

Transient Recognition Control for Fuel Cell Systems

Steven R. Shaw – MSU Bozeman

SECA CTP Review Meeting
October 25, 2005





Transient Recognition Control Outline

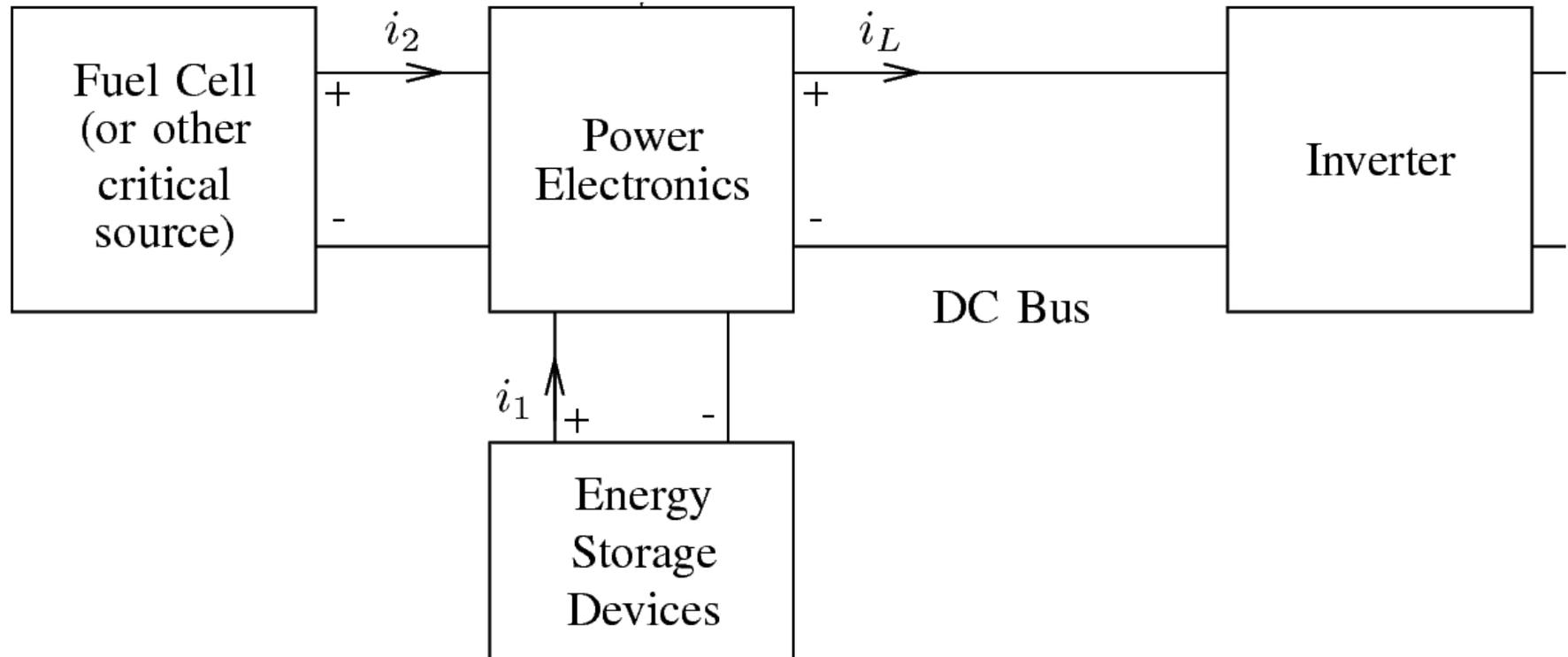


- What's the problem?
- Transient recognition control
- Sequential cluster-weighted modeling
- Simulation results
- FPGA implementation
- FPGA results
- Power electronics
- Future directions



