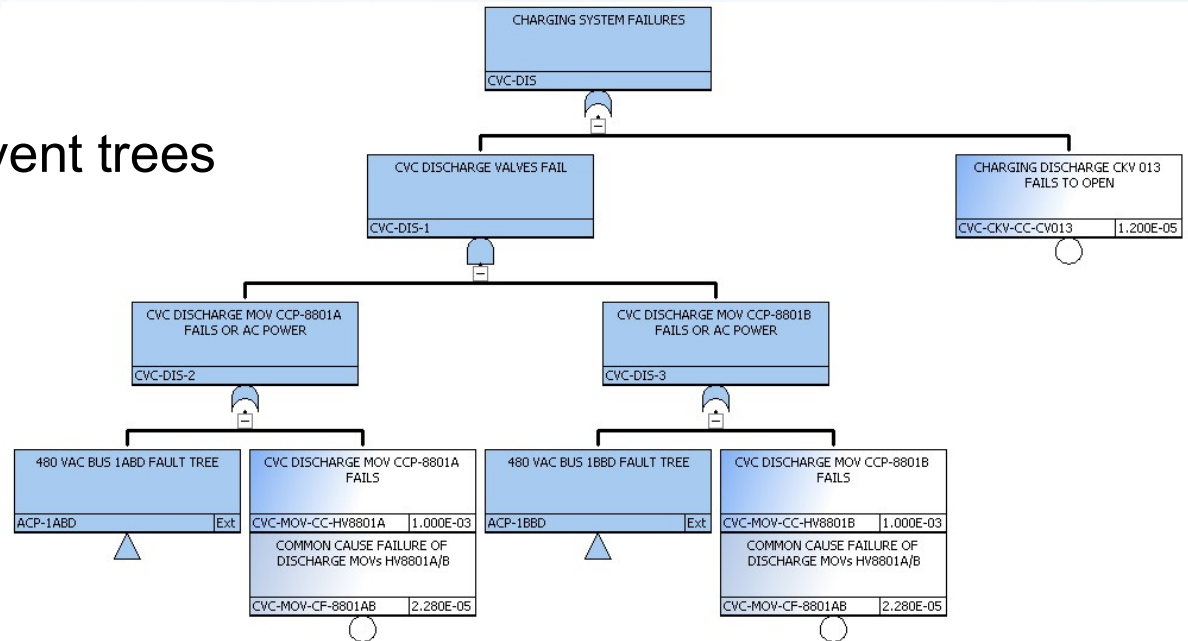
- Generic Communication Protocol & API [Feb 29, March 31]
- Web based User Interface (UI) [April 31]
- Test cases [July 31]
- Beta release [Sept 31]

What is Probabilistic Risk Assessment (PRA)

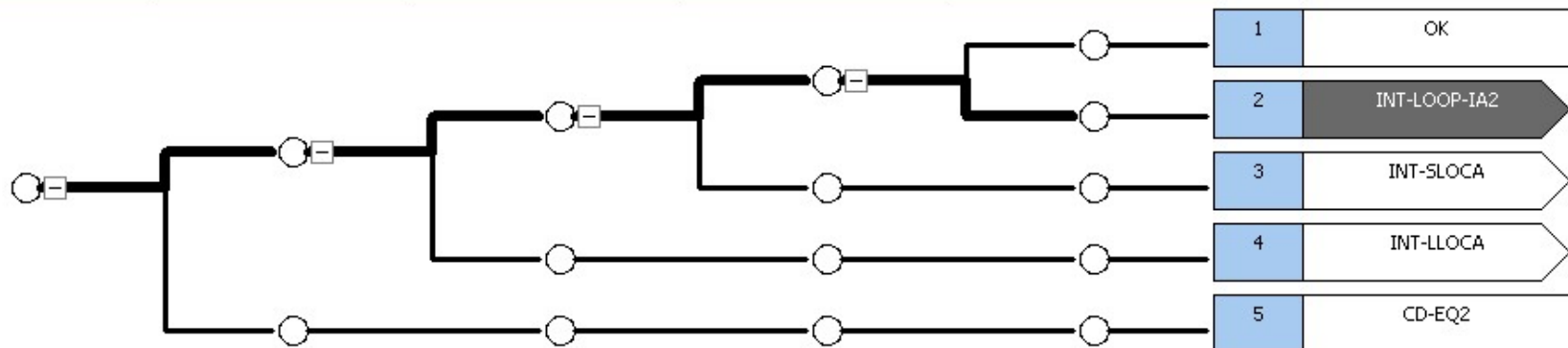
Traditional PRA properties

- Basic events, fault trees, event trees
- Failure probabilities
- Fast calculations
- Static models
- No time aspect

(SAPHIRE developed at INL)



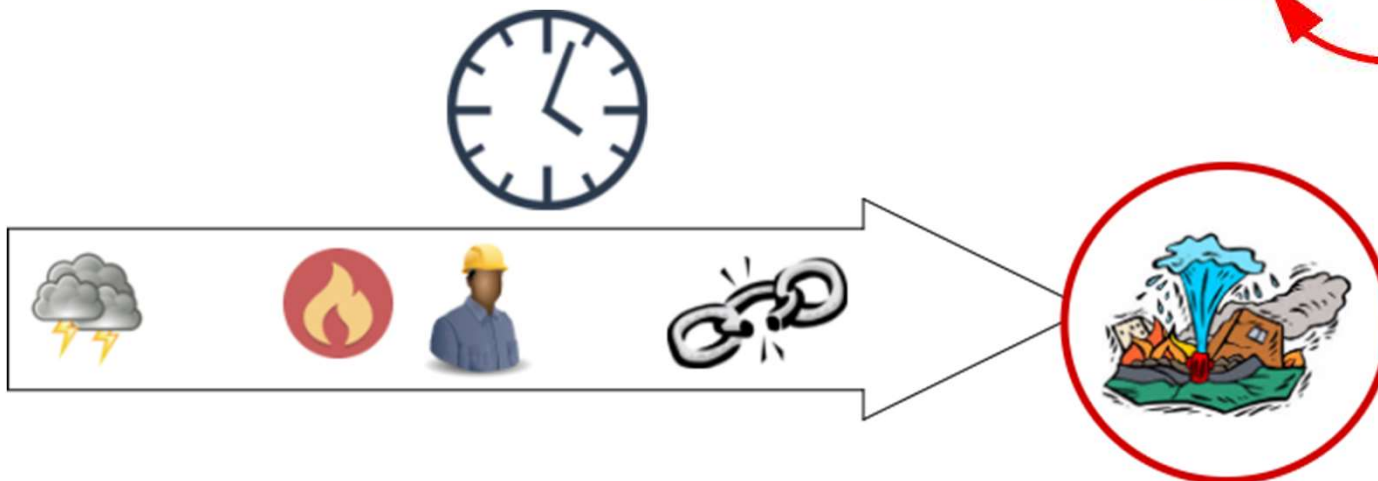
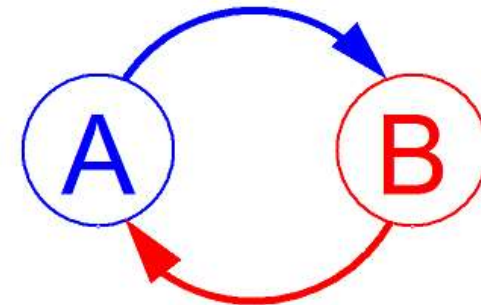
Seismic Initiator (0.3- 0.5g)	Core Damage due to Major Structure Failure	Large LOCA Occurs	Small LOCA occurs	LOOP occurs	#	End State (Phase - CD)
IE-EQK-BIN-2	CD-EQ2	LLOCA-EQ2	SLOCA-EQ2	LOOP-EQ2		



Dynamic PRA

