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## MFIX-DEM Phi: Performance and Capability Improvements Towards Industrial Grade Open-source DEM Framework with Integrated Uncertainty Quantification

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□ Team members

□ Potential Significance of The Results of The Work

Physical Modeling Enhancements

**D** Results and Discussion

□ Acknowledgements



#### **MFIX-DEM Phi team: ASU campus**



#### **Co-PI: Heather Emady**

- PhD, Purdue U. 2012
- Assistant Professor, School of Engineering, Materials, Transport and Energy (SEMTE), ASU.
- Expertise: particulate processes and product design
- Award: Bisgrove Scholar, 2015



PI: Aytekin Gel

- PhD, West Virginia U. 1999; MBA, ASU, 2007.
- Professor of Practice, School of Computing, Informatics, Decision Systems Engineering (SCIDSE), ASU
- Expertise: HPC, CFD, UQ, multiphase reactive flow, Six Sigma for Quality
- 16 years of startup company experience; Involved with MFIX since 1999
- Award: Team Member of R&D 100, 2007



#### **Co-PI: Yang Jiao**

- PhD, Princeton U. 2010
- Assistant Professor, School of Engineering, Materials, Transport and Energy (SEMTE), ASU.
- Expertise: computational materials
- Award: DARPA Young Faculty, 2014



**GRA: Manogna Adepu** • PhD candidate, SEMTE.

• Focus: Validations



GRA: Shaohua Chen

• PhD candidate, SEMTE.



• Focus: Computation

#### **MFIX-DEM Phi Team**

#### Member at Lawrence Livermore National Laboratory (LLNL)



#### **Co-PI: Charles Tong**

- Research Scientist
- Expertise: uncertainty quantification
- Developer of open-source UQ toolbox PSUADE and CCSI Toolkit UQ framework FOQUS

#### Members at Sandia National Laboratory (SNL)



#### **Co-PI: Jonathan Hu**

- Principal Member of the Technical Staff at Sandia National Laboratories
- Expertise: highly scalable linear equation solver, developer of Trilinos Project (ML, nextgen ML: MueLu)
- Award: R&D 100 (Trilinos)



#### Nathan Ellingwood

- Research Staff at Sandia National Laboratories
- Ph.D. in Applied Math & and Computational Sciences, University of Iowa (2014)
- Expertise: Data parallel algorithms for GPU, FEM, CFD, HPC, Digital Lung Project







## **Physical Modeling Enhancement**



# **Hopper with mass inflow BC**









Testing polydispersity implementation with conduction heat transfer



Testing polydispersity implementation with conduction heat transfer



Granular flow in a rotary drum



Diameter [cm] Diameter [cm] 2.900e-01 2.900e-01 0.255 0.255 0.22 0.22 0.185 0.185 1.500e-01 .500e-01

The particles in the hopper possess a bi-modal particle size distribution, which includes two normal distributions for fine and coarse particles.

Initial configuration of the discharge hopper containing a layered packing of spherical beads with a bi-modal size distribution.

Initial configuration of the hopper discharge containing a well-mixed packing of spherical beads with a bi-modal size distribution.

Source: Chen, S. et. al., Enhancing the Capability for Handling Particle Size Polydispersity of Open-Source CFD-DEM Software : Implementation and Validation. Submitted to Powder Technology. (completed first stage of peer review)



## Validation of Polydispersity Implementation



Sample	mean diameter (m)	max diameter (m)	min diameter (m)	STDV (m)	total mass (g)
Fine	0.0015	0.0017	0.0013	0.0003	580
Coarse	0.0029	0.0031	0.0027	0.0001	420



Coarse particles



Fine particles

Source: Chen, S. et. al., Enhancing the Capability for Handling Particle Size Polydispersity of Open-Source CFD-DEM Software : Implementation and Validation. Submitted to Powder Technology. (completed first stage of peer review)



# Validation of Polydispersity Implementation

### Well-mixed configuration



Snapshots of the discharge simulation of the well-mixed configuration at 6 s, 9 s, 11s and 12 s respectively from left to right. The upper panels show the top view and the lower panels show the side view.

Source: Chen, S. et. al., Enhancing the Capability for Handling Particle Size Polydispersity of Open-Source CFD-DEM Software : Implementation and Validation. Submitted to Powder Technology. (completed first stage of peer review)



# Validation of Polydispersity Implementation

## Layered configuration





Lavered Configuration

Snapshots of the discharge simulation of the layered configuration at 6 s, 9 s, 11 s and 12 s respectively from left to right. The upper panels show the top view and the lower panels show the side view.

Source: Chen, S. et. al., Enhancing the Capability for Handling Particle Size Polydispersity of Open-Source CFD-DEM Software : Implementation and Validation. Submitted to Powder Technology. (completed first stage of peer review) **ASU** 14



#### Wall heat transfer in a rotary drum



Snapshot of wall HT after 2 sec of simulation.