Transient Recognition Control

Multi-source systems

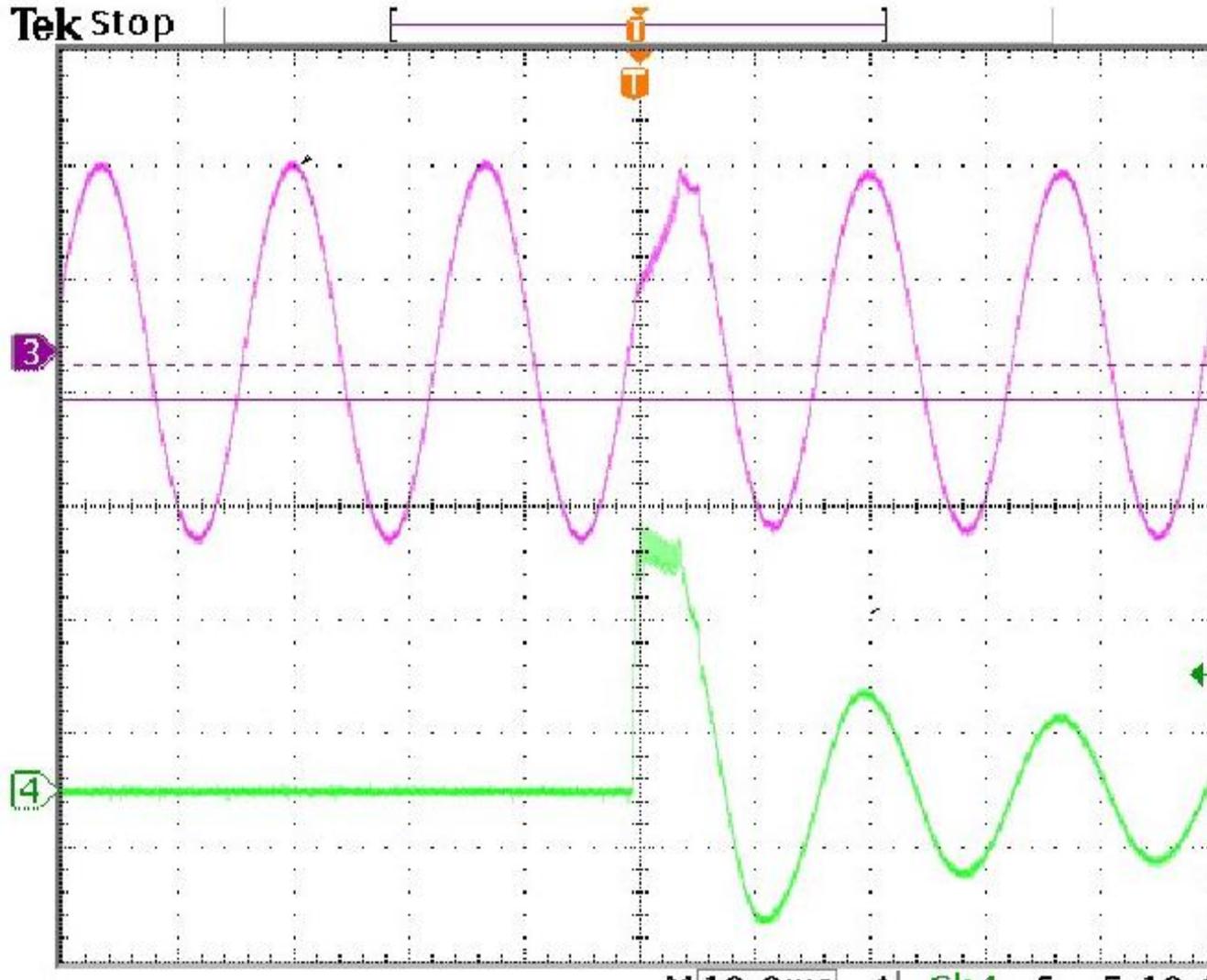


Allocation of power from different sources should be a *control* decision



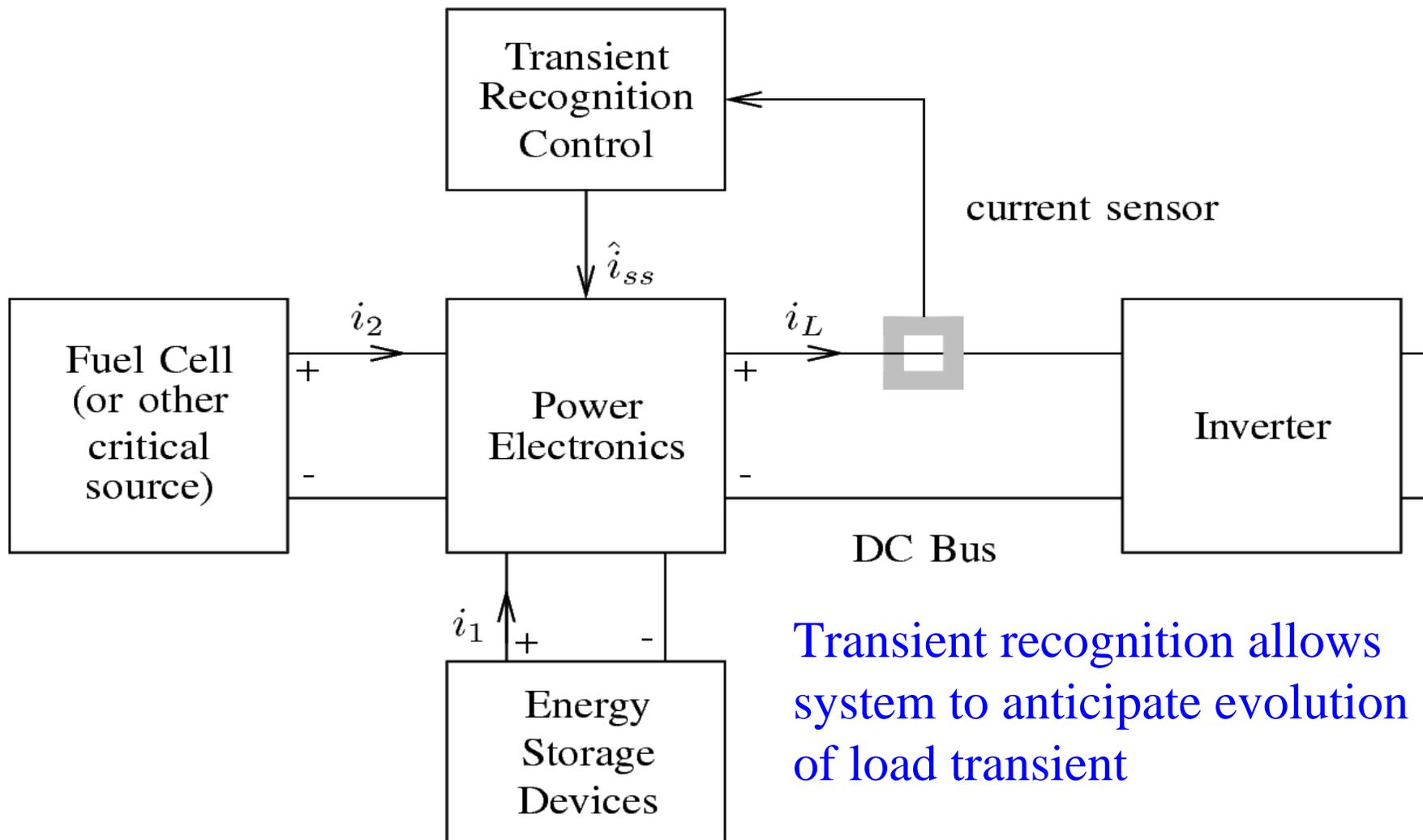
Transient Recognition Control

The load following problem



- Transients typically impulsive
- Transient excitation may degrade FC
- Transient distortion may cause load/FC interaction

Conventional controls are a compromise solution



Transient recognition allows system to anticipate evolution of load transient



Transient Recognition Control

Sequential Cluster Weighted Modeling (SCWM)



$$\langle \hat{y} | \vec{x}_n \rangle = \frac{\sum_{m=1}^M f(\vec{q}_m, \vec{\beta}_m) p(\vec{x}_n^{(1:K)} | c_m) P(c_m)}{\sum_{m=1}^M p(\vec{x}_n^{(1:K)} | c_m) P(c_m)}$$

$$\vec{q}_m = \left(\vec{x}_n^{(1:K)T} \quad \vec{\mu}_m^{(K+1:D)T} \right)^T$$

Prediction is sequential, probabilistic interpolation of local models



Transient Recognition Control

Sequential Cluster Weighted Modeling (SCWM)



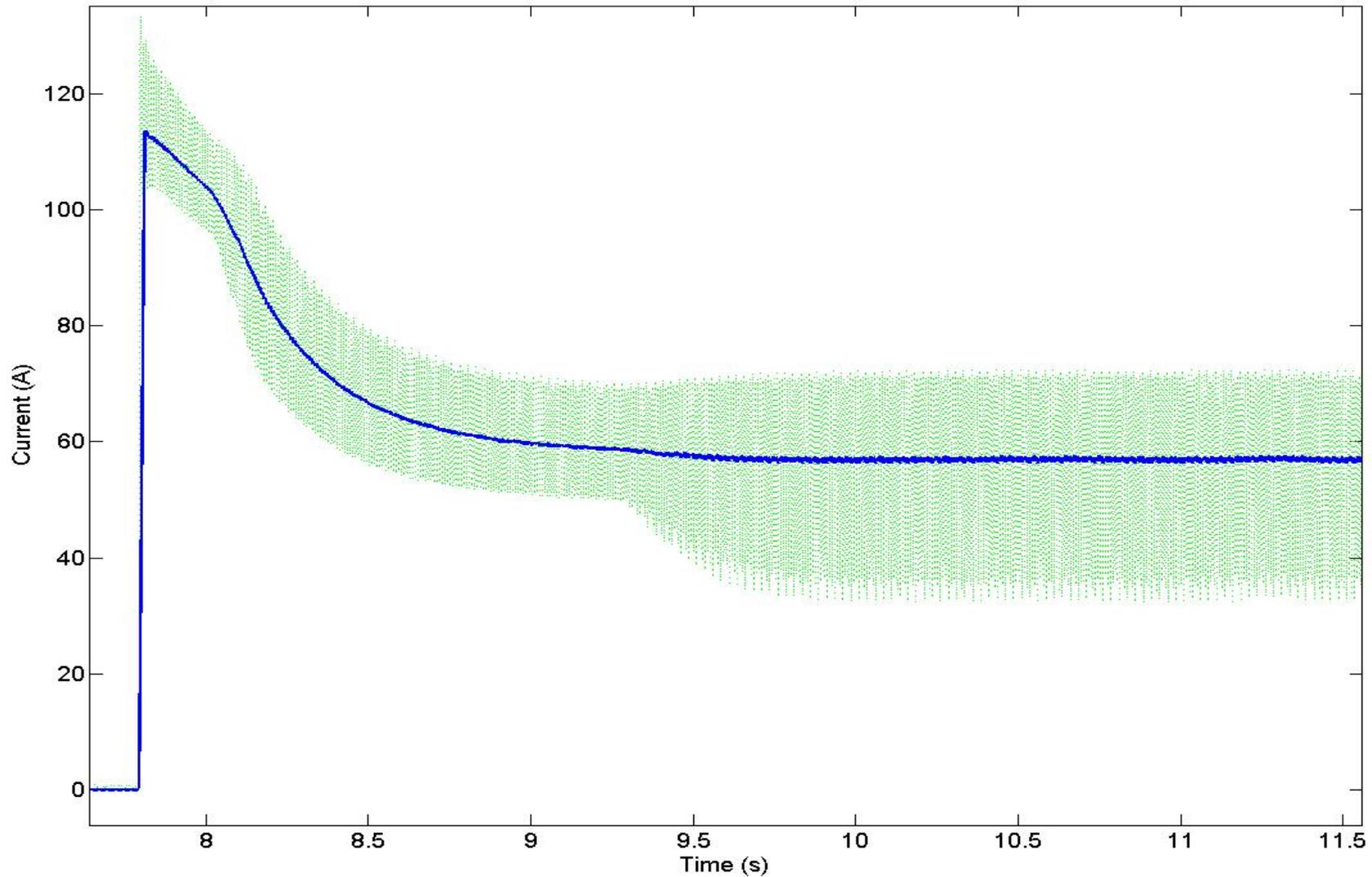
$$f(\vec{x}_n, \vec{\beta}_m) = \vec{\beta}_m^T \cdot \vec{x}_n = \sum_{d=1}^D \beta_{m,d} \cdot x_{n,d}$$

$$p(\vec{x}_n | c_m) = \prod_{d=1}^D \frac{1}{\sqrt{2\pi\sigma_{m,d}^2}} \exp \left[\frac{-(x_{n,d} - \mu_{m,d})^2}{2\sigma_{m,d}^2} \right]$$