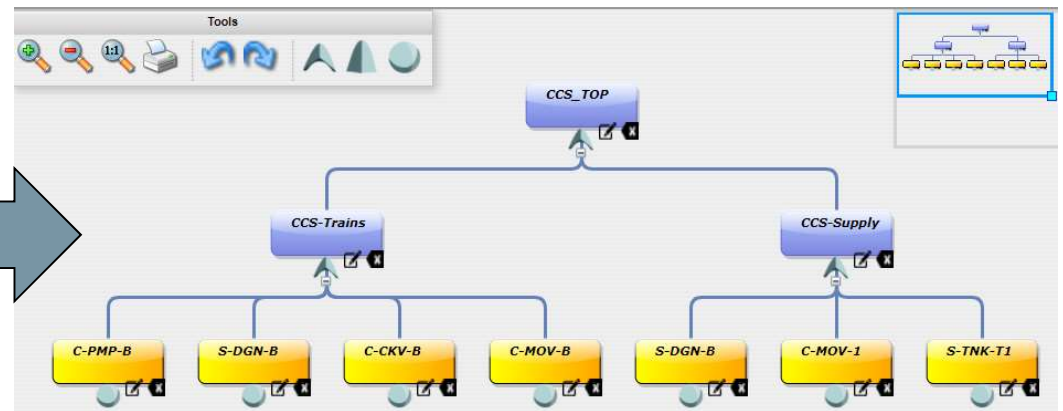
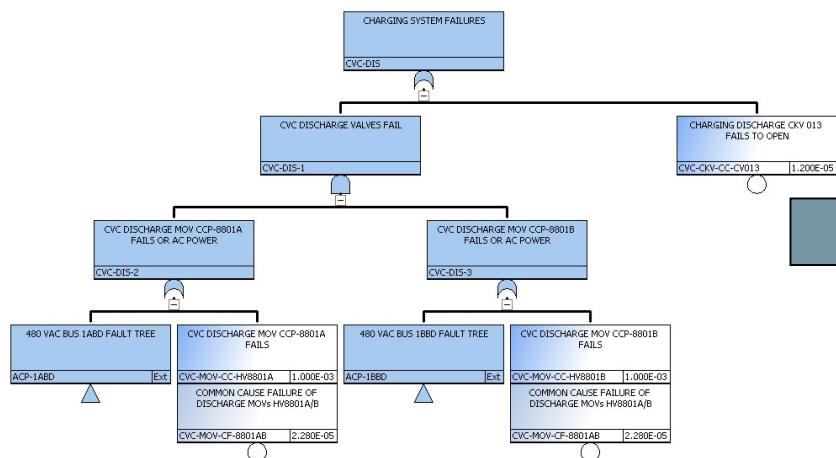
Properties

- Simulation based
- Captures feedback
- Cascade of events in time
- Couple with other simulation
- State based models
- Higher computation costs (Slower)



Why EMERALD

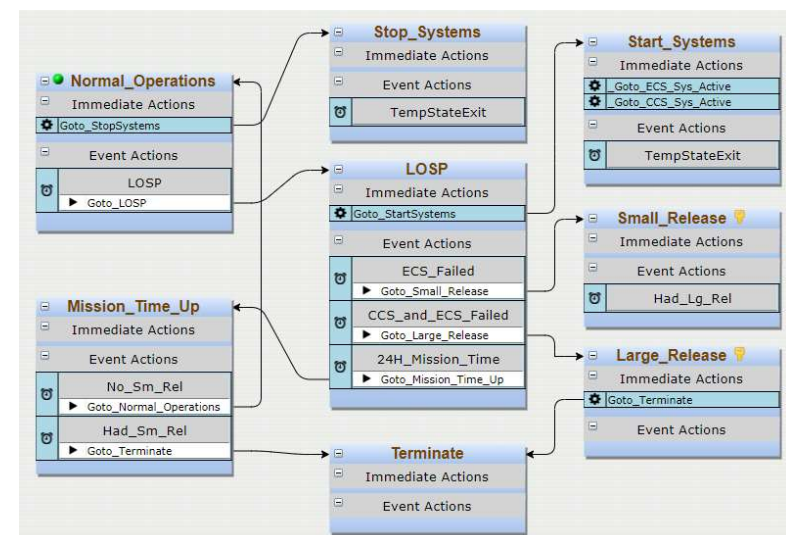
1. Combine modeling methods (existing and new PRA modelers)
2. Industry use focus for UI vs. scientific research



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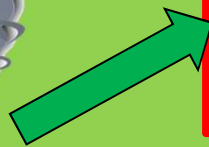
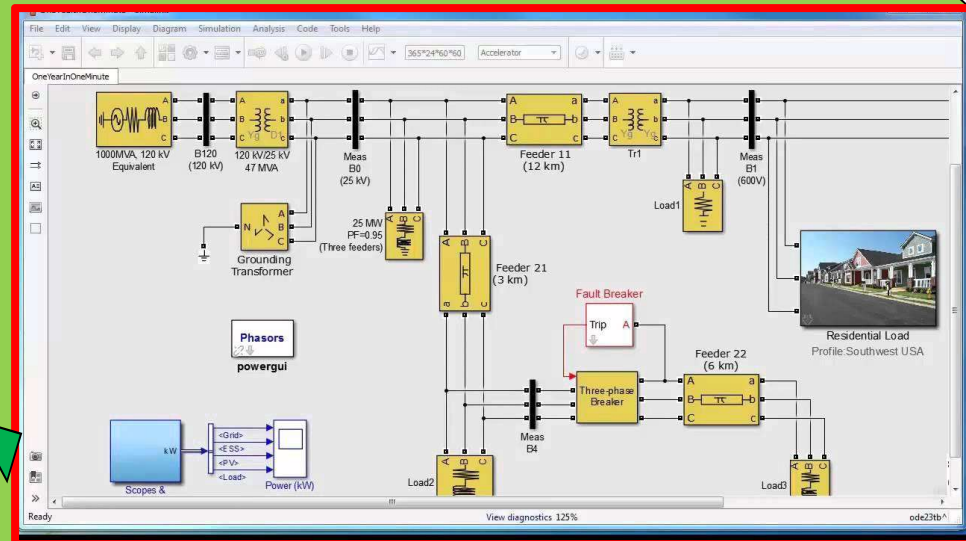
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  <Features>x1, x2</Features>
  <SobolOrder>2</SobolOrder>
  <IndexSet>TotalDegree</IndexSet>
  <PolynomialOrder>4</PolynomialOrder>
