

# MFiX - Multiphase Flow with Interphase Exchanges



*Software tools and expertise to address multiphase flow challenges in research, design, and optimization*

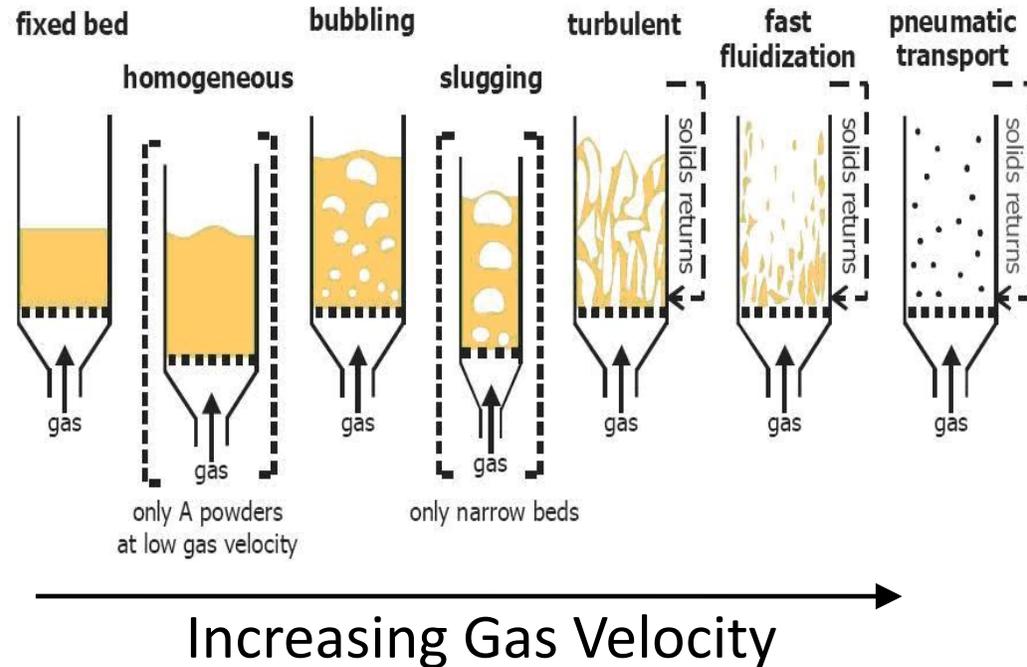
Jeff Dietiker, Multiphase Flow Science Group, NETL/LRST



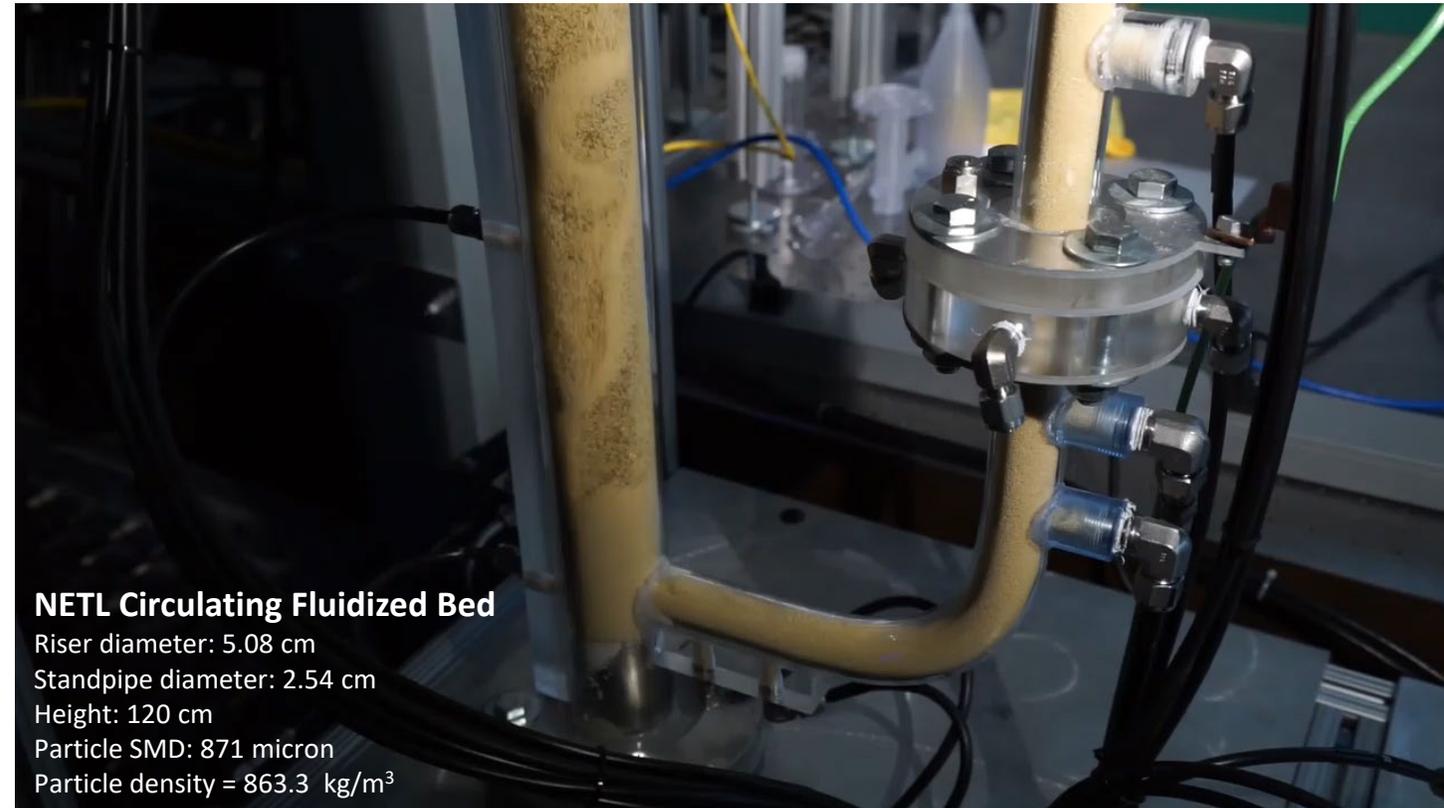
# Use Simulation Tools to Predict Performance

Gas-solid fluidization is very challenging to accurately model

- Fluidized bed: solid particles are suspended in a fluid-like state
- With Increasing of gas velocity, several fluidization regimes can be observed – often in the same reactor!