Update allows SCWM to adapt



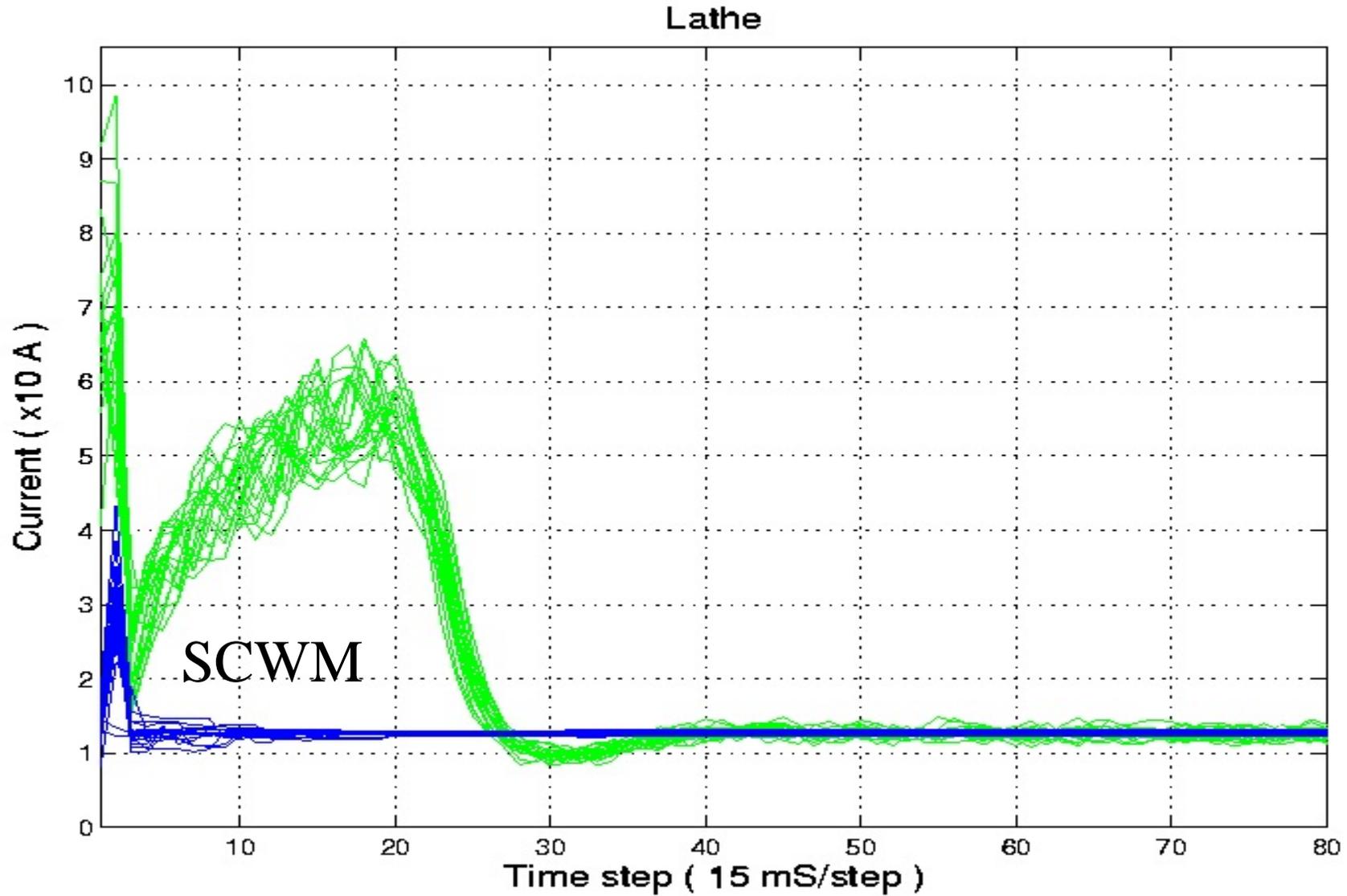
Transient Recognition Control Filtering inverter ripple