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  <Interpolation quad='ClenshawCurtis' poly='Jacobi'
    weight='2'>x2</Interpolation>
</ROM>

```



Why EMERALD (cont.)

3. Evaluate existing design models & tools in operating conditions!
4. Identify key risk contributors
5. Optimize mitigation



EMERALD Modeling - States

Types

- Start – Initiating state for a diagram.
- Standard – a normal state representing no special conditions.
- Key State – marks a state of interest, to be tracked.
- Terminal – ends the simulation run.

State
Actions
Transition
Change Variable
Run Script
Events
Failure Rate Sampling
Timer
State Change
Logic Tree
Evaluate Variable
External Event

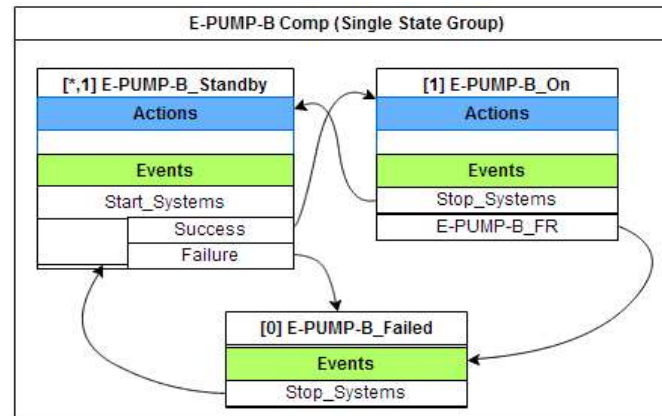
Immediate Actions Section – Actions taken when a new state is entered.