- Conduction, convection, and radiation occur in many multiphase processes. Particle-particle conduction is now commonly used in DEM codes, but more complex heat transfer nodels are necessary to more accurately simulate these processes.
- Current serial version of MFIX-DEM has codes for each of these, but they remain to be tested and validated.
- Whether drying, mixing, granulating, coating or heating, rotary drum systems are among the most common process equipment, offering efficient economical solutions. Thus, a rotary drum was selected for validating heat transfer models.





Source : http://www.muzzio.rutgers.edu/



#### Testing all modes of HT implemented in MFIX-DEM

- Simulations were done to test the implementation of all the three modes of HT.
- The drum was held at a fixed hot temperature of 1000 K and particles are initially placed in the drum with a temperature of 298K.

Simulations demonstrates:

- 1. particle-wall and particle-fluid-wall heat transfer
- 2. Radiation heat transfer



Settled particles: Used as the initial setup

Global	Coefficient of restitution, PP, PW	0.9
	Friction coefficient, PP, PW	0.1
	Stiffness coefficient, PP, PW [N/m]	1.0D2
	DEM time step [s]	1*10-5
Geometry	Diameter [cm]	15.24
	Length [cm]	7.62
	Rotation speed [rpm]	45
	Boundary condition	CG_NSW
	Temperature(fixed) [K]	1000
Solid phase	Density [Kg/m <sup>3</sup> ]	2500
(Silica balls/glass)	Number of particles	3583
	Initial temperature [K]	298

Parameters employed for the simulations



Testing all modes of HT implemented in MFIX-DEM using a rotary drum



	Parameters	Conduction in vacuum	Conduction in stagnant air	Convection & Conduction	Conduction, convection and radiation	_
Solid Phase	Specific heat [J/KgK]	840	840	840	840	
	Thermal conductivity [W/mK]	1.05	1.05	1.05	1.05	
	Thermal emissivity	0	0	0	0.8	
Coupling	Drag model	-	-	SYAM_OBRIEN	SYAM_OBRIEN	
Gas phase	Specific heat [J/Kg-K]	0	1000.7	1000.7	1000.7	
(air)	Thermal conductivity [W/mK]	0	0.0261	0.0261	0.0261	18

#### Validation of conduction heat transfer

- Bodhisattwa Chaudhuri, et al. "Experimentally validated computations of heat transfer in granular materials in rotary calciners". Powder Technology 198 (2010) 6–15.
- A cylindrical drum with **6**" diameter and **3**" long was held at 398 K.
- Drum is half filled with 2 mm alumina particles and rotated at 20 rpm.
- All the parameters and setup was **based on the experimental works** published by *Chaudhuri et al., 2010*.
- Particles are loaded and allowed to fall under gravity.
- **Particles move due to friction** between the wall and particles.
- Heat is transferred simultaneously from wall to particles.



Animation of conduction wall heat transfer (20 sec)

#### Validation of conduction heat transfer

- To validate MFIX, the **normalized temperature curve** was compared to the experimental results.
- **Good agreement** of temperature profile between the MFIX simulations and paper experiments was observed.
- For a better quantitative comparison the thermal time constant was estimated.



Evolution of average bed temperature. The fill level of the drum is 50% and is rotated at 20 rpm.



#### Validation of conduction heat transfer

#### Estimation of the thermal time constant-simulations and experimental results

The heat transfer from the wall to the particles can be calculated from the heat balance equation:

$$M_s C_{ps} \frac{d}{dt} (T_s) = \alpha e_s A_s L (T_W - T_s)$$
$$ln \left( \frac{T_W - T_s}{T_W - T_s^\circ} \right) = -\frac{\alpha e_s A_s L}{M_s C_{ps}} t = -\frac{t}{\tau}$$

1



Technology 198 (2010) 6-15.

## Local experimental setup for Validation all modes of heat transfer

- A stainless steel drum with 6" inner diameter and 3" long was constructed for the HT experiments.
- One side is a sapphire window, capable of transmitting IR radiations, and one side is quartz for internal view.
- The system was constructed to handle 1000° C.
- Temperature profile can be monitored using an IR camera and thermocouples.
- All heat transfer modes will be tested and validated using this setup.



Rotary drum for validation studies

Drum design with Titanium wheel supporting the IR sapphire window, and the quartz glass with air inlet and outlet holes.



## Local experimental setup for Validation all modes of heat transfer



Indirect heating with heat guns

Heating with hot air injection



## Local experimental setup for Validation all modes of heat transfer

## Heating and temperature recoding



- Three heat guns will be used for maintaining the wall at the desired constant temperature.
- Current design can have up to 5 heat guns.



- Drum is stopped and the thermocouples are inserted to record the temperature.
- The response time is less than 2 s.