Pre-filtering eliminates inverter ripple



Transient Recognition Control SCWM Lathe Transient Prediction

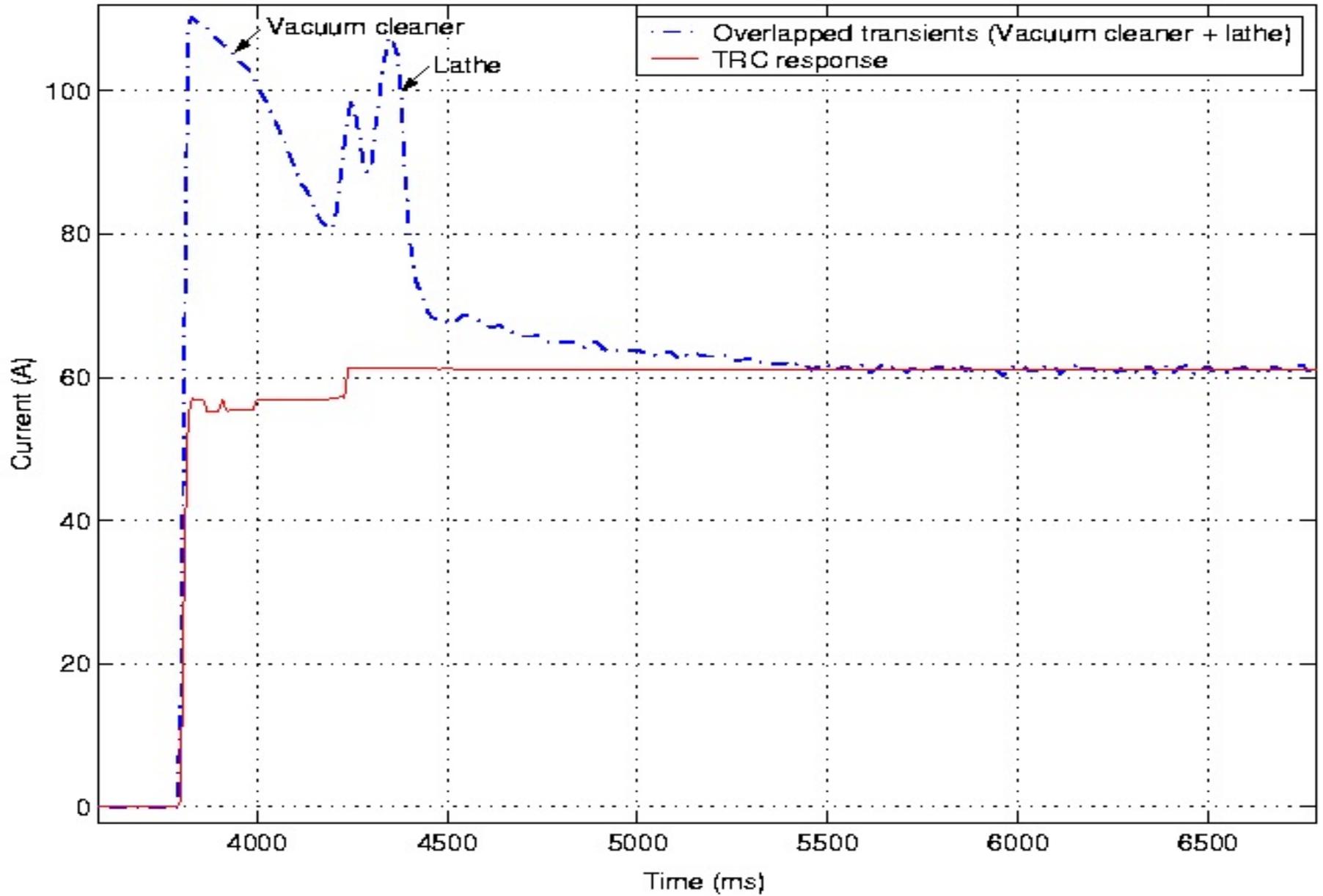


Physically similar load transients differ by scale factors



Transient Recognition Control

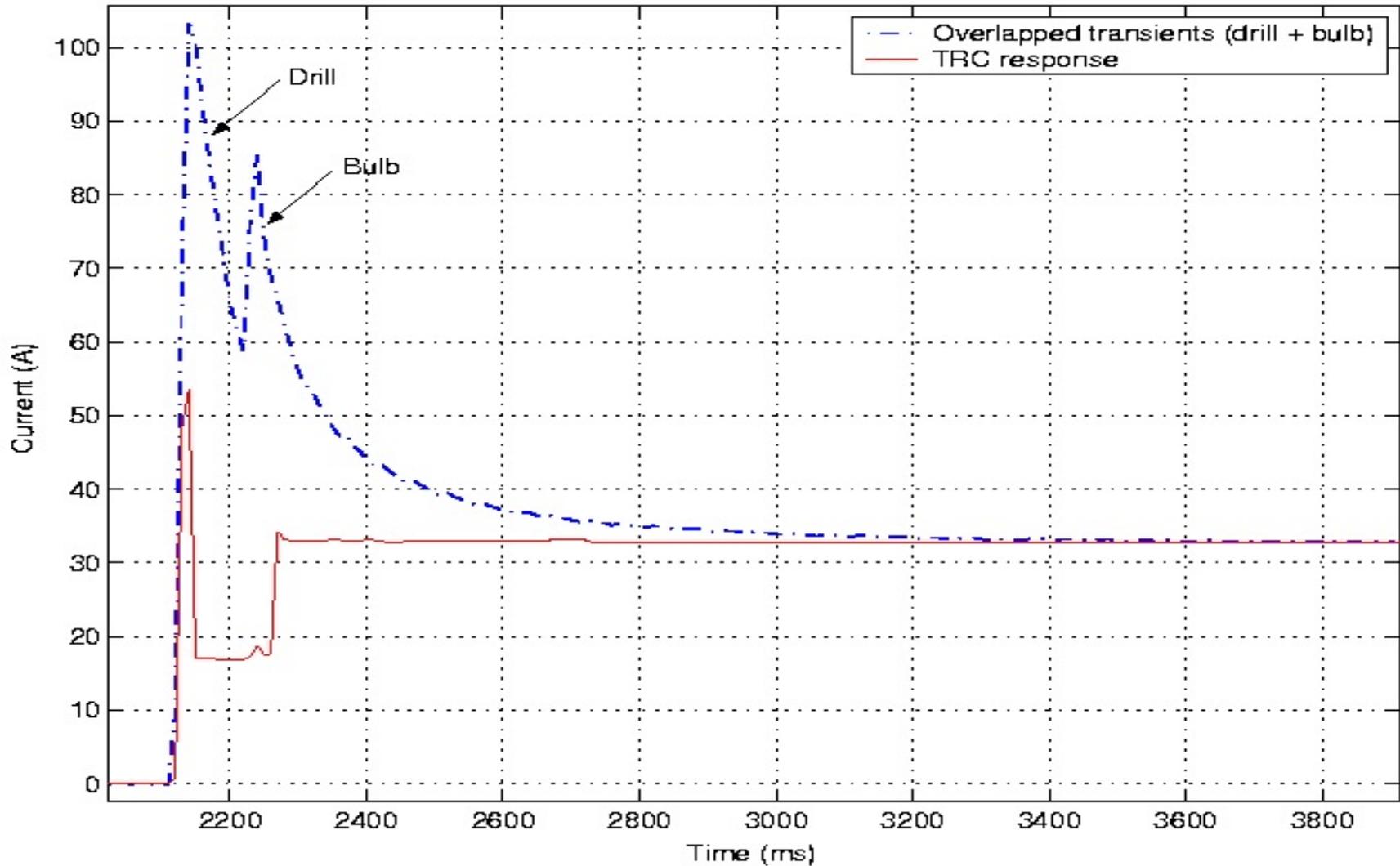
Transient overlap resolution





Transient Recognition Control

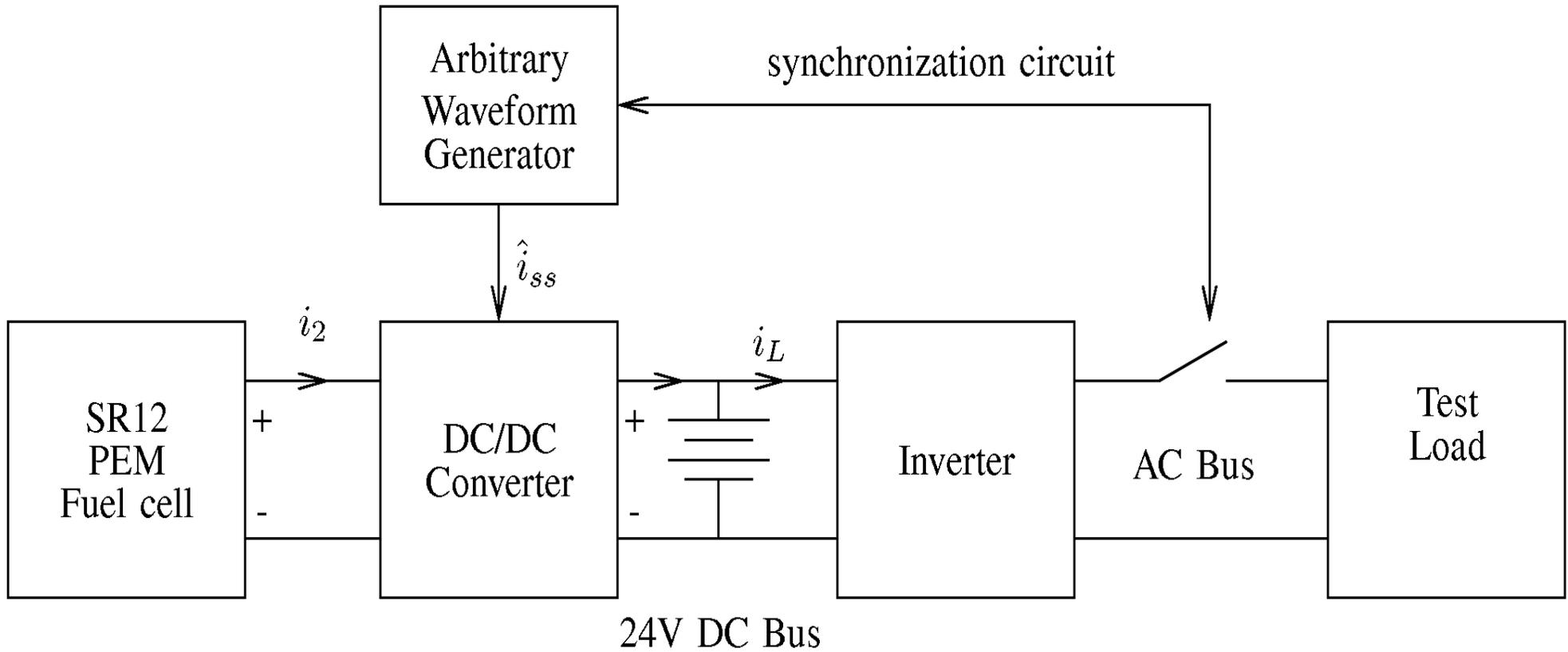
Transient overlap resolution