Event Actions – Events to look for when in this state and what action to take if the event is triggered. (Time or Condition)

EMERALD Modeling - Diagrams

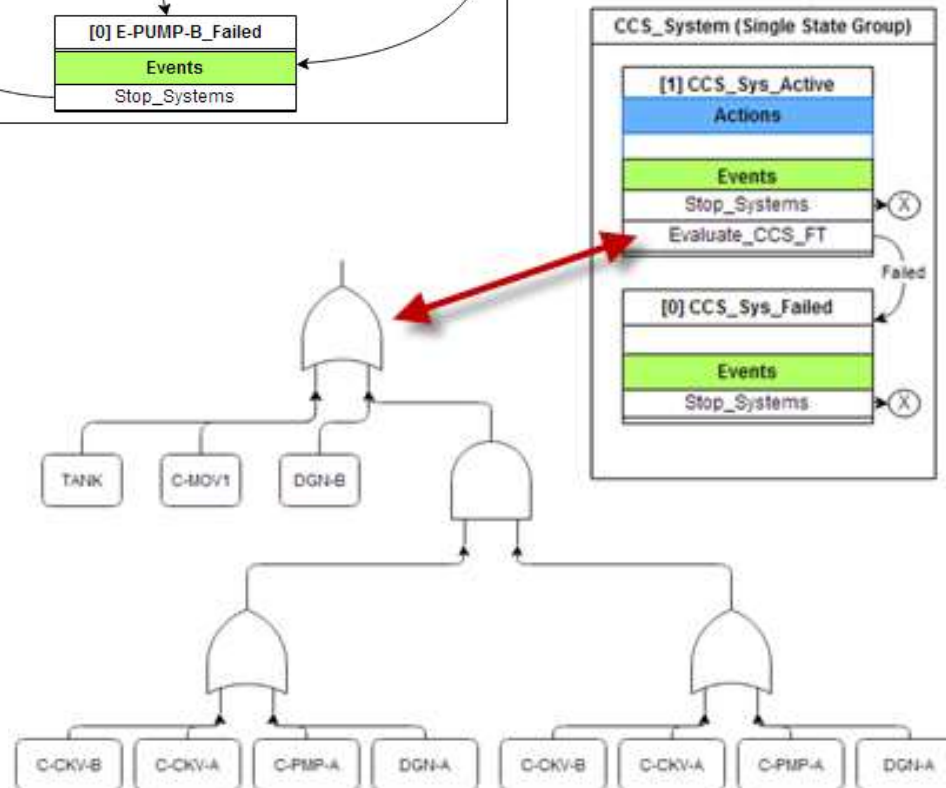
Components

- Failure rates
- Status
- Operator actions



Systems

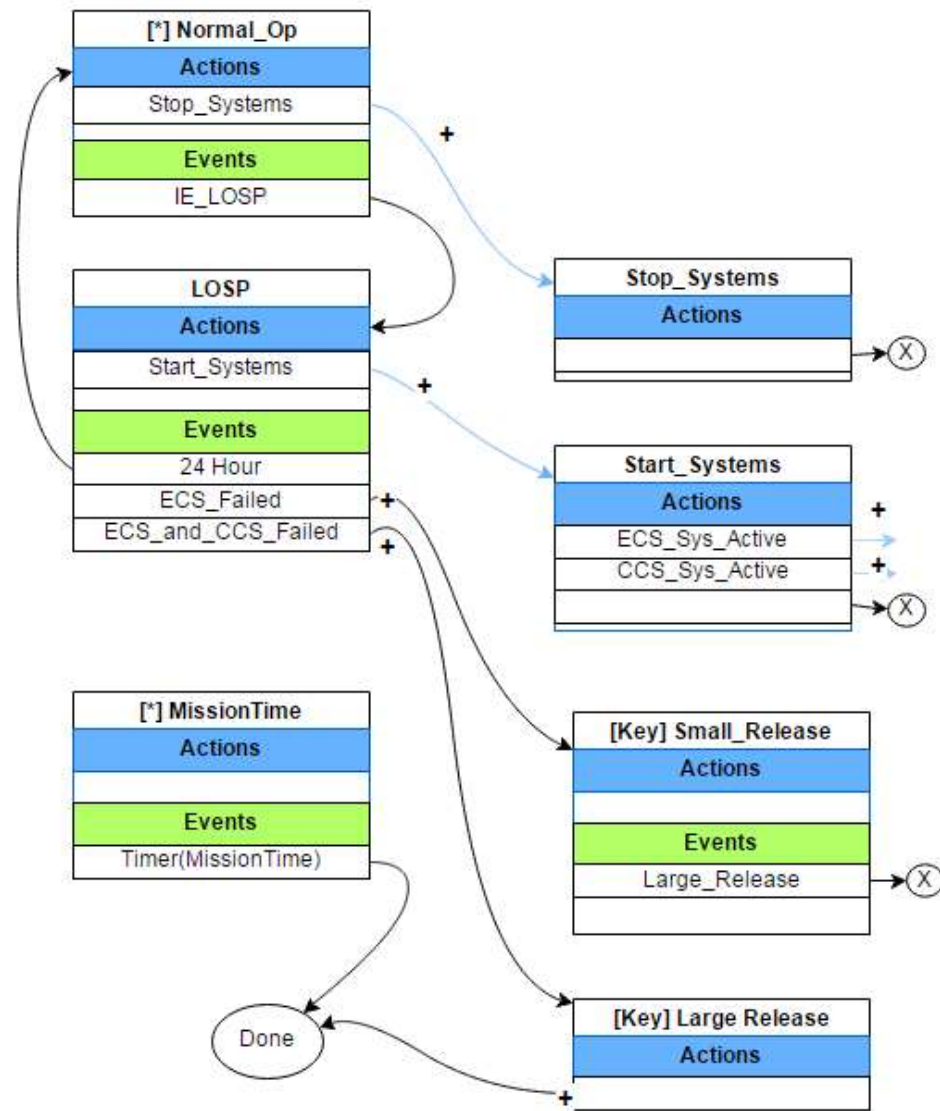
- Component interaction
- Evaluate logic trees



EMERALD Modeling - Diagrams

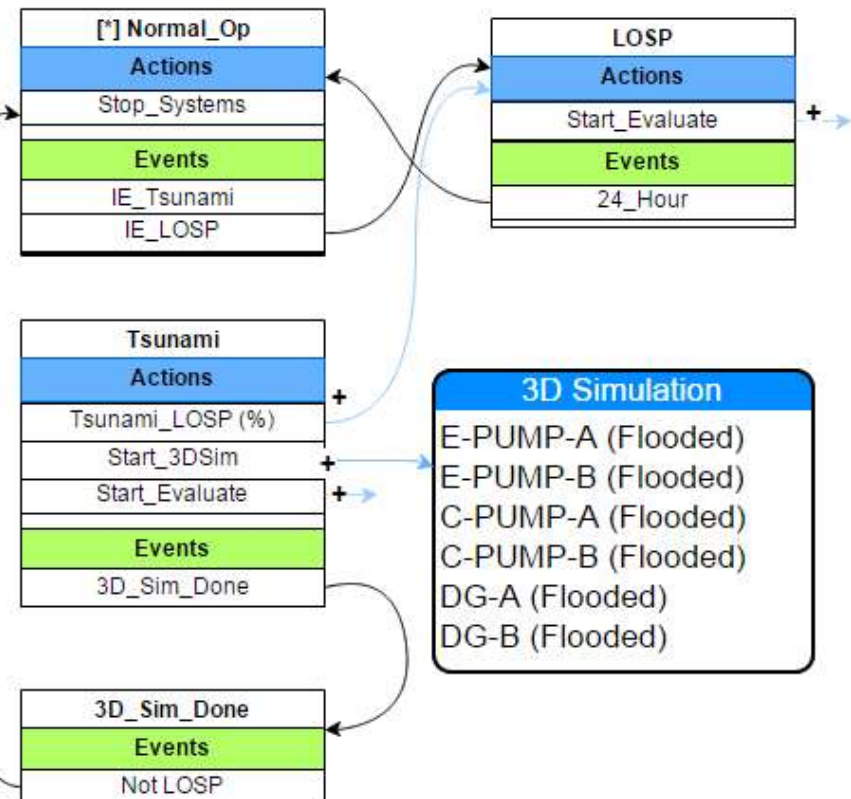
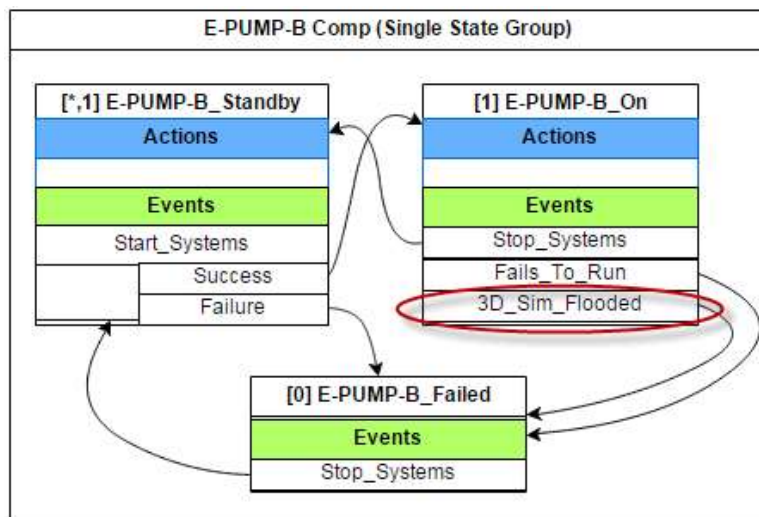
Plant Response