J. Ruud van Ommen, 2003



# MFiX Suite of Multiphase CFD Software

## Capabilities and Benefits

 is NETL flagship computational fluid dynamic (CFD) code

- **Versatile toolset** for understanding the behavior and characterizing the performance of energy conversion processes
- **Accelerate reactor development and reduce cost** by using multiphase flow reactor modeling and simulation tools
- **Optimizes performance** for equipment and unit operations, enabling more throughput and less process downtime
- **Reduces design risks** when validated by predictive science-based calculations, lowering risk in obtaining return on investment

MFiX-TFM (Two-Fluid Model)

MFiX-DEM (Discrete Element Model)

MFiX-PIC (Multiphase Particle-In-Cell)

MFiX-CGDEM (Coarse Grain DEM)

MFiX Exa (Exascale) – under development

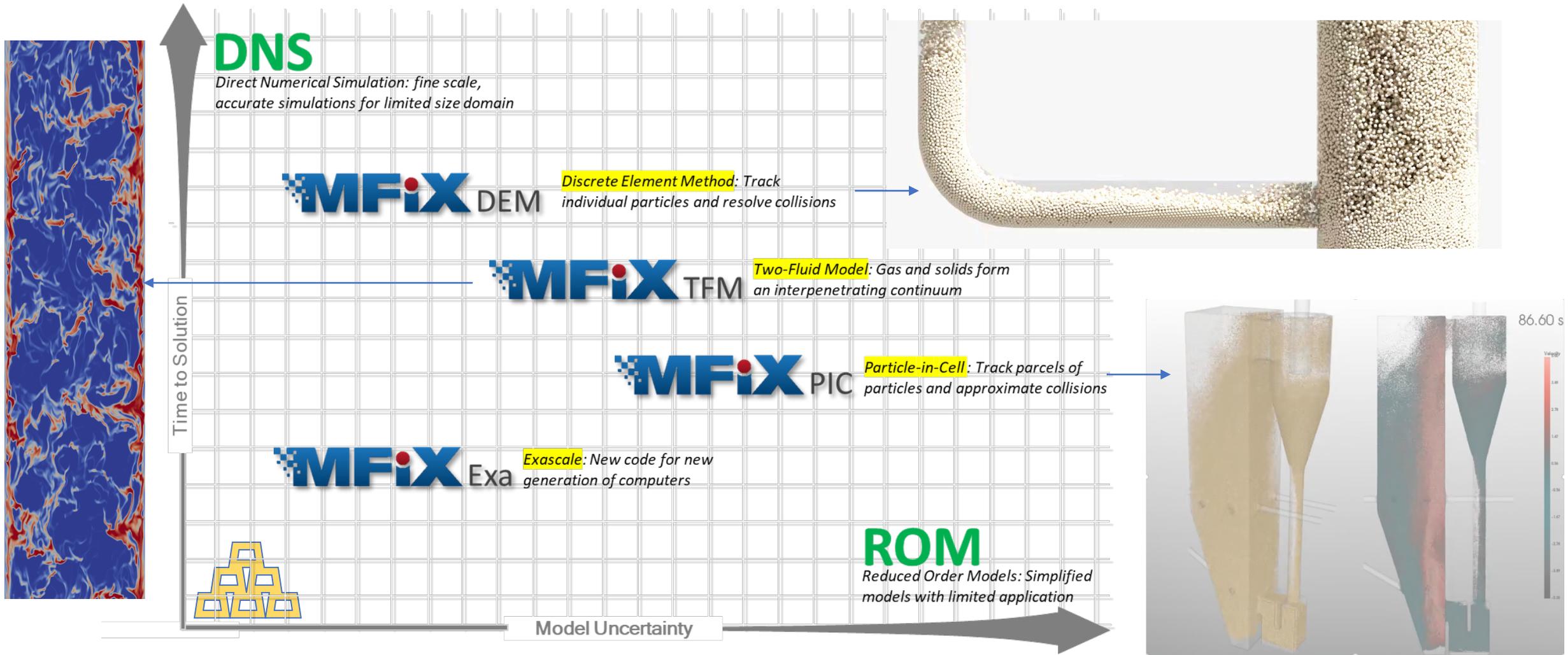
C3M multiphase chemistry management software

Nodeworks: Optimization and UQ Toolsets

**MFS Software Portfolio**

# MFiX Suite of Multiphase CFD Software

Managing the tradeoff between accuracy and time to solution



# MFiX-TFM : Model Overview

Continuous and disperse phases (e.g., gas and solids) are treated as coexisting continua.

## Highlights

- Long track record of successfully supporting DOE-FE priorities
- Computationally efficient
- Historical workhorse for large-scale FE applications

## Technical limitations

- Unable to efficiently model phenomena like particle size distributions
- Relies on complex constitutive relations to approximate solid stresses
- Ad hoc extension to multiple solids phases

**Fluid continuity equation:**

$$\frac{\partial}{\partial t}(\varepsilon_g \rho_g) + \nabla \cdot (\varepsilon_g \rho_g \mathbf{u}_g) = \mathcal{S}_g$$

**Fluid momentum equation:**

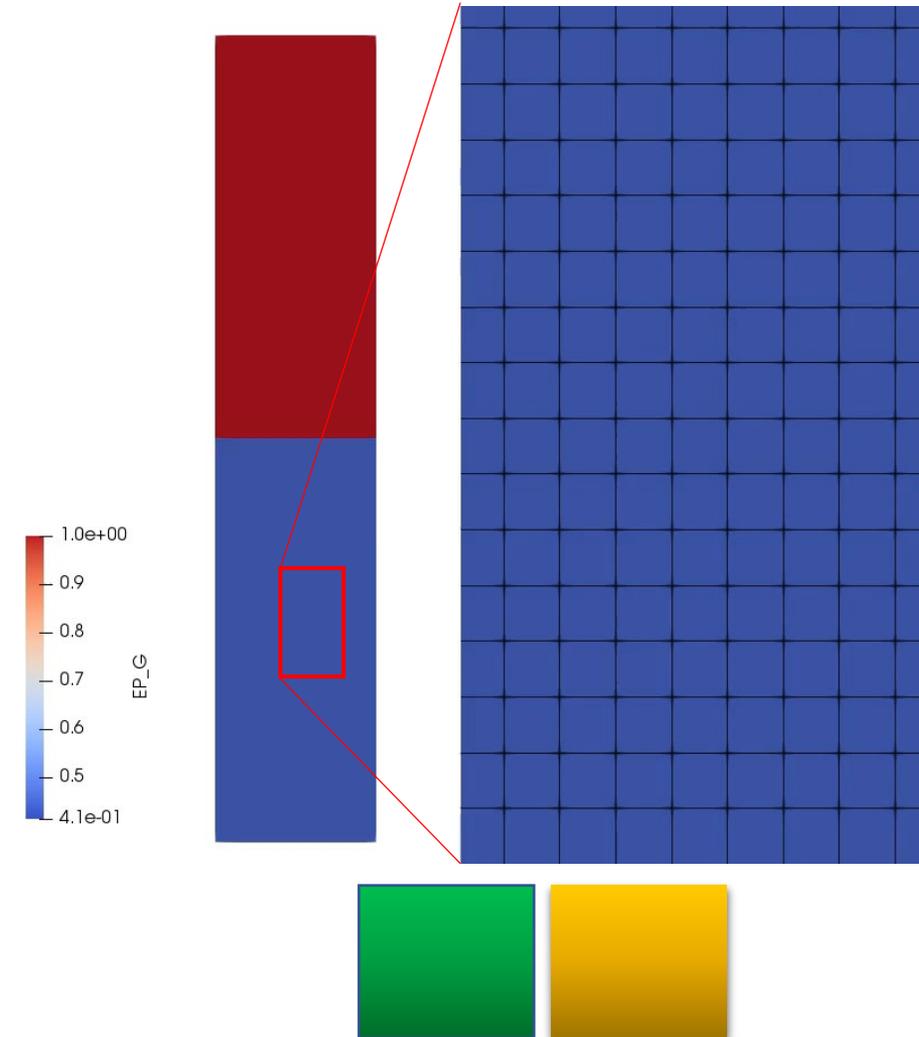
$$\begin{aligned} \frac{\partial}{\partial t}(\varepsilon_g \rho_g \mathbf{u}_g) + \nabla \cdot (\varepsilon_g \rho_g \mathbf{u}_g \mathbf{u}_g) \\ = -\varepsilon_g \nabla p_g + \nabla \cdot \boldsymbol{\tau}_g + \varepsilon_g \rho_g \mathbf{g} + \sum_m \mathcal{J}_{g,m} \end{aligned}$$