SCWM likelihood calculation helps resolve overlap



Transient Recognition Control Test setup

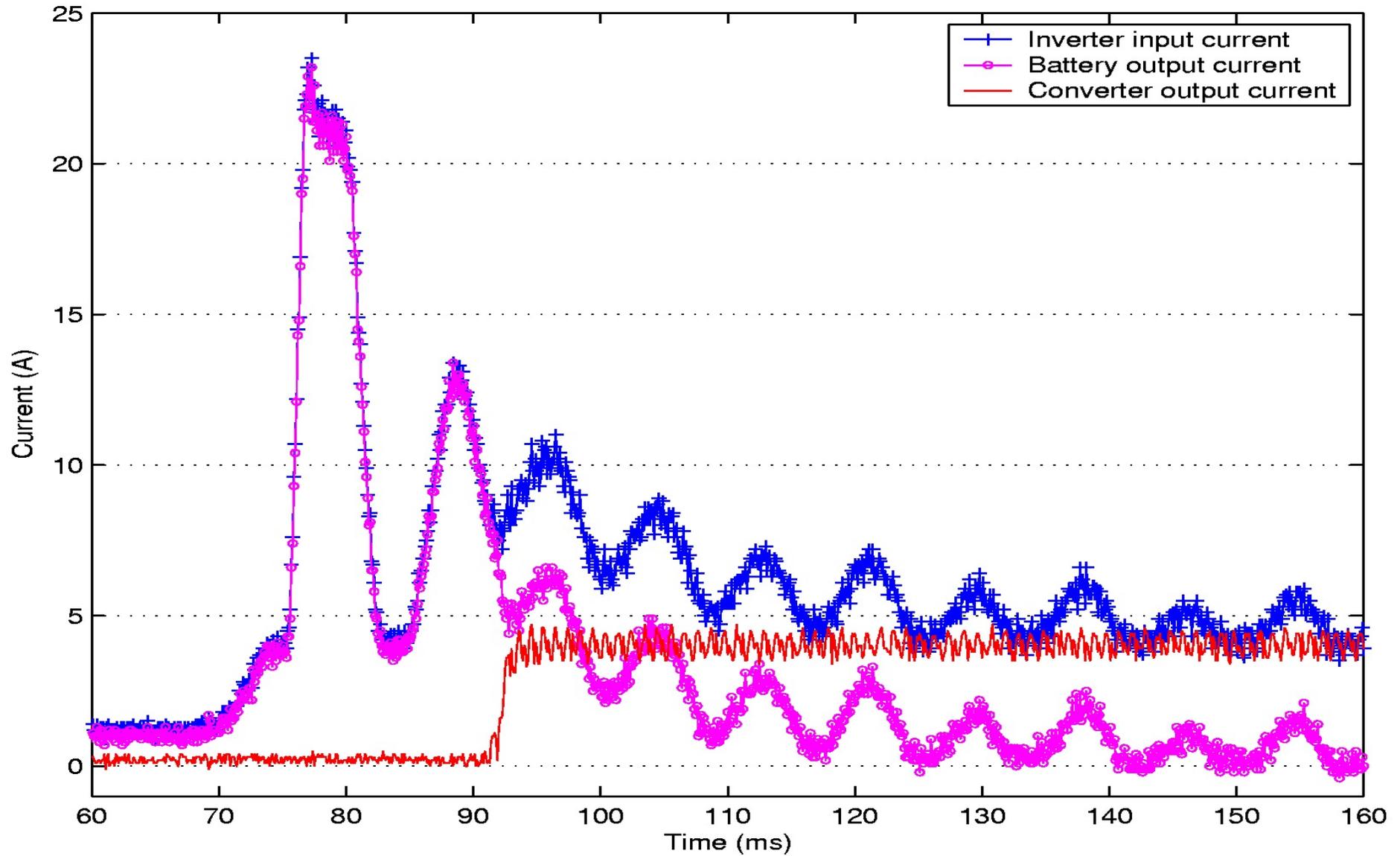


SCWM responses precomputed and stored in AWG



Transient Recognition Control

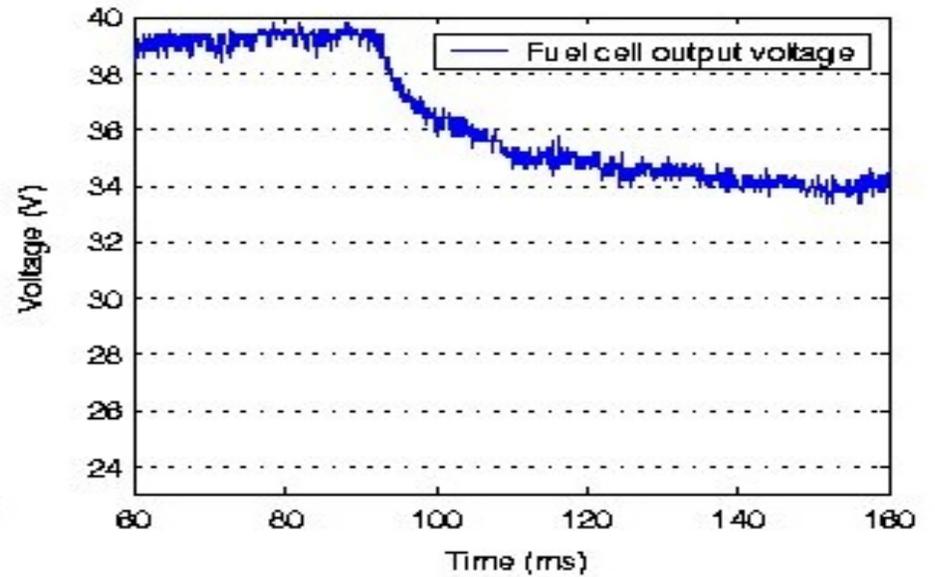
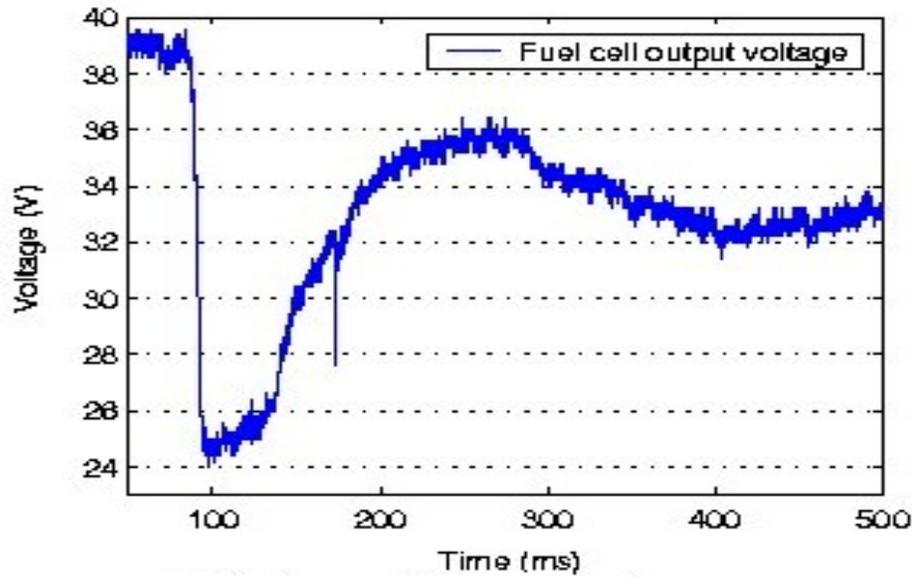
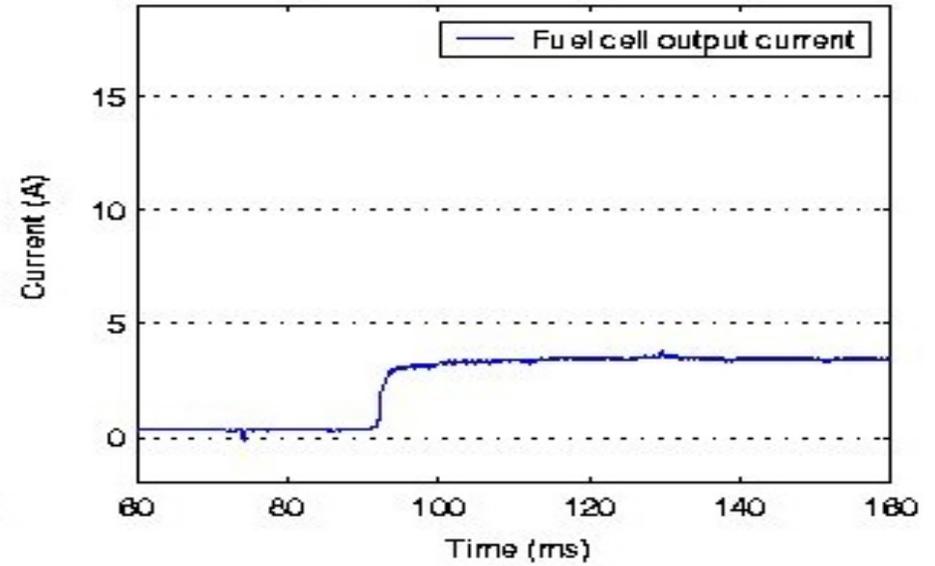
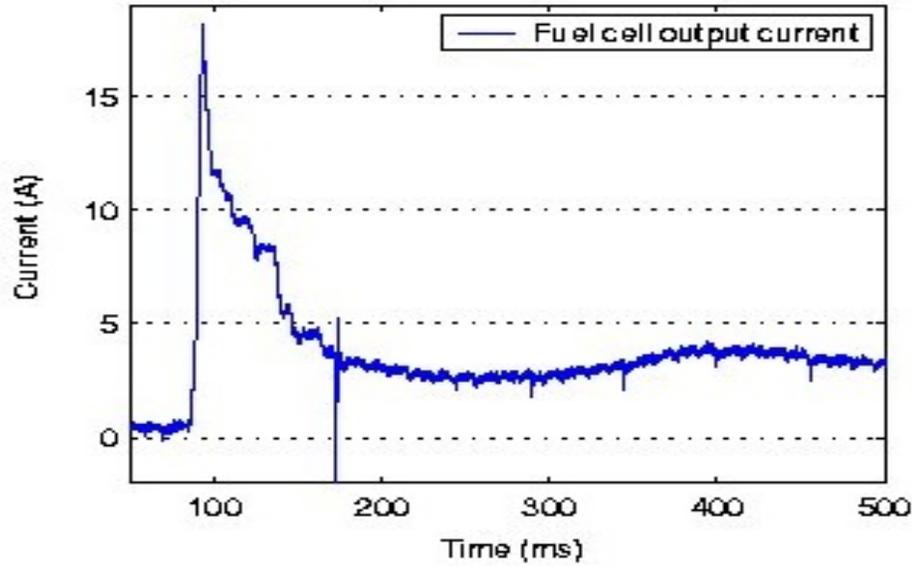
DC-link currents