- Overall Operation
- Key States
- Mission Time
- Termination



Incorporating Other Simulations

- One or Two way coupling
- Modify external simulation through actions
- Monitor external changes through events

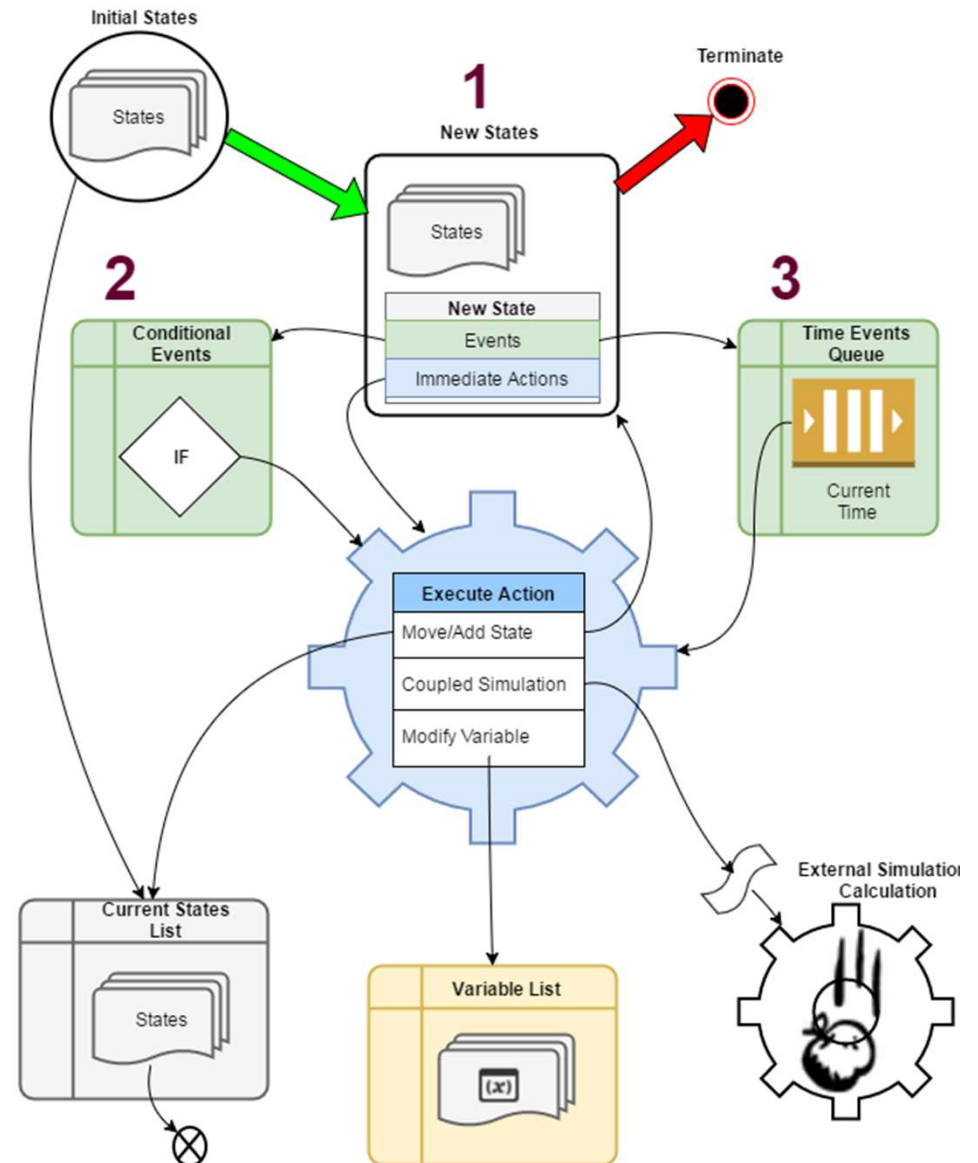


EMERALD Simulation

Based on a three-phased discrete event simulation.

To begin, add initial start states to Current and New States List.

1. While there are States in the New States list, For each State :
 - Add the Events to the Time Queue or Conditional List.