## Validation of conduction heat transfer: Temperature recoding



Capability to capture heat transfer profile using an IR camera.



# Capabilities



Experimental setup: Rotating stainless steel drum with heat gun to heat the drum walls



Image analysis to validate granular flow



Experimental infrared image to validate heat transfer



**MFIX** simulations



## Conclusions



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The overarching goal is for MFIX-DEM-Phi to be able to solve industrial-scale problems, and to encourage its adoption by industry.



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Source: Visualizations prepared by A. Gel & OLCF Visualization Support for Commercial Scale Gasifier Simulations with MFIX as part of INCITE award (2010) <u>https://mfix.netl.doe.gov/results.php#commercialscalegasifier</u>



# APPENDIX



## **Technical Background/Motivation for The Project**

MFIX: <u>M</u>ultiphase <u>F</u>low with <u>I</u>nterphase e<u>X</u>changes

#### (1) MFIX-TFM (Eulerian-Eulerian)

	Serial	<sup>†</sup> DMP	<sup>‡</sup> SMP
Momentum Equations	•	•	•ŗ
Energy Equations	•	•	•
Species Equations	•	•	•
Chemical Reactions	•	•	
Cartesian cut-cell	•	•	



#### (2) MFIX-DEM (Eulerian-Lagrangian with CFD+DEM or DEM only)

	Serial	<sup>†</sup> DMP	<sup>‡</sup> SMP
Momentum Equations	•	•	•
Energy Equations	•		
Species Equations	•	•	
Chemical Reactions	•		
Cartesian cut-cell	0	0	



#### (3) MFIX-PIC (Eulerian-Lagrangian with Parcel in Cell)

	Serial	<sup>†</sup> DMP	<sup>‡</sup> SMP
Momentum Equations	•		0
Energy Equations			
Species Equations			
Chemical Reactions			
Cartesian cut-cell	0		



#### (4) MFIX-Hybrid (Eulerian-Lagrangian-Eulerian blend of TFM + DEM)

- implemented and fully tested
- o implemented with limited testing
- not tested or status unknown





## **MFIX\* Open Source Multiphase Flow Solver Suite**

## MFIX Two-Fluid Model (TFM) Equations Solved:

Mass conservation for phase m (m=g for gas and s for solids)

$$\frac{\partial}{\partial t} (\varepsilon_m \rho_m) + \nabla \cdot (\varepsilon_m \rho_m \vec{v}_m) = \sum_{l=1}^{N_m} R_{ml}$$

Momentum conservation

$$\frac{\partial}{\partial t} \left( \varepsilon_m \rho_m \vec{v}_m \right) + \nabla \cdot \left( \varepsilon_m \rho_m \vec{v}_m \vec{v}_m \right) = \nabla \cdot \overline{\overline{S}}_m + \varepsilon_m \rho_m \vec{g} + \sum_n \vec{I}_{mn}$$

Granular energy conservation  $(m \neq g)$ 

$$\frac{3}{2}\varepsilon_m\rho_m\left(\frac{\partial\Theta_m}{\partial t}+\vec{v}_m\cdot\nabla\Theta_m\right)=\nabla\cdot\vec{q}_{\Theta_m}+\overline{\bar{S}}_m:\nabla\vec{v}_m-\varepsilon_m\rho_mJ_m+\Pi_{\Theta_m}$$

Energy conservation

Sources:

$$\varepsilon_m \rho_m C_{pm} \left( \frac{\partial T_m}{\partial t} + \vec{\mathbf{v}}_m \cdot \nabla T_m \right) = -\nabla \cdot \vec{q}_m + \sum_n \gamma_{mn} \left( T_n - T_m \right) - \Delta H_{rm}$$

Species mass conservation

$$\frac{\partial}{\partial t} \left( \varepsilon_m \rho_m X_{ml} \right) + \nabla \cdot \left( \varepsilon_m \rho_m X_{ml} \vec{v}_m \right) = R_{ml}$$







#### \* MFIX: <u>M</u>ultiphase <u>F</u>low with <u>I</u>nterphase e<u>X</u>changes

• Syamlal et al. "MFIX Documentation, Theory Guide," DOE/METC-94/1004, NTIS/DE94000087 (1993)

• Benyahia et al. "Summary of MFIX Equations 2005-4", From http://www.mfix.org/documentation/MfixEquations2005-4-3.pdf, July 2007.