Transient Recognition Control

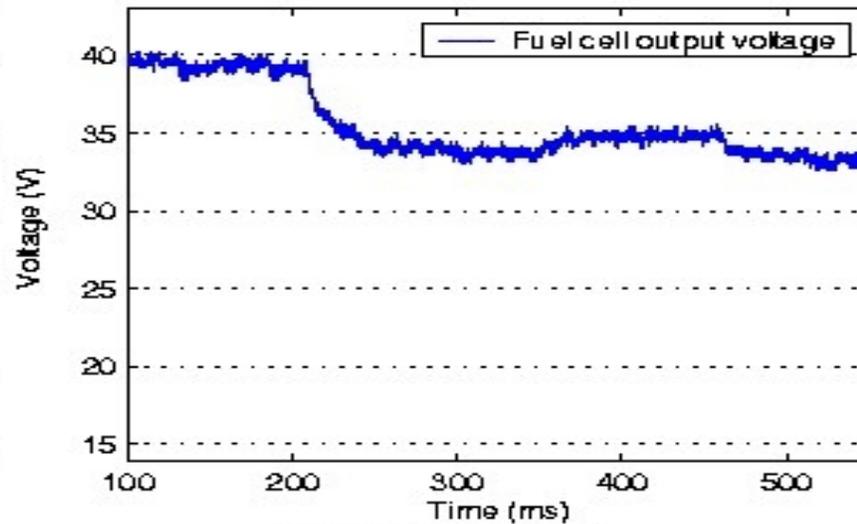
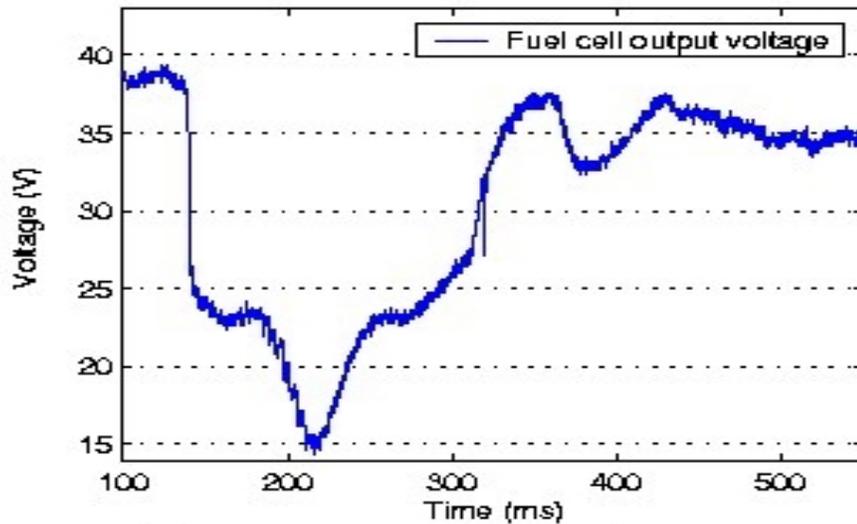
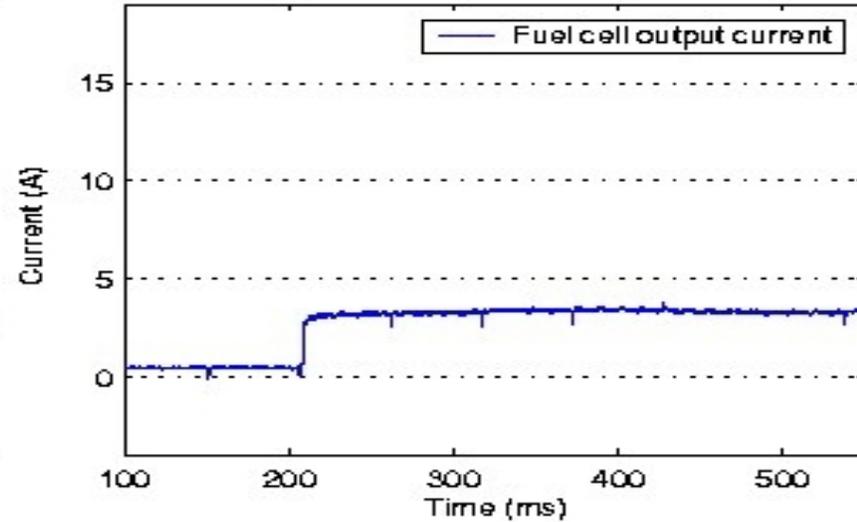
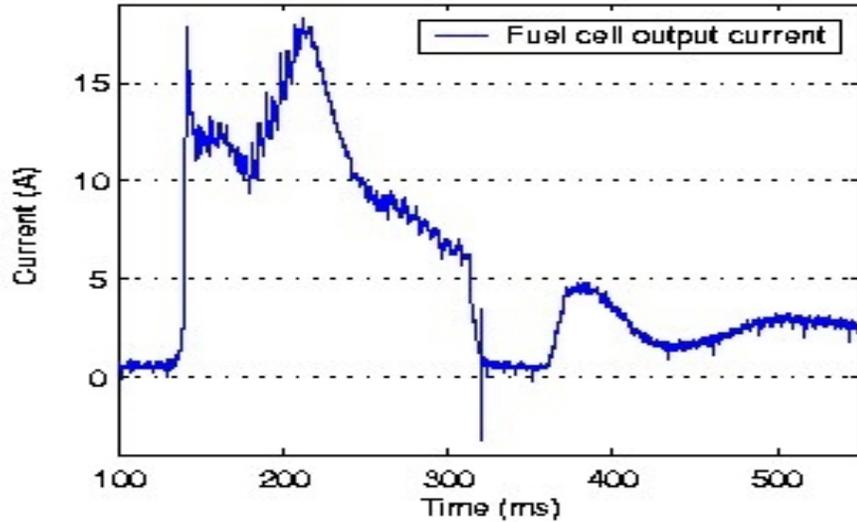
Transient impact at fuel cell terminals





