Robust Metal-Ceramic Coaxial Cable Sensors for Distributed Temperature Monitoring in Harsh Environments of Fossil Energy Power Systems



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Introduction:

The development of cleaner coal-based power plants has necessitated real time monitoring of process conditions and equipment physical states. The realization of such monitoring capability will rely largely on the development of harsh environment sensors that are currently nonexistent. In recently years, various fiber optic sensors (FOS) have been under development and found many successful applications in harsh environments due to their unique advantages including compactness, high resolution, immunity to electromagnetic interference, remote operability, multiplexing capability, and thermal and chemical stabilities [1]. However, they are fragile, requiring very bulky, costly, and sophisticated packaging, and have a small dynamic range due to their limited reversible deformability. Coaxial cables may overcome the fragility issue and the signal generation and transmission mechanisms are governed by the same electromagnetic principles as in FOS.

Concept & Approach:

The approach to this project is to implement a well-known optical fiber interferometric sensor mechanism, the Fabry-Perot interferometer (FPI), in the coaxial cable (CC), referred as a CC-FPI sensor [3]. The CC-FPI sensors, as illustrated below, operate in radio frequency (RF) domain which allows choices of low-cost commercial components and instruments for sensor signal processing.



Assuming the amplitude reflection coefficients of the two reflectors are the same, the two reflected waves (U1 and U2) are given as:

$$U_1 = \Gamma(f)e^{-\alpha z}\cos(2\pi ft)$$
 and $U_2 = \Gamma(f)e^{-\alpha z}\cos[2\pi f(t+\tau)]$
where $\tau = 2d\sqrt{\varepsilon_r}/c$

where $\Gamma(f)$ is the amplitude reflection coefficient of the reflector; f is the frequency of the EM wave; α is the propagation loss coefficient; z denotes the cable axial direction; τ is the time delay between the two reflected wave; d is the distance between the two reflectors; ε_r is the relative permittivity of the inner dielectric material of the cable; and c is the speed of light in vacuum. The interference signal (U) is the summation of the two reflected waves, expressed as

$$U = 2 \cdot \Gamma(f) e^{-\alpha z} \cos\left(2\pi f \frac{2d\sqrt{\varepsilon_r}}{c}\right) \cos\left[2\pi f\left(t + \frac{2d\sqrt{\varepsilon_r}}{c}\right)\right]$$

The CC-FPI measures temperature by monitoring the interferogram shift from a reference defined at an arbitrary temperature (T_0) because d and ε_r are functions of temperature:

$$d_{T} = d_{0} + \beta_{T} (T - T_{0})$$
$$\varepsilon_{r,T} = \sum_{i=0}^{n} (a_{i} \times T^{i})$$

The interference signal thus becomes a function of temperature and monitoring the interfeometric spectrum shift, U(T), allows for real-time measurement of temperature by the CC-FPI.

$$U(T) = K_1 \cos(K_2 \cdot \tau(T)) \cdot \cos[K_2(t + \tau(T))]$$
$$\tau(T) = 2d_T \cdot \varepsilon_{r,T}^{0.5} / c$$

Objectives & Deliverables :



Year 1	Design sensor structure, identify/develop sensing materials, and fabricate single-point MCCC-FPI.	Annual report (6/30/2015)
Year 2	Examine single-point MCCC-FPI sensor performance and stability, and construct multi-point FPI sensors for distributed sensing.	Annual report (6/30/2016)
Year 3	Integrate sensor systems and perform distributed temperature measurement by the multi-point MCCC-FPI sensor.	Final report (6/30/2017)