**Solids continuity equation:**

$$\frac{\partial}{\partial t}(\varepsilon_m \rho_m) + \nabla \cdot (\varepsilon_m \rho_m \mathbf{u}_m) = \mathcal{S}_m$$

**Solids momentum equation:**

$$\begin{aligned} \frac{\partial}{\partial t}(\varepsilon_m \rho_m \mathbf{u}_m) + \nabla \cdot (\varepsilon_m \rho_m \mathbf{u}_m \mathbf{u}_m) \\ = -\nabla p_m + \nabla \cdot \boldsymbol{\tau}_m + \varepsilon_m \rho_m \mathbf{g} - \mathcal{J}_{g,m} \end{aligned}$$



**Solver time: Fluid  
(one solids phase)**

**Solid**

# MFiX-DEM : Discrete Element Model

Fluid is a continuum and particles are individually tracked, resolving particle-particle-wall collisions

## Advantages

- Uses first principles to account for particle interactions, reducing model complexity.
- Fewer complex closures results in less overall model uncertainty.
- Only open-source, fully coupled CFD-DEM code designed for reacting flows.

## Technical limitations

- Computationally expensive, limiting the size of systems that can be modeled.
- Fluid-particle interaction is closed using drag models.

**Fluid continuity equation:**

$$\frac{\partial}{\partial t}(\varepsilon_g \rho_g) + \nabla \cdot (\varepsilon_g \rho_g \mathbf{u}_g) = \mathcal{S}_g$$

**Fluid momentum equation:**

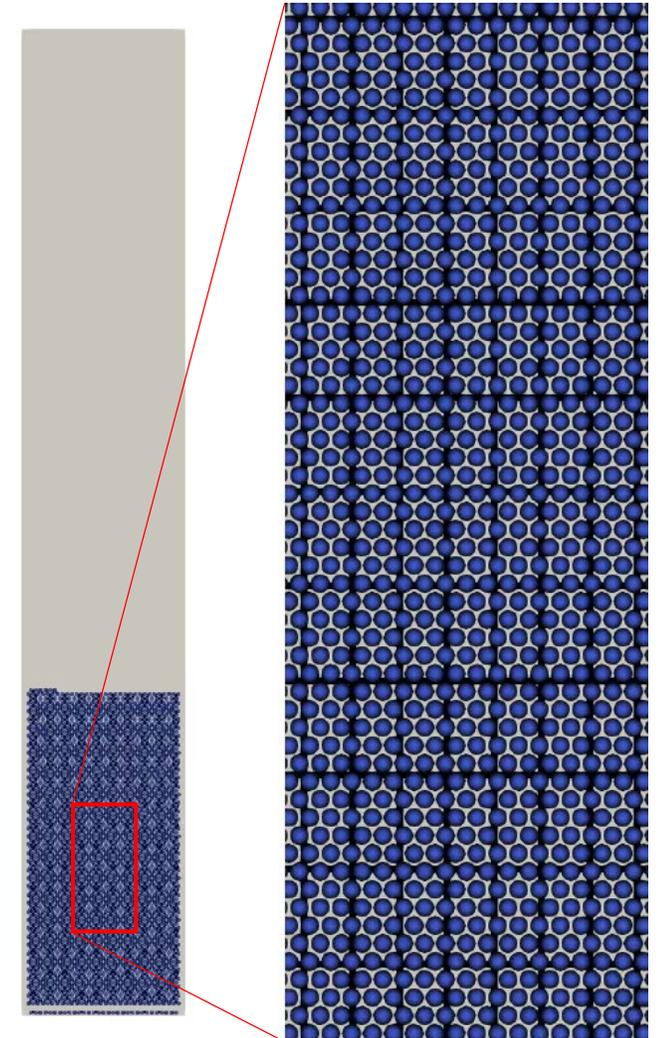
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**Particle continuity equation:**

$$\frac{\partial}{\partial t}(m_p) = \mathcal{S}_p$$

**Particle momentum equations:**

$$\begin{aligned} m_p \frac{\partial \mathbf{u}_p}{\partial t} &= m \mathbf{g} + \mathbf{F}_{coll} - \mathcal{J}_{g,p} \\ I_p \frac{\partial \boldsymbol{\omega}_p}{\partial t} &= \mathcal{J} \end{aligned}$$



# MFiX-DEM : Discrete Element Model

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Particle continuity equation:

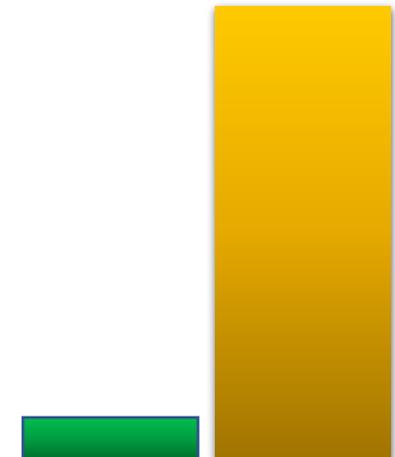
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Particle momentum equations:

$$\begin{aligned} m_p \frac{\partial \mathbf{u}_p}{\partial t} &= m \mathbf{g} + \mathbf{F}_{coll} - \mathbf{J}_{g,p} \\ I_p \frac{\partial \boldsymbol{\omega}_p}{\partial t} &= \boldsymbol{\mathcal{J}} \end{aligned}$$



P-P and P-W collisions are resolved  
(soft sphere)



Solver time: Fluid Solid

# MFiX-PIC : (Multiphase) Particle-in-Cell

Fluid is a continuum and particles are tracked as parcels, solid-stress model approximates collisions

## Advantages

- Computationally efficient
- Able to track particle-scale phenomena like time-histories and size distributions
- Only open-source, PIC model

## Technical limitations

- Relies on a continuum stress model to approximate particle-particle interactions
- Strong dependence on implementation

Formally released: April, 2019

Fluid continuity equation:

$$\frac{\partial}{\partial t}(\varepsilon_g \rho_g) + \nabla \cdot (\varepsilon_g \rho_g \mathbf{u}_g) = \mathcal{S}_g$$

Fluid momentum equation:

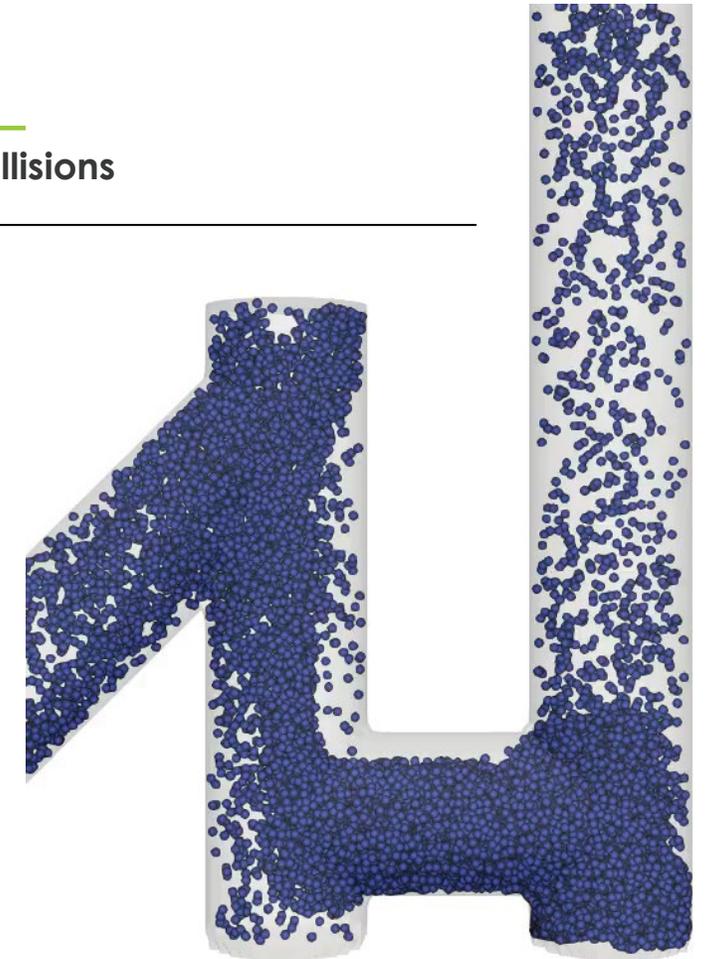
$$\frac{\partial}{\partial t}(\varepsilon_g \rho_g \mathbf{u}_g) + \nabla \cdot (\varepsilon_g \rho_g \mathbf{u}_g \mathbf{u}_g) = -\varepsilon_g \nabla p_g + \nabla \cdot \boldsymbol{\tau}_g + \varepsilon_g \rho_g \mathbf{g} + \sum_p \mathcal{J}_{g,p}$$