Transient Recognition Control

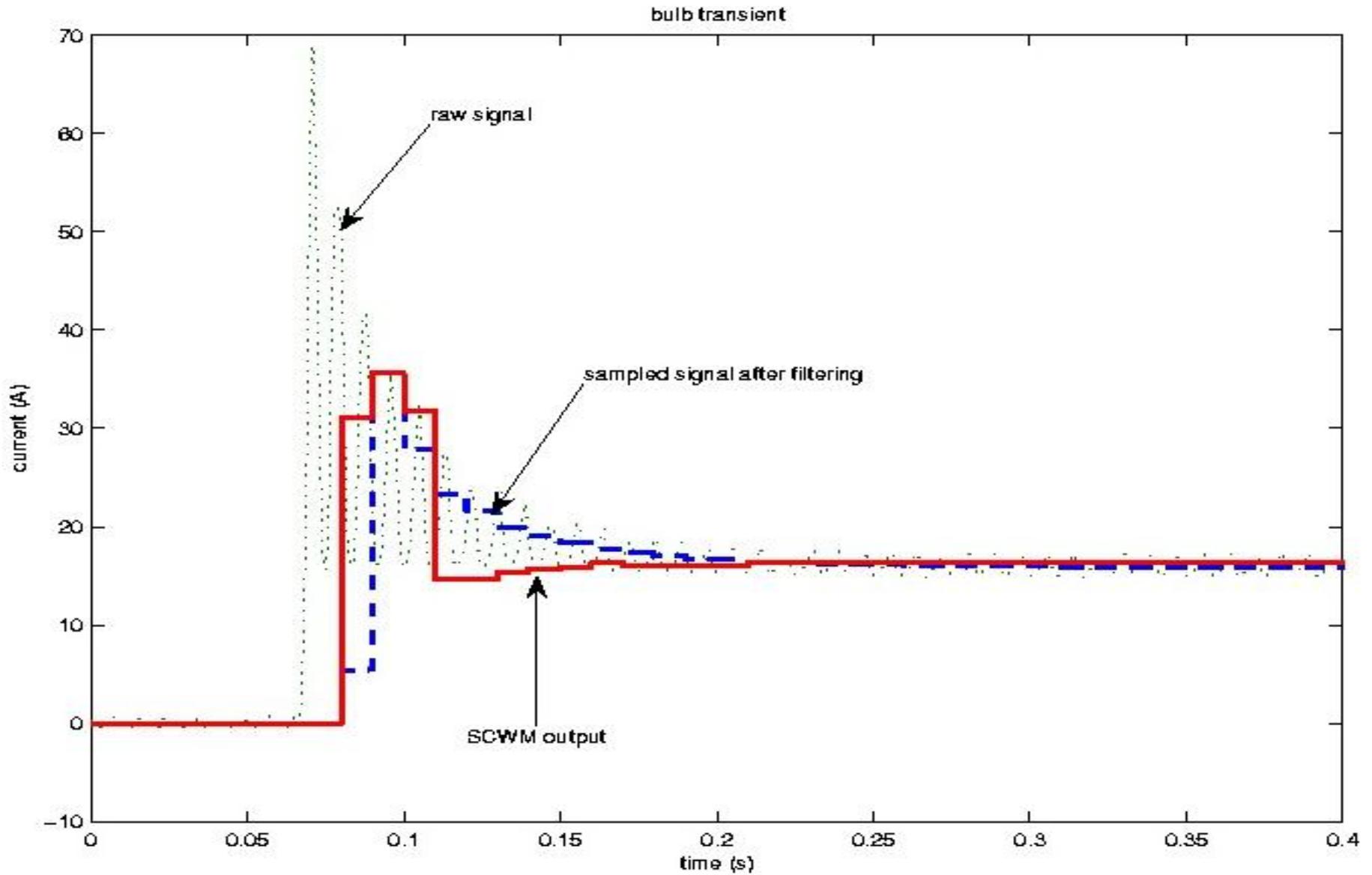
Transient impact at fuel cell terminals



TRC mitigates transient effect at fuelcell terminals

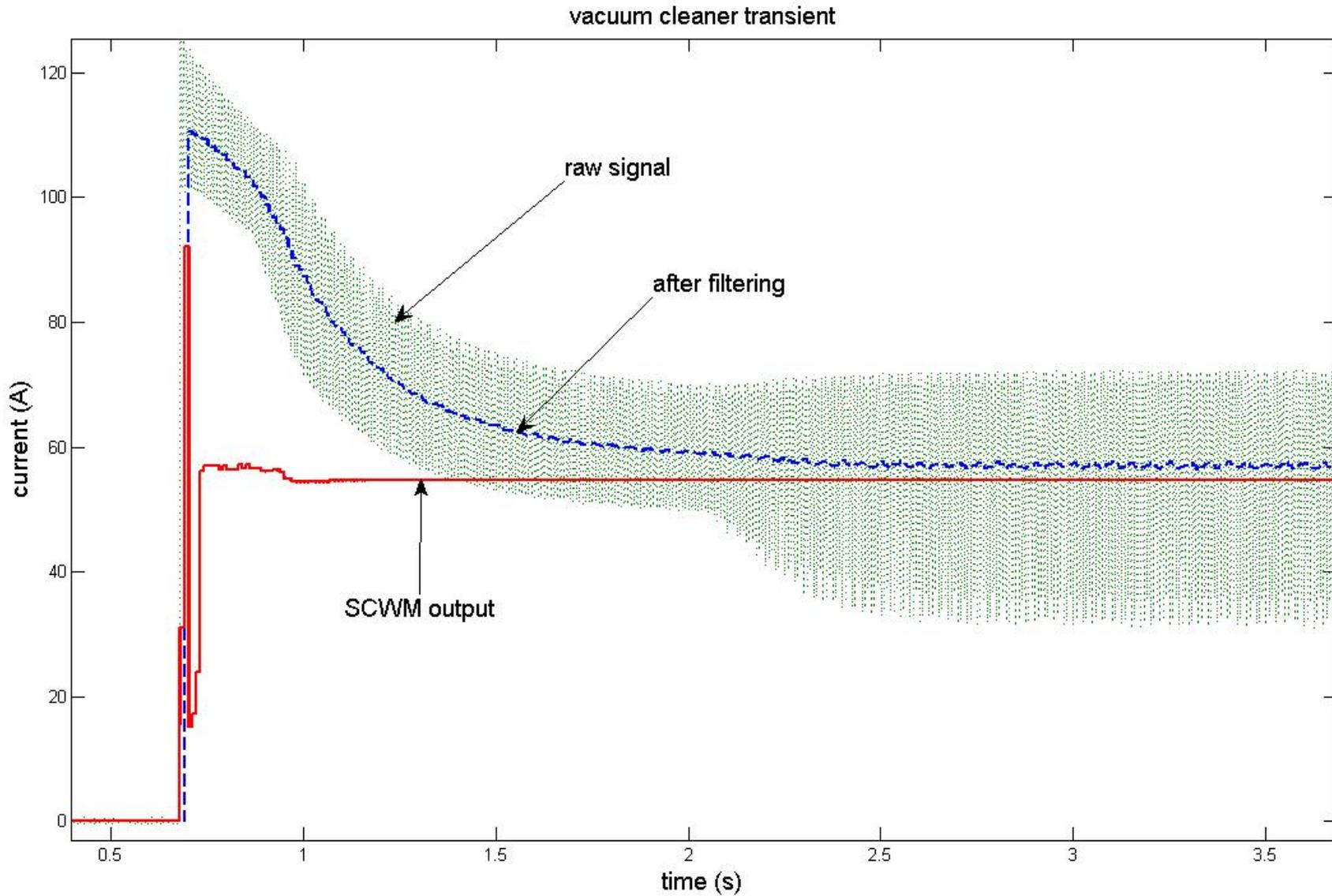


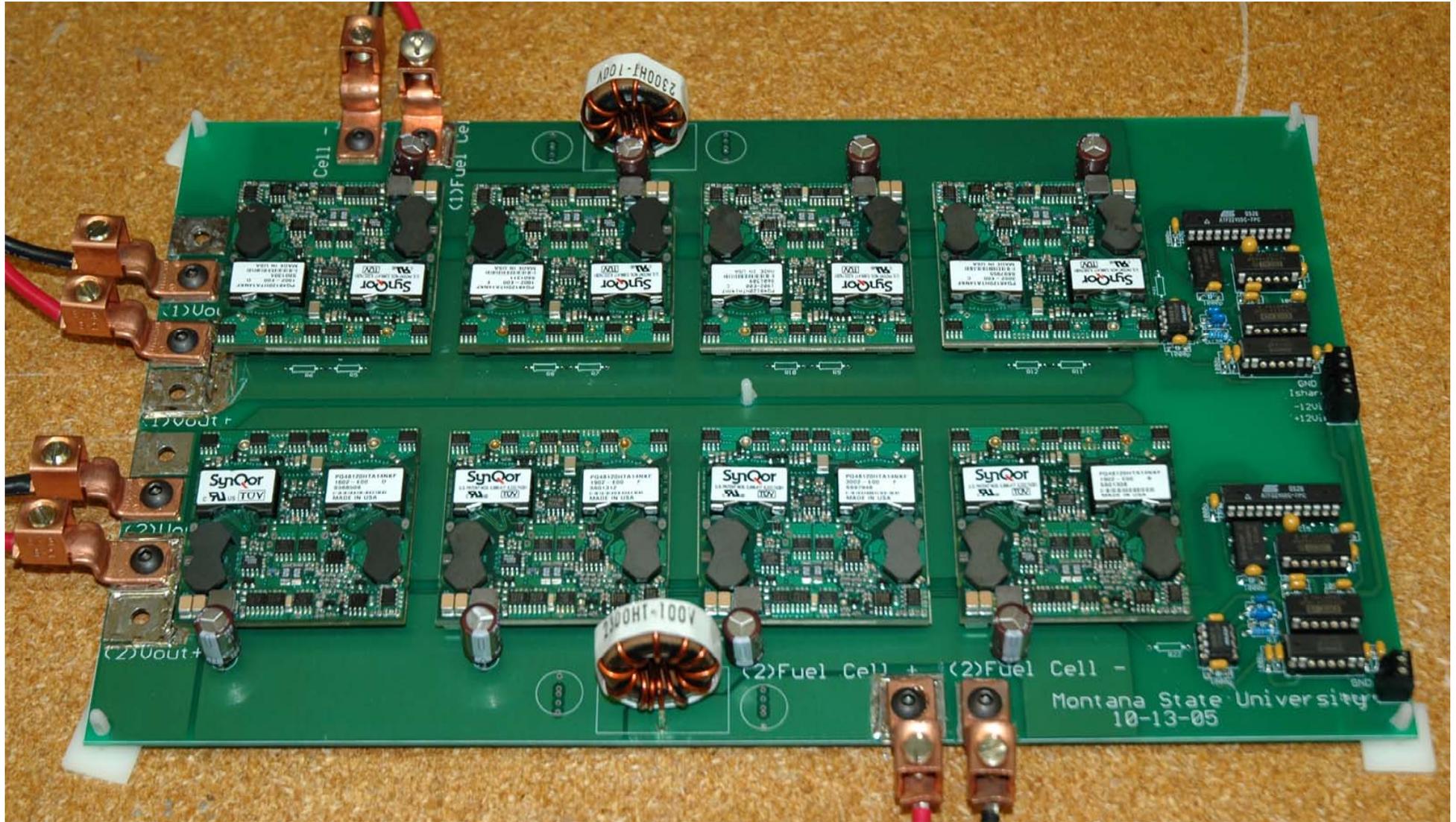
Transient Recognition Control Virtex-II Hardware Co-simulation