## **MFIX\* Open Source Multiphase Flow Solver Suite**

## **MFIX Discrete Element Method (DEM) Equations:**

#### Newtonian Equations for Particles

$$\frac{d\mathbf{X}^{(i)}(t)}{dt} = \mathbf{V}^{(i)}(t),$$

$$m^{(i)}\frac{d\mathbf{V}^{(i)}(t)}{dt} = \mathbf{F}_{\mathrm{T}}^{(i)} = m^{(i)}\mathbf{g} + \mathbf{F}_{\mathrm{d}}^{(i\in k,m)}(t) + \mathbf{F}_{\mathrm{c}}^{(i)}(t),$$

$$I^{(i)}\frac{d\boldsymbol{\omega}^{(i)}(t)}{dt} = \mathbf{T}^{(i)}$$

#### Particle Contact Force Models

$$\mathbf{F}_{\mathrm{n}ij}(t) = \mathbf{F}_{\mathrm{n}ij}^{\mathrm{S}}(t) + \mathbf{F}_{\mathrm{n}ij}^{\mathrm{D}}(t) \qquad \mathbf{F}_{\mathrm{t}ij}(t) = \mathbf{F}_{\mathrm{t}ij}^{\mathrm{S}}(t) + \mathbf{F}_{\mathrm{t}ij}^{\mathrm{D}}(t)$$

#### Drag Forces on Particles

$$\mathbf{F}_{d}^{(i \in k,m)} = -\boldsymbol{\nabla} P_{g}\left(\mathbf{x}_{k}\right) \mathcal{V}_{m} + \frac{\beta_{m}^{(k)} \mathcal{V}_{m}}{\varepsilon_{sm}} \left(\mathbf{v}_{g}\left(\mathbf{x}_{k}\right) - \mathbf{v}_{sm}\left(\mathbf{x}_{k}\right)\right)$$

#### Solid-Fluid Momentum Transfer

$$\mathbf{I}_{\mathrm{g}m}^{k} = -\varepsilon_{\mathrm{s}m} \boldsymbol{\nabla} P_{\mathrm{g}}\left(\mathbf{x}_{k}\right) + \beta_{\mathrm{m}}^{\left(k\right)}\left(\mathbf{v}_{\mathrm{g}}\left(\mathbf{x}_{k}\right) - \mathbf{v}_{\mathrm{s}m}\left(\mathbf{x}_{k}\right)\right)$$







Sources:

• R Garg, J Galvin, T Li, S Pannala, "Documentation of open-source MFIX-DEM software for gas-solids flows" (2010)

## **MFIX Overview (Today)**

# A suite of multiphase flow models & solvers



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#### MFIX: A Unified Framework and Code Base for Eulerian-Lagrangian and Lagrangian Treatment of Multiphase Flows

Flow chart illustrating the key solution processes coupling the CFD & DEM solvers and the associated governing equations



No need for external coupling of multiple software

## Summary of subroutine modification



# Particle size distributions



Uniform distribution

Segmented normal distribution





Validation of conduction heat transfer

- > As time progresses, temperature of particles inside the drum increases.
- The particles are heated first along the boundary of the drum forming a cool middle core and hot outer layer.
- DEM tracks temperature of every individual particles after each time step and the average temperature of the particle bed is calculated as a mean of temperature of all the particles.



Snapshots of temperature profile at different time intervals



## **Preliminary Results for Bin Flow Case**



Particle injection (0.4s) and settling (0.3s)

Particle discharge (4.0 s)



## Verification of Polydispersity Implementation

## Discharge dynamics for a 3D hopper with equal-sized spherical beads.

	Domain Decomposition	Total Number	CPU
	Configuration	of Particles	hour
MFIX-DEM 2016-1	$2 \times 2 \times 2$	15544	5.45
Our implementation	$2\times 2\times 2$	15540	5.44



- The discharged mass vs. discharge time curves obtained from both the 2016-1 MFIX and our new implementation agree well with one another.
- The total computational cost in terms of wallclock CPU hours for the simulations are also comparable in the two cases.
- Hence, these results verify the correctness of our new implementation.





Segregation results for the discontinuous discharge methods in experiment and mfix simulation. 43

# Multilayer Discharge Simulation



199442 particles

199442 particles

• 199442 particles





## Validation and Implementation of particle size polydispersity

#### Enhancing Capability for Handling Particle Size Distributions

- New data structures have been implemented to separate geometrical and physical parameters of each particles of a solid phase, and to allow each solid phase to possess a different size distribution.
- New subroutines have been written to generate initial particle configurations with built-in distributions, including Gaussian, Log-Normal, and Uniform.

Implemented distribution types: Uniform, Normal(Gaussian), Log Normal

• New subroutines have been written to generate initial particle configurations with arbitrary user-defined particle size distributions.

Added commands for ICs: IC\_PSD\_TYPE(ICV, Phase) IC\_PSD\_MEAN\_DP(ICV, Phase) IC\_PSD\_STDEV(ICV, Phase) IC\_PSD\_MAX\_DP(ICV, Phase) IC\_PSD\_MIN\_DP(ICV, Phase)

- Subroutines using particle radii as parameters have been modified accordingly.
- The implementations have been tested in a discharging hopper case provided by our collaborator.