Parcel continuity equation:

$$\frac{\partial}{\partial t}(m_p) = \mathcal{S}_p$$

Parcel momentum equation:

$$m_p \frac{\partial \mathbf{u}_p}{\partial t} = m_p \mathbf{g} + \nabla \tau_p - \mathcal{J}_{g,p}$$



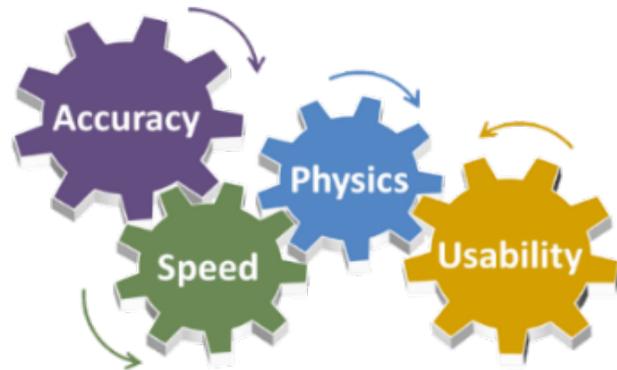
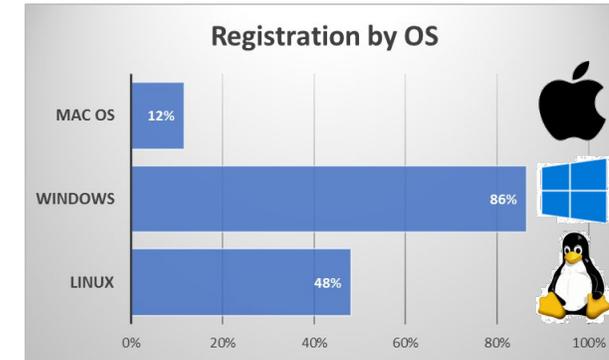
Parcel collisions are not resolved



Solver time: Fluid Solid

# Graphical User Interface (GUI)

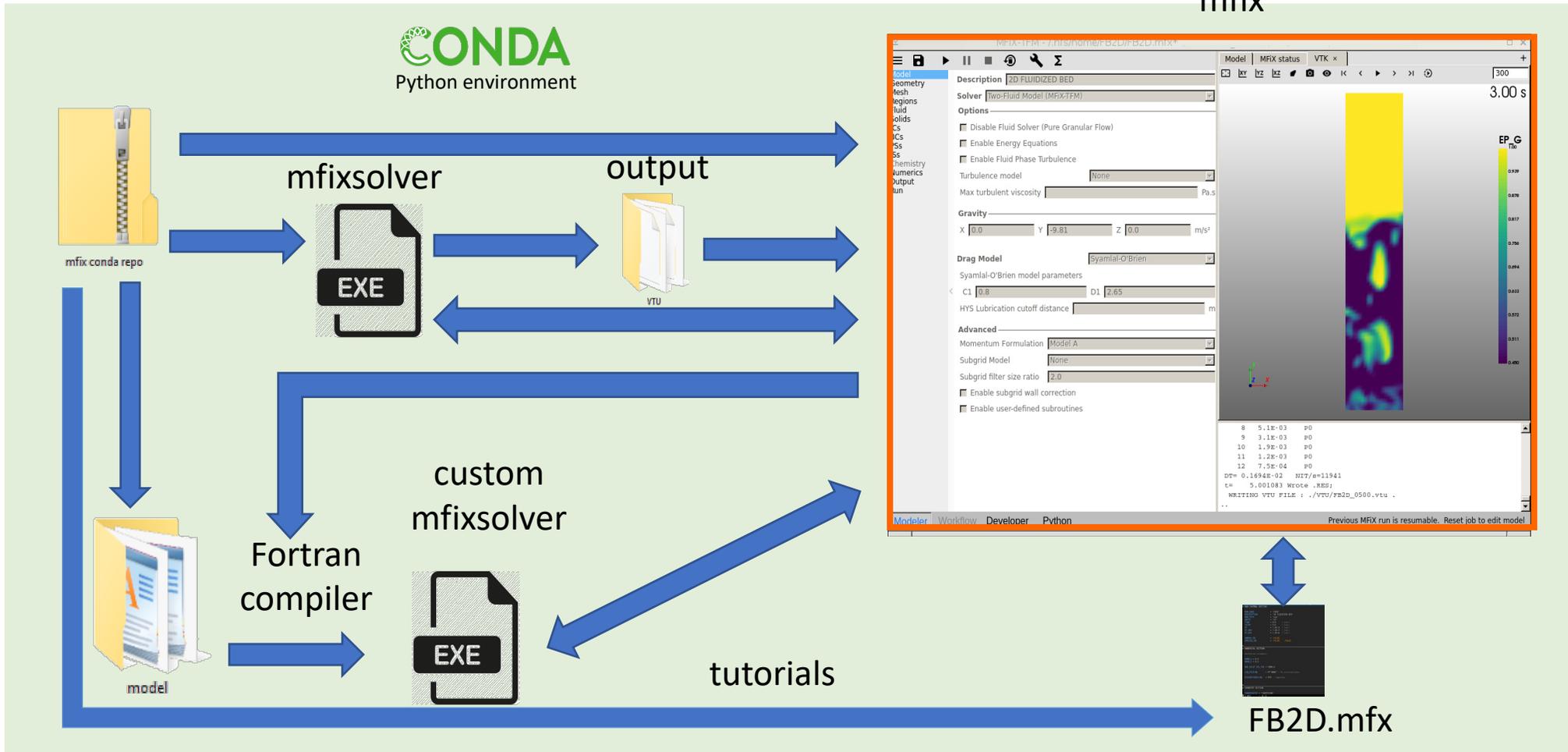
- **Open-source** (<https://mfix.netl.doe.gov>)
- **Motivation: Better serve MFiX community**
  - Improve usability of MFiX
  - Support Linux, macOS and Windows OS
  - Decrease time to setup, reduce error
- **Solution: Graphical User Interface**
  - Released in 2017
  - Between 1 and 4 releases per year