 - Execute any Immediate Actions
2. If any Conditional Events criteria is met.
 - Execute that events action/s.
 - (Go to Step 1)
3. Jump to the next chronological event.
 - Process that event's actions.
 - (Go to Step 1)

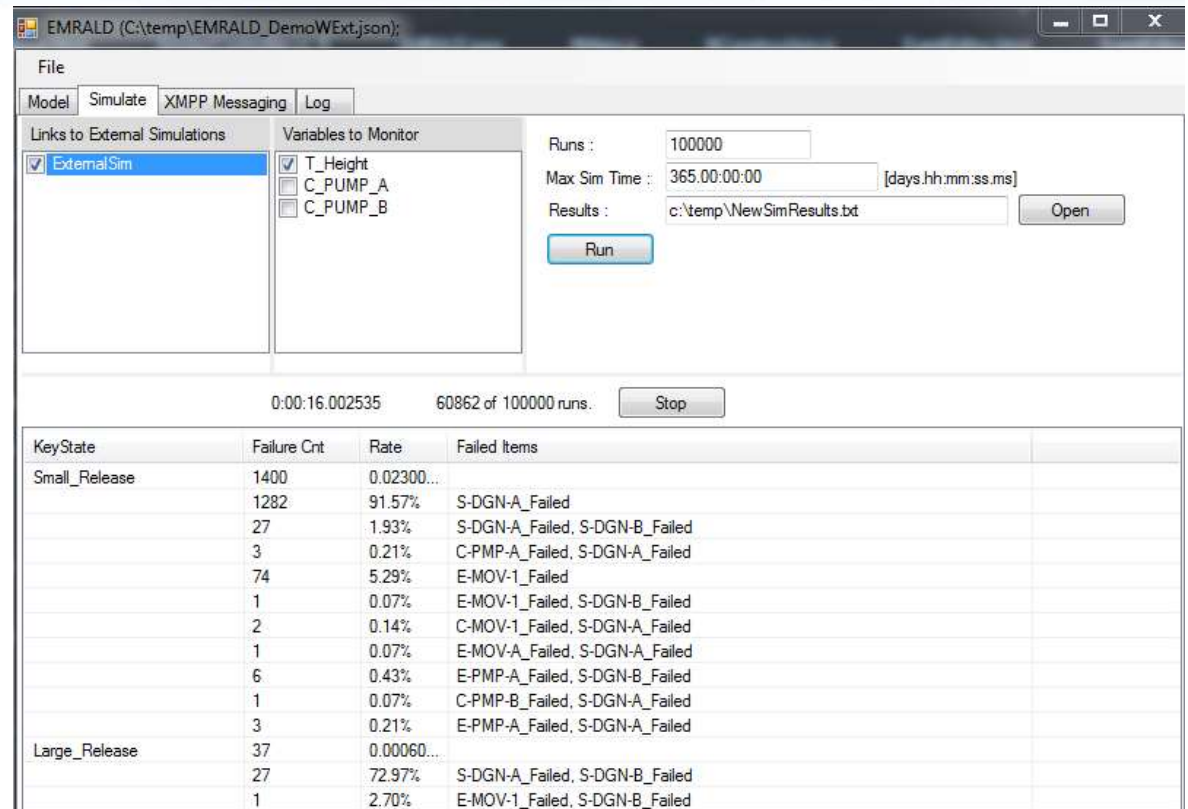


EMERALD Solve Engine & Results

Features

- Decoupled from modeling UI
- Command line or UI
- Monitor progress
- Monitor coupled communication

Results include timing and events for component failures.