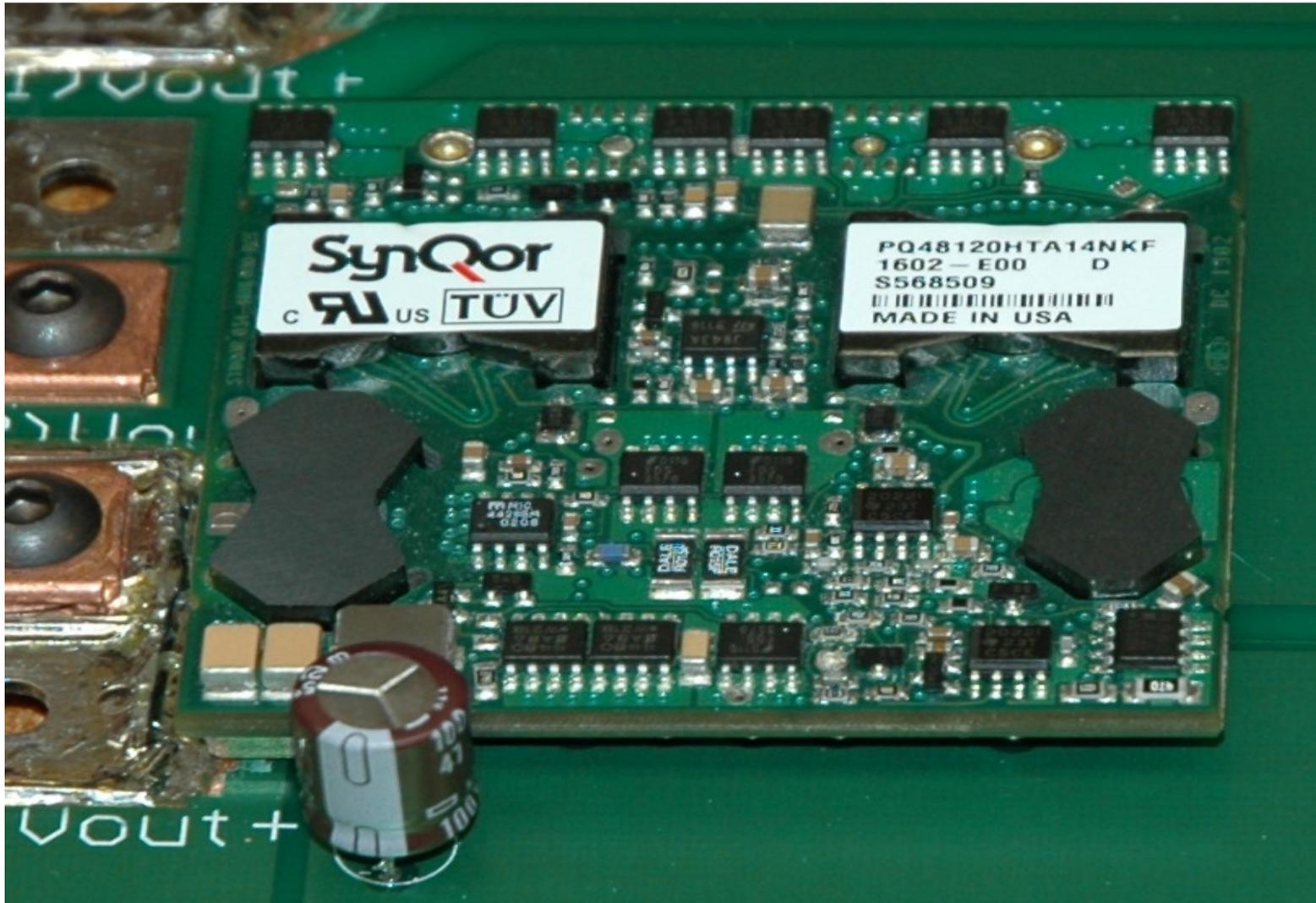


Transient Recognition Control Virtex-II Hardware Co-simulation





Current sharing control integrates with TRC.

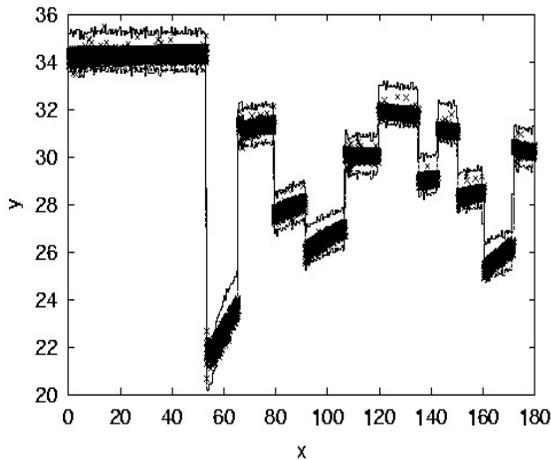
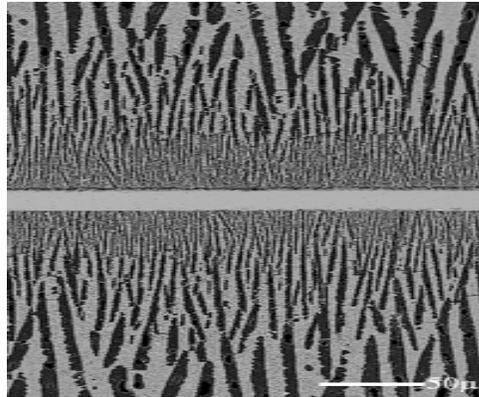


500W in a half-brick, no heat sink



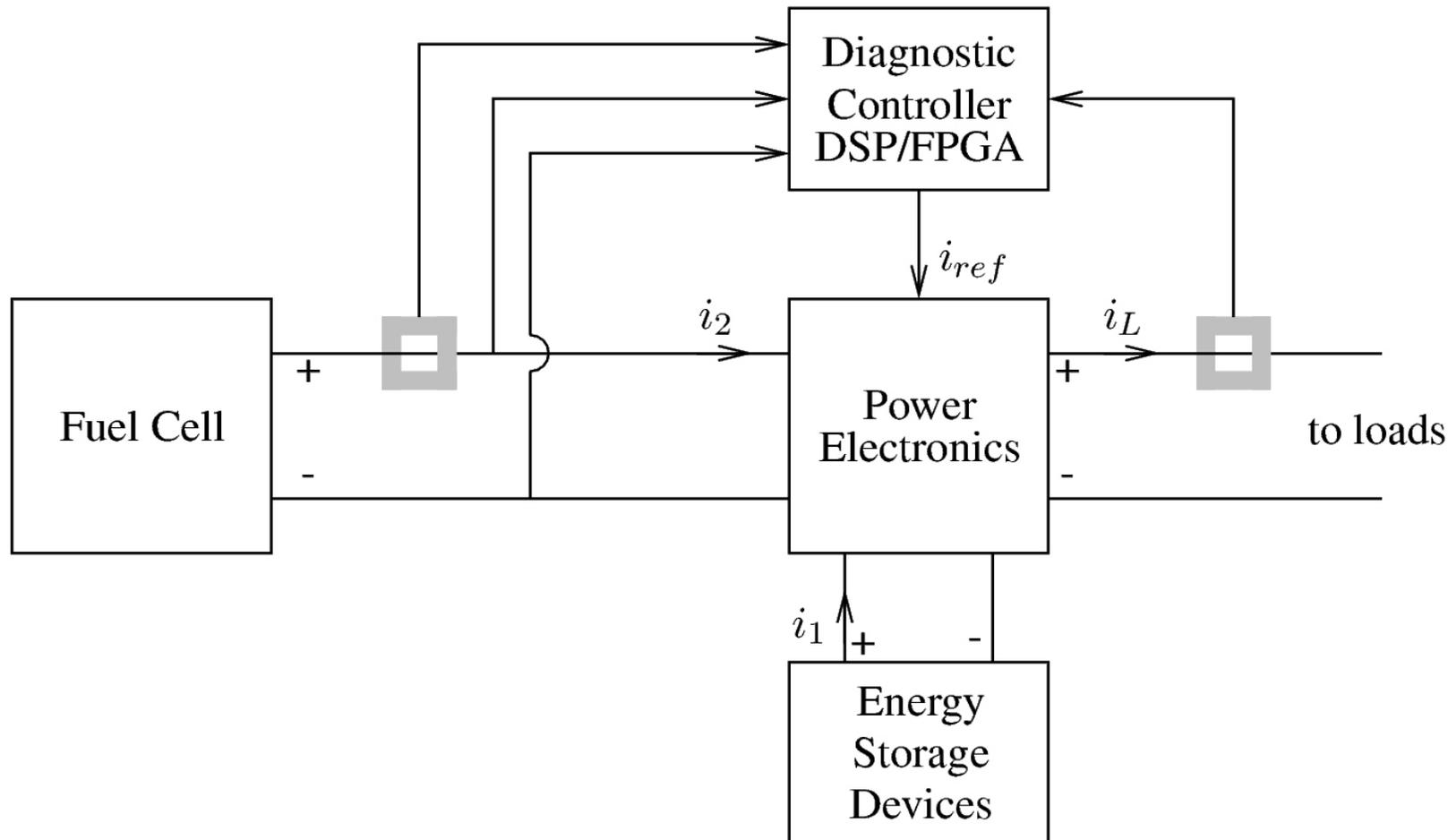
Transient Recognition Control - new directions

Full-stack simulator



50V, 75A
3500 W
4-quadrant
> 100 kHz

Accelerated test platform for full-scale electronics and controls



Continuously diagnose fuel cell and adapt control response



Transient Recognition Control

Closing thoughts



- TRC can mitigate transient effects at FC terminals
- SCWM is a useful model for implementing TRC
- TRC is feasible using FPGA techniques
- Simplified TRC?

Can appropriate controls ease materials/BOP problems?



Transient Recognition Control Acknowledgements



Tao Zhu
Brandon Inberg

Lee Spangler
Jen Nichols

Larry Pederson
Gary McVay
Mark Williams

M. Hashem Nehrir