# MFiX usability improvement

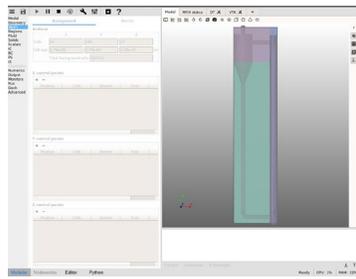


— User interaction

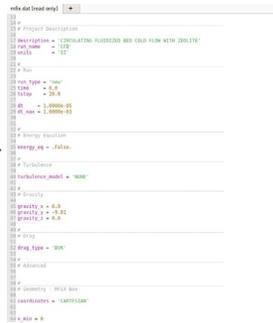


# Preprocessor development

## Old workflow GUI



.mfx



MFiX solver

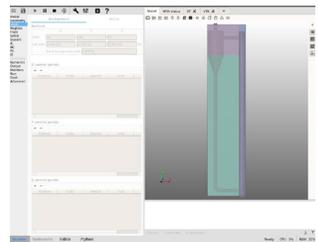
mesh results



## New (20.1) workflow

Inspection

GUI



MFiX mesher

mesh

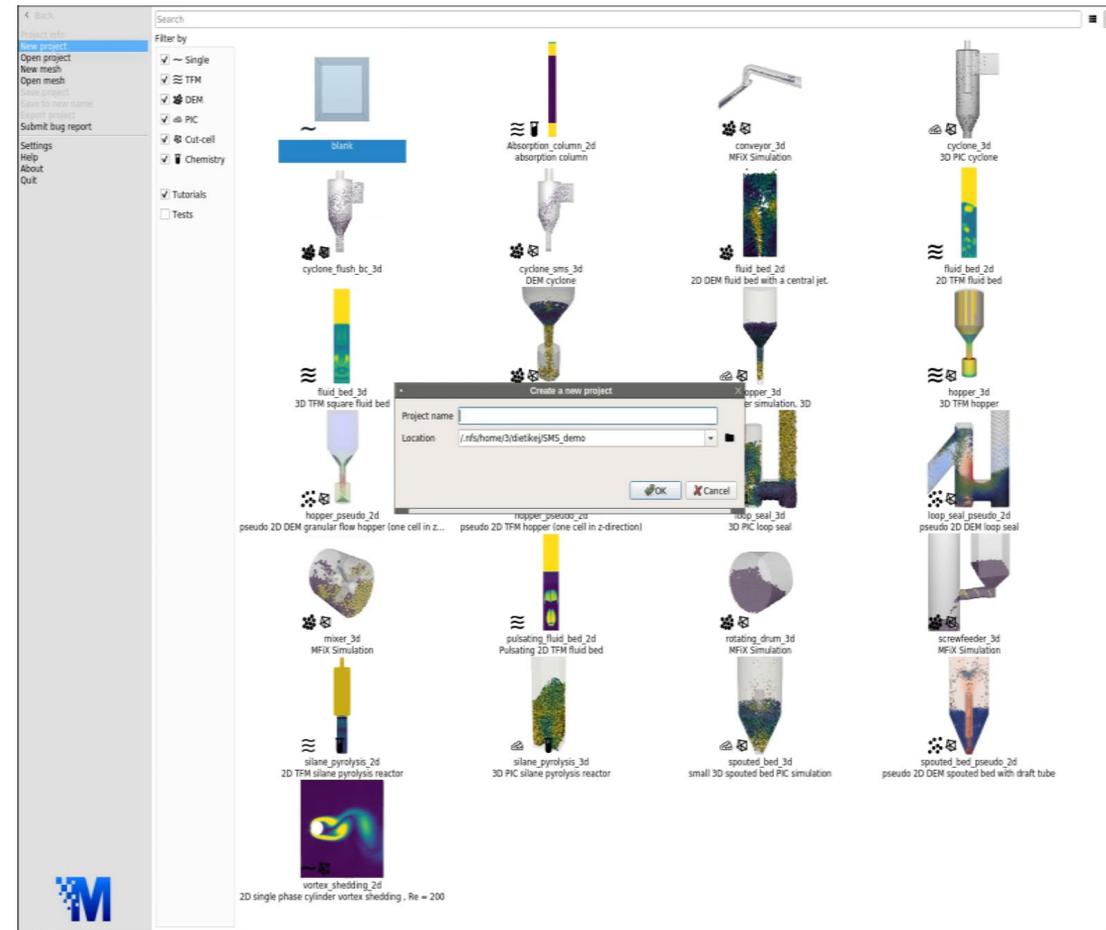


.mfx

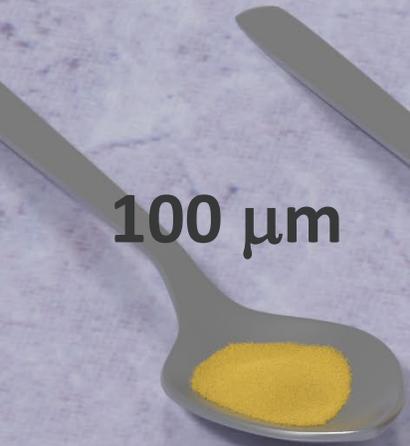


MFiX solver

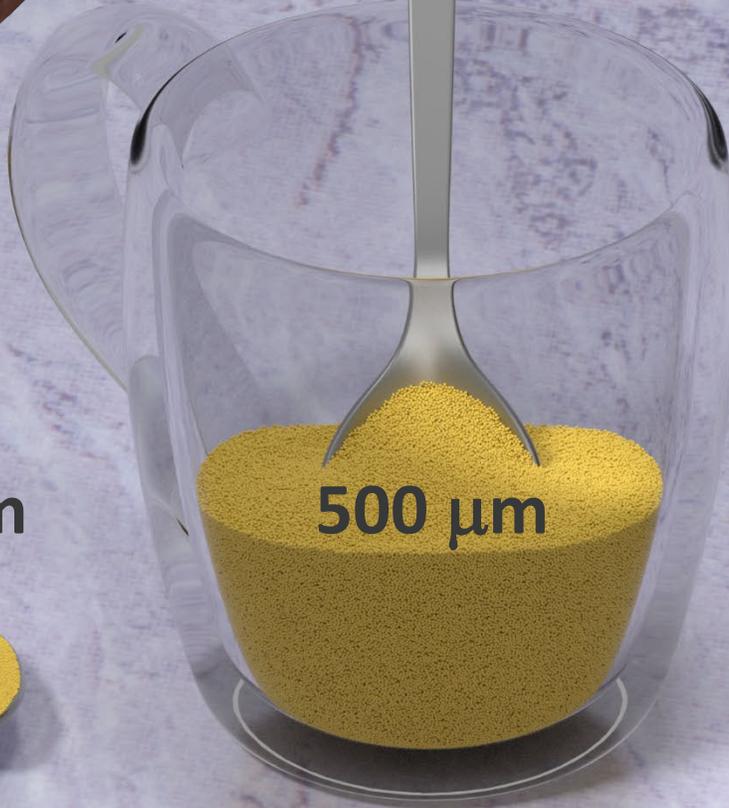
results



# What can be modeled with 1 Million particles?



100 μm



200 μm

500 μm



1,000 μm



# Enabling large Scale simulations

DEM example

Height = 0.68 m

Particle diameter = 800 microns

Particle count = 500,000 particles



# Enabling large Scale simulations

Height = 4.0 m (x6)  
Particle count = 650 Millions (x1,300)