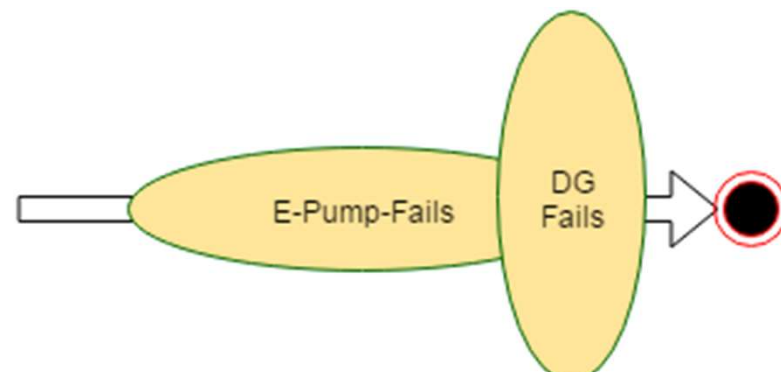
The screenshot shows the EMERALD software interface with the following settings:

- File: EMERALD (C:\temp\EMERALD_DemoWExt.json)
- Model: Simulate
- Links to External Simulations: ExternalSim (checked)
- Variables to Monitor: T_Height (checked), C_PUMP_A (unchecked), C_PUMP_B (unchecked)
- Runs: 100000
- Max Sim Time: 365.00:00:00 [days.hh:mm:ss.ms]
- Results: c:\temp\NewSimResults.txt
- Buttons: Run, Open, Stop

The results table below shows the following data:

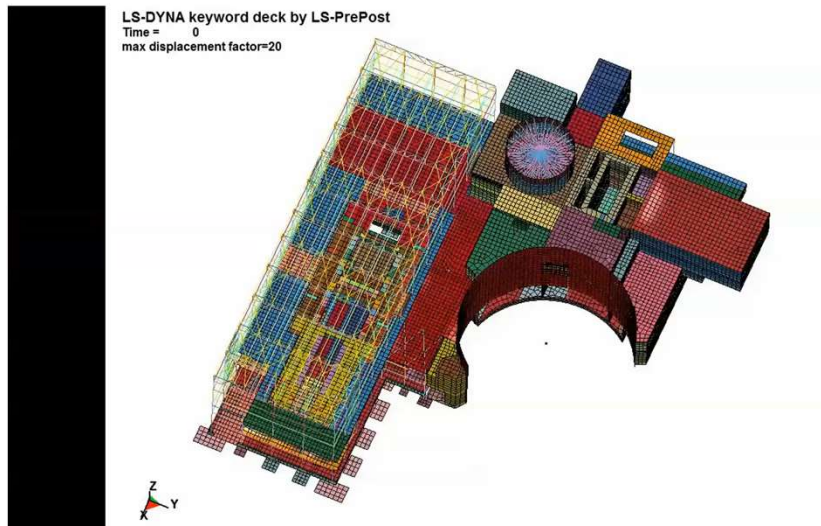
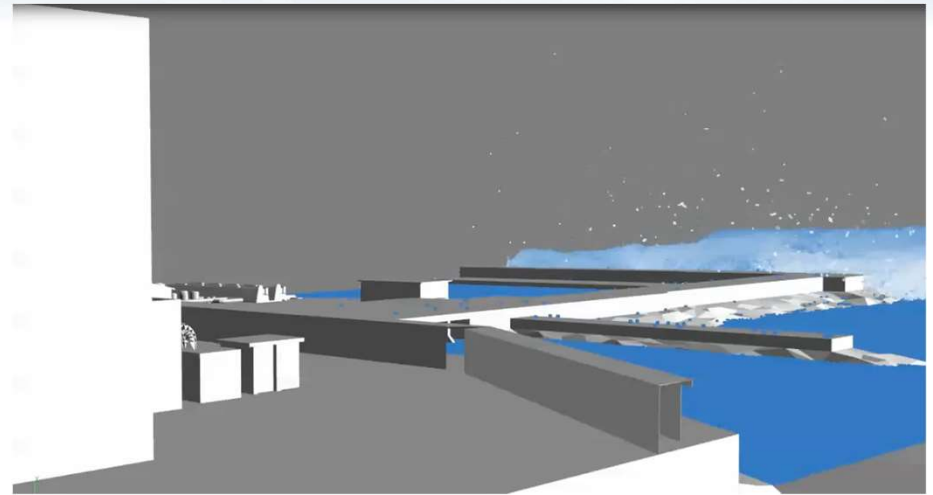
KeyState	Failure Crit	Rate	Failed Items
Small_Release	1400	0.02300...	
	1282	91.57%	S-DGN-A_Failed
	27	1.93%	S-DGN-A_Failed, S-DGN-B_Failed
	3	0.21%	C-PMP-A_Failed, S-DGN-A_Failed
	74	5.29%	E-MOV-1_Failed
	1	0.07%	E-MOV-1_Failed, S-DGN-B_Failed
	2	0.14%	C-MOV-1_Failed, S-DGN-A_Failed
	1	0.07%	E-MOV-A_Failed, S-DGN-A_Failed
	6	0.43%	E-PMP-A_Failed, S-DGN-B_Failed
	1	0.07%	C-PMP-B_Failed, S-DGN-A_Failed
Large_Release	3	0.21%	E-PMP-A_Failed, S-DGN-A_Failed
	37	0.00060...	
	27	72.97%	S-DGN-A_Failed, S-DGN-B_Failed
	1	2.70%	E-MOV-1_Failed, S-DGN-B_Failed

Need to develop visualization for clustering failure contributors.



Current Applications

1. External flooding
2. Multi hazard evaluation (seismic, internal flooding, thermal hydraulics)
3. Operator procedures with fire simulation (preliminary work)



TCF Task - Coupling Protocol

Platform – XMPP (originally Jabber)

- Message-oriented middleware based on XML
- Near real-time
- Cross-Platform, Cross-Network
- Numerous language packages
- Open source



Message Protocol

- JSON - JavaScript Object Notation
- Open & expandable
- Schema validation

Status

- Example packages
- Beta ready

```
{
  "dispName": "SetFlow",
  "version": "0.1.0",
  "pID": "f028d34e-2111-4857-a911-11d83f8e343f",
  "msgType": "mtSimAction",
  "globalRunTime": "00:00:00",
  "desc": "Adjusting the Flow",
  "simAction": {
    "itemData": {
      "nameId": "Flow",
      "value": "300"
    }
  },
  "actType": "atCompModify",
  "time": "01:05:00"
}
```

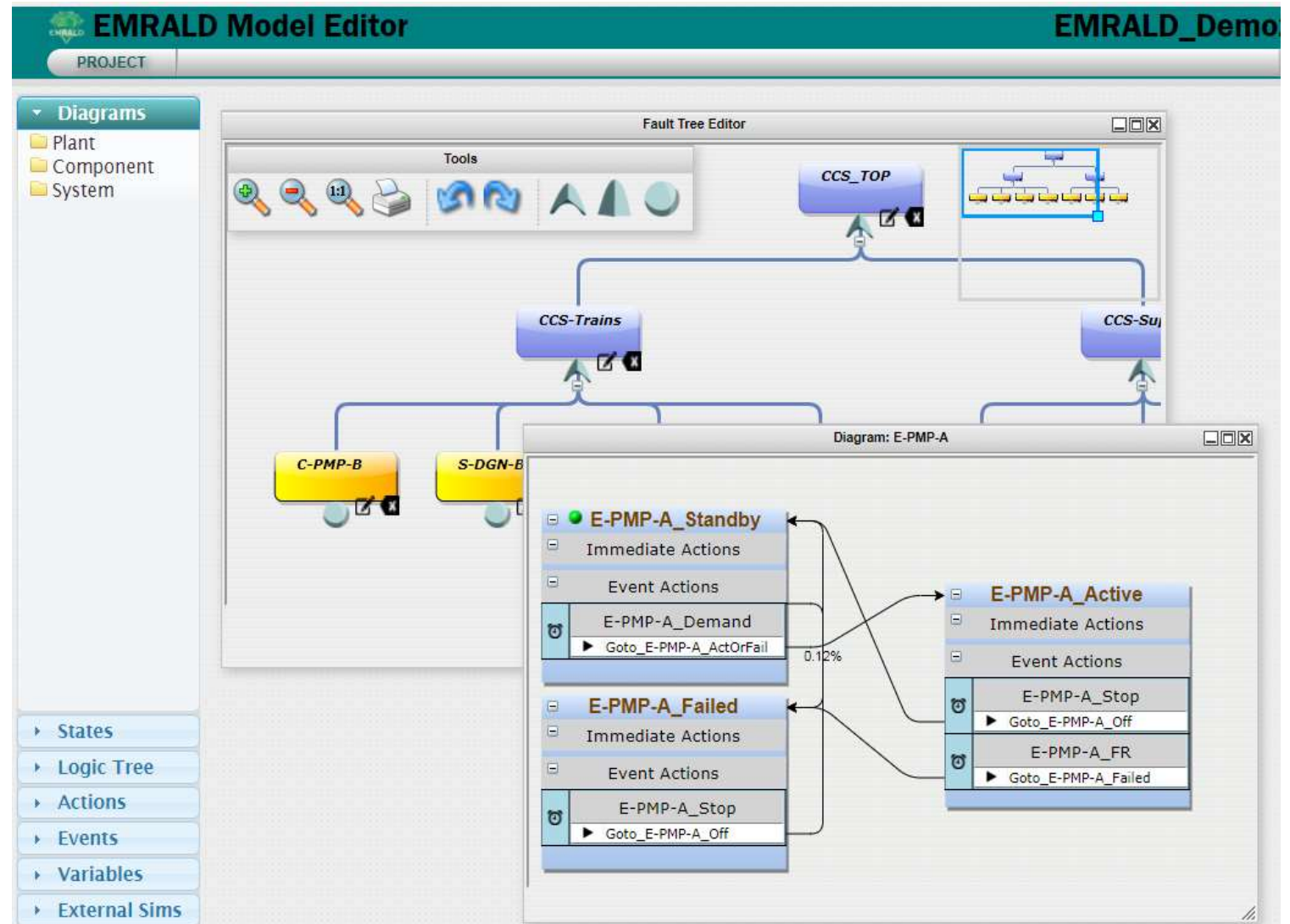
TCF Task - User Interface

Interface

- Web based
- Open Source Packages
- Customizable

Status

- ~80%



Current Commercialization Work

Small Business Innovation Research (SBIR)

- 3 requests

Grid Reliability

- Investigating a combined proposal with University of Idaho, Siemens.
- Funding Opportunity Announcement (FOA)



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Coupling features

- XMPP cross platform, open JSON protocol
- Time Step simulations
- Other discrete event simulations
- Formula Solvers
- Static Input Deck

Input Deck	
Event	Time
Power Failure	3:36.40
Battery Exhausted	4:50.22
...	