DEM

PIC, Parcel counts = 13 Millions

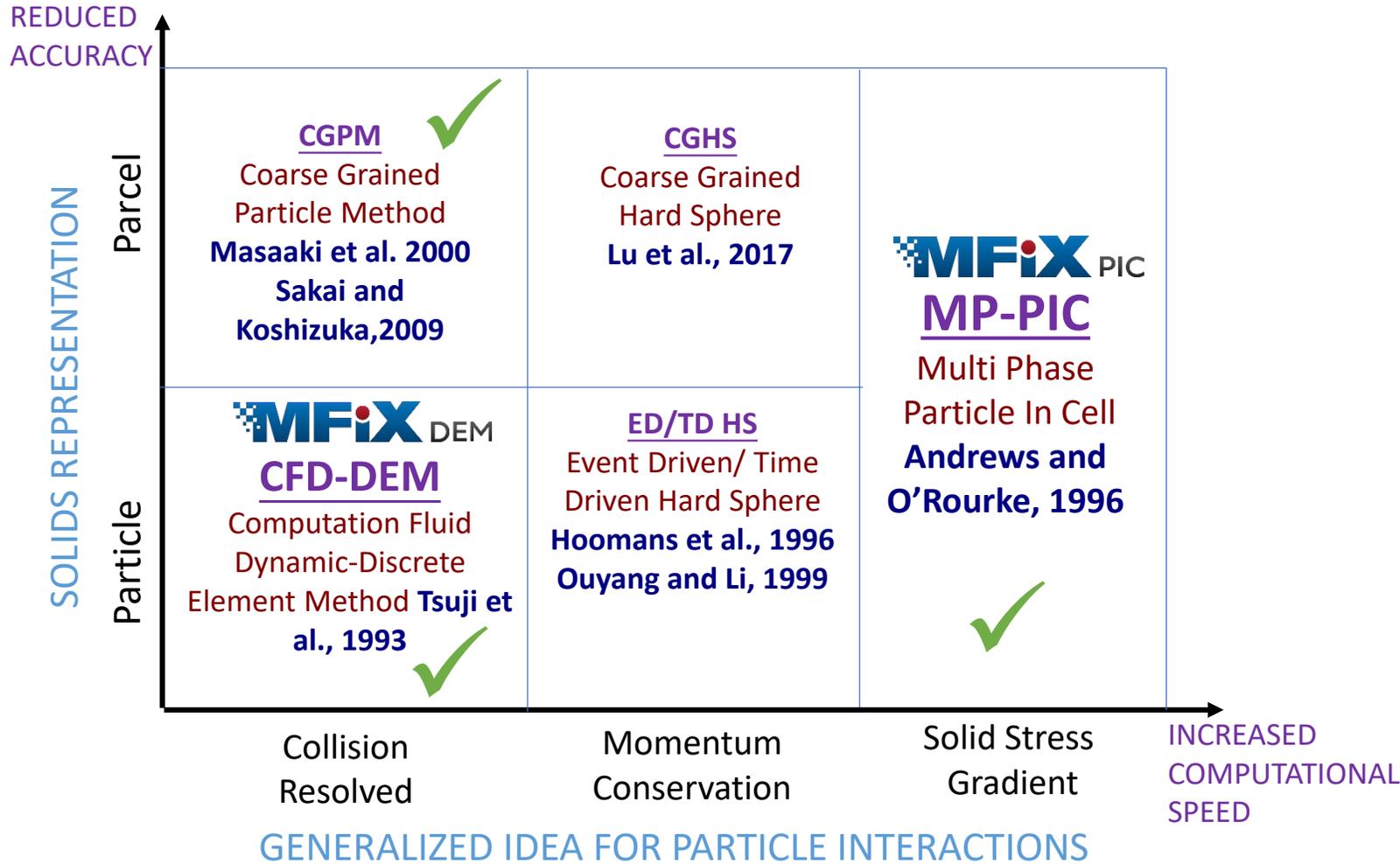


Height = 0.68 m  
Particle count = 500,000

DEM

# Multiphase Particle In Cell (MP-PIC)

Use MP-PIC for computational speed and averaged accuracy



Particle Flow in Cyclone

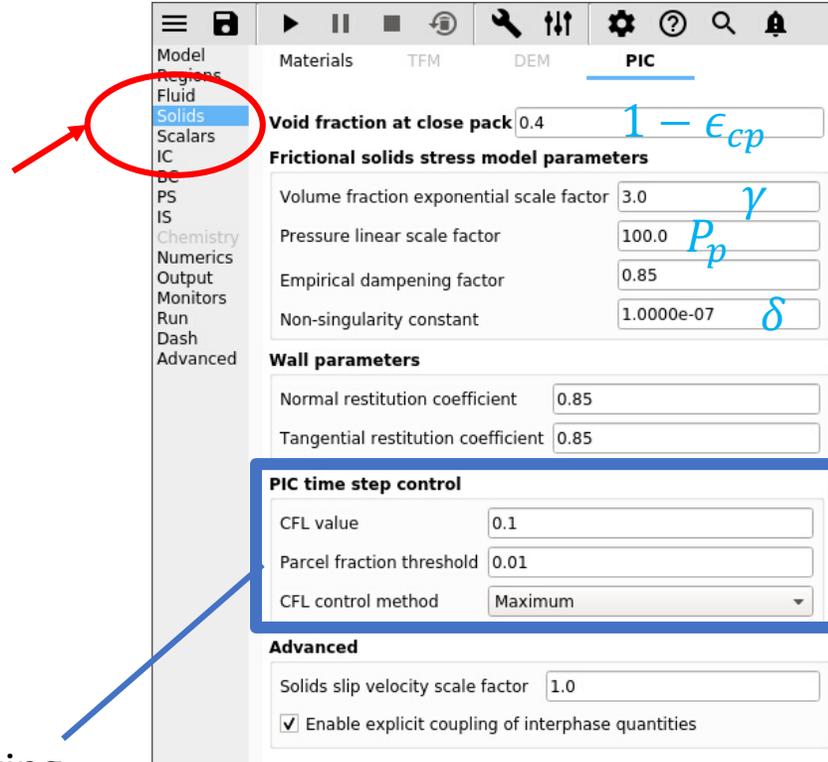


MP-PIC can significantly reduce computational effort, and in the right type of application, maintain accuracy.

# Multiphase Particle In Cell (MP-PIC)

## Basic Set-Up Information

The PIC model parameters are clustered under the Solids tab.



New in 20.2: PIC CFL setting

- Need for CFL identified by QA program
- Allows consistent results with large Fluid time step
- Showed speed up of 3 for a cyclone simulation

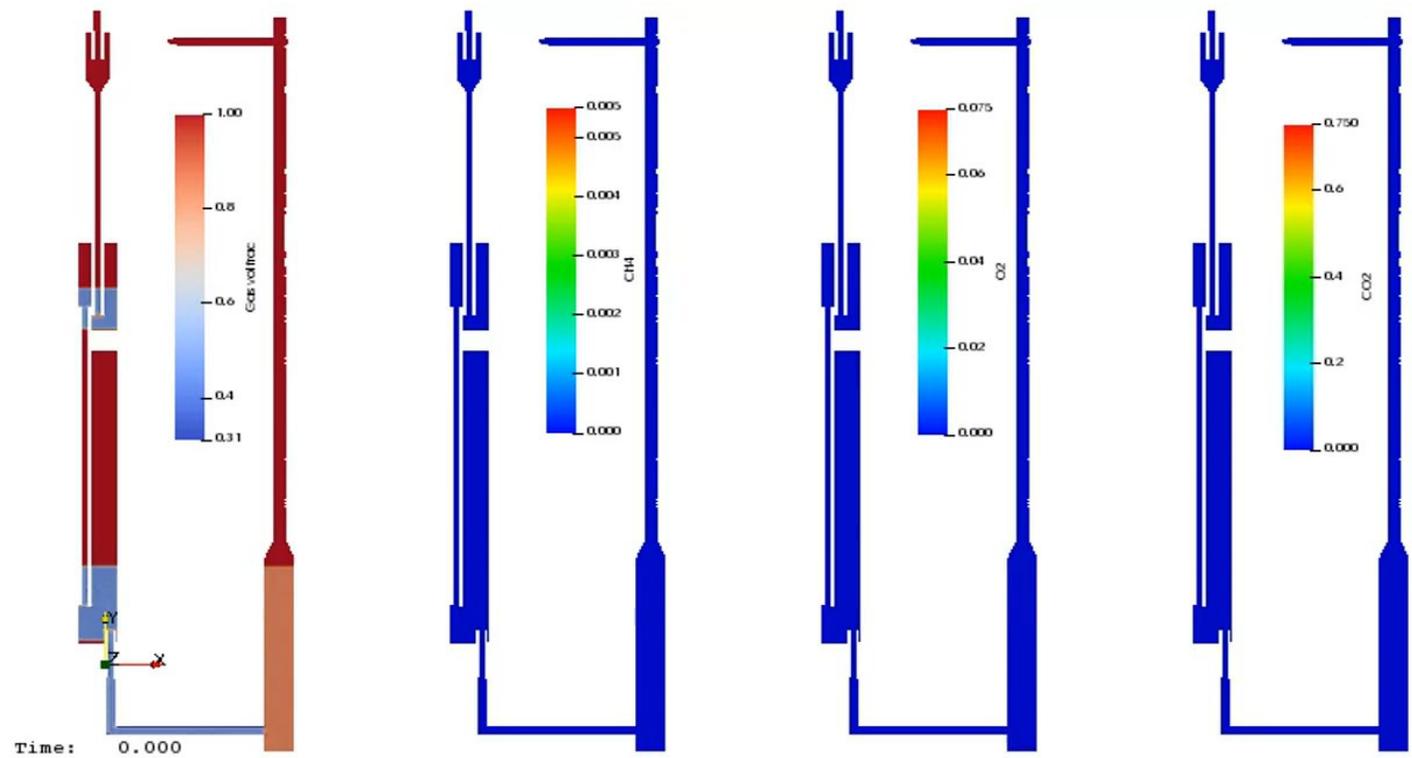
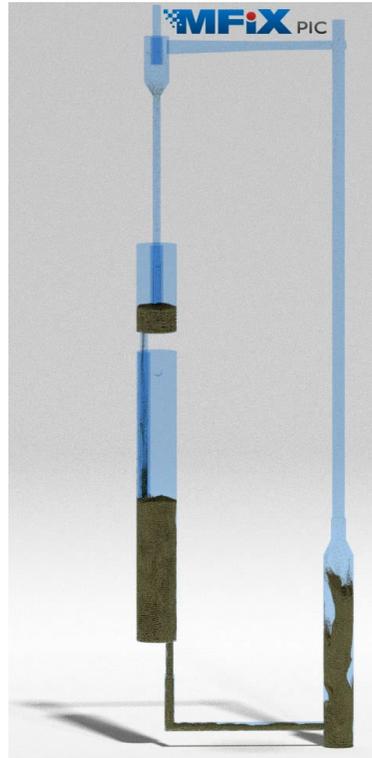
Some parameters that a user defines directly influence the momentum equation through solids stress calculation.

$$\tau_p = \frac{P_p \epsilon_p^\gamma}{\max(\epsilon_{cp} - \epsilon_p, \delta(1 - \epsilon_p))}$$

$$\frac{d\vec{V}_p}{dt} = \beta(\vec{U}_g - \vec{V}_p) - \frac{1}{\rho_p} \nabla p - \frac{1}{\epsilon_p \rho_p} \nabla \tau_p + \vec{g}$$

Other parameters act as scale factors for energy exchange between parcels and their surroundings.

# Multiphase Particle In Cell (MP-PIC)



**Simulation of industrial scale multi-phase flow devices is within MFiX's grasp!**

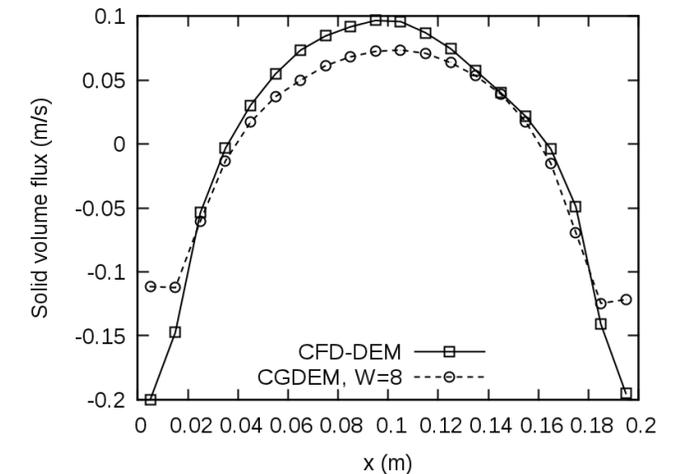
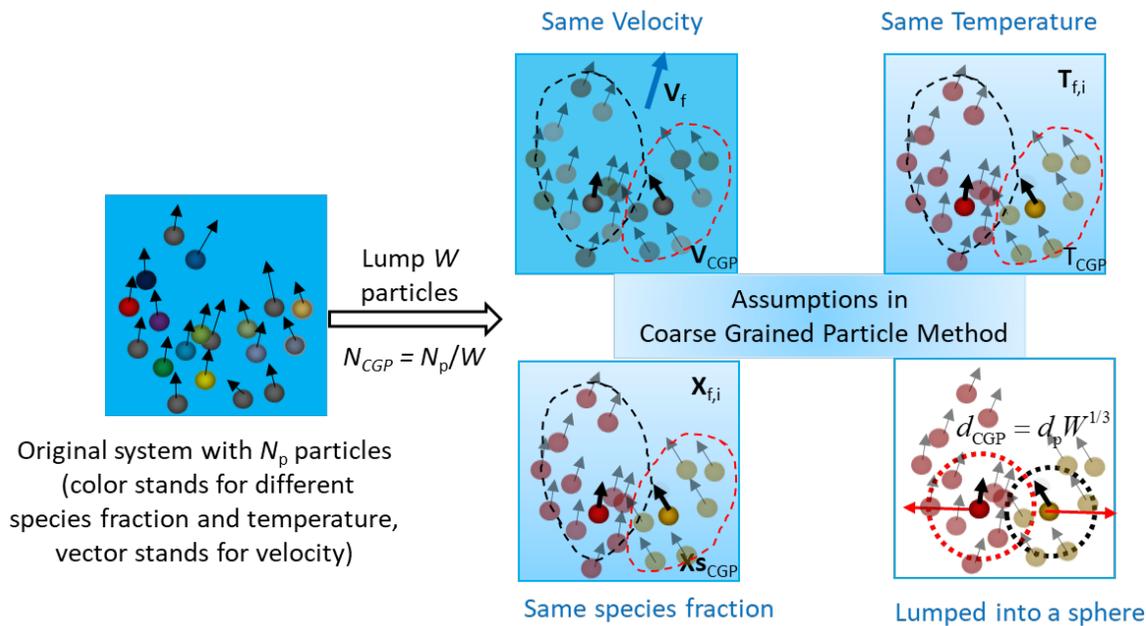
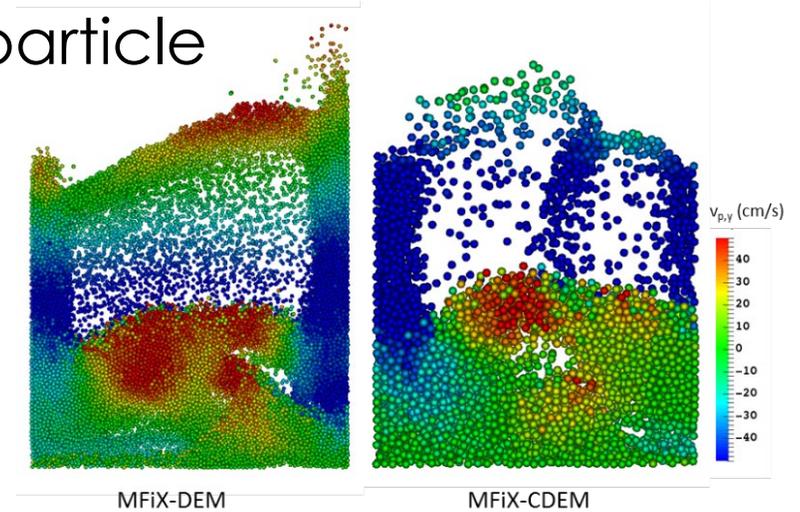
MFiX-PIC couples the MFiX Eulerian fluid solver with new Lagrangian solids stress model.

Excellent matching to pressure drop, temperature profiles and chemical species production at industrial scale.

Tractable time to solution.

# Coarse Grain DEM

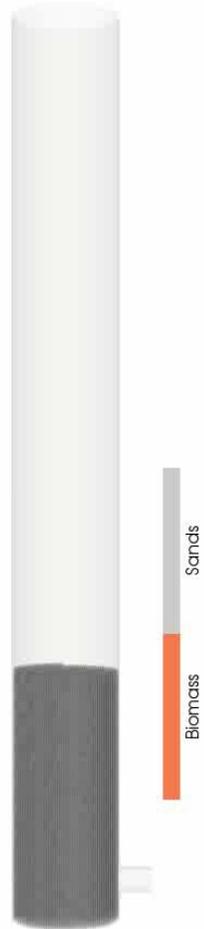
- Particles are lumped together to create a CG particle
- CG particles collide with each other
- Heat transfer, chemical reactions
- MFiX-CGDEM formal release: 12/31/2020



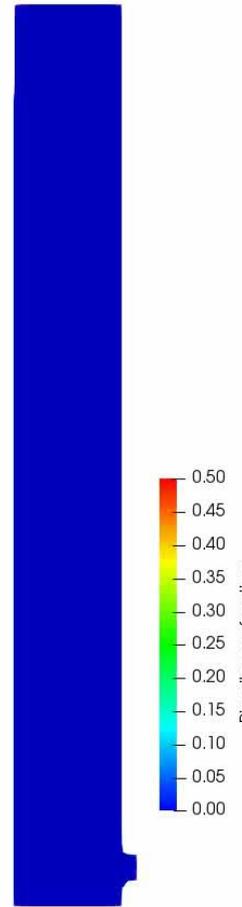
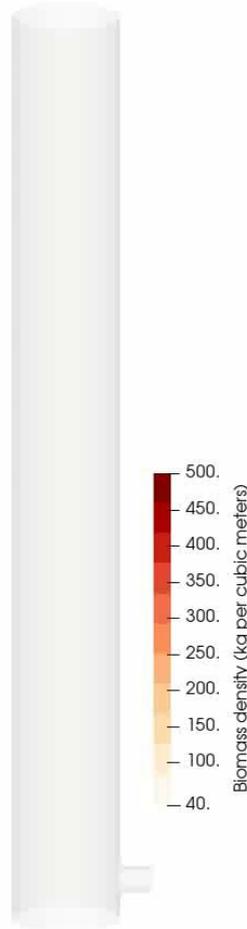
# Coarse Grain DEM

## CG-DEM Simulation of 2-inch Fluidized Bed Pyrolysis Reactor

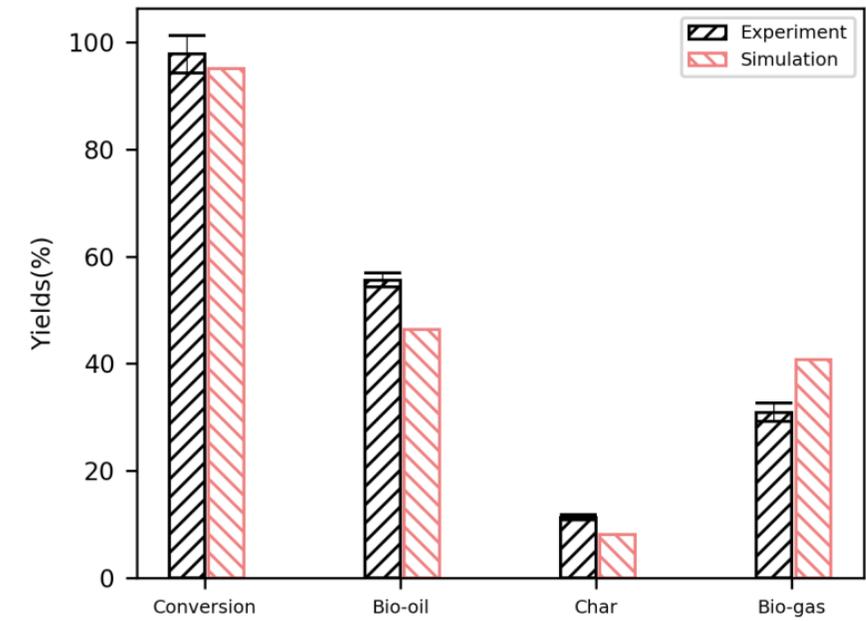
Time: 0.00 s



Biomass (enlarged 2 times)



1. Sands & 130 microns Biomass
2. Coarse Grained DEM Simulation
3. Hybrid drag model
4. DNS calibrated heat transfer & reaction kinetics

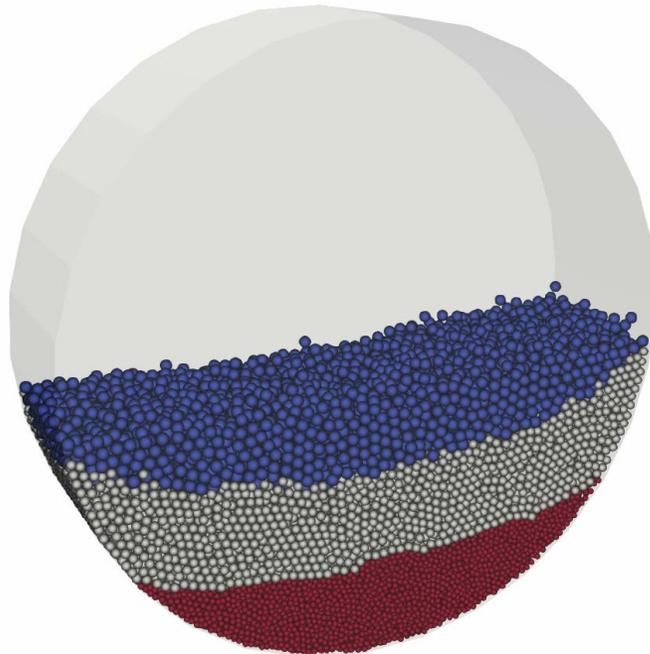


# Moving geometry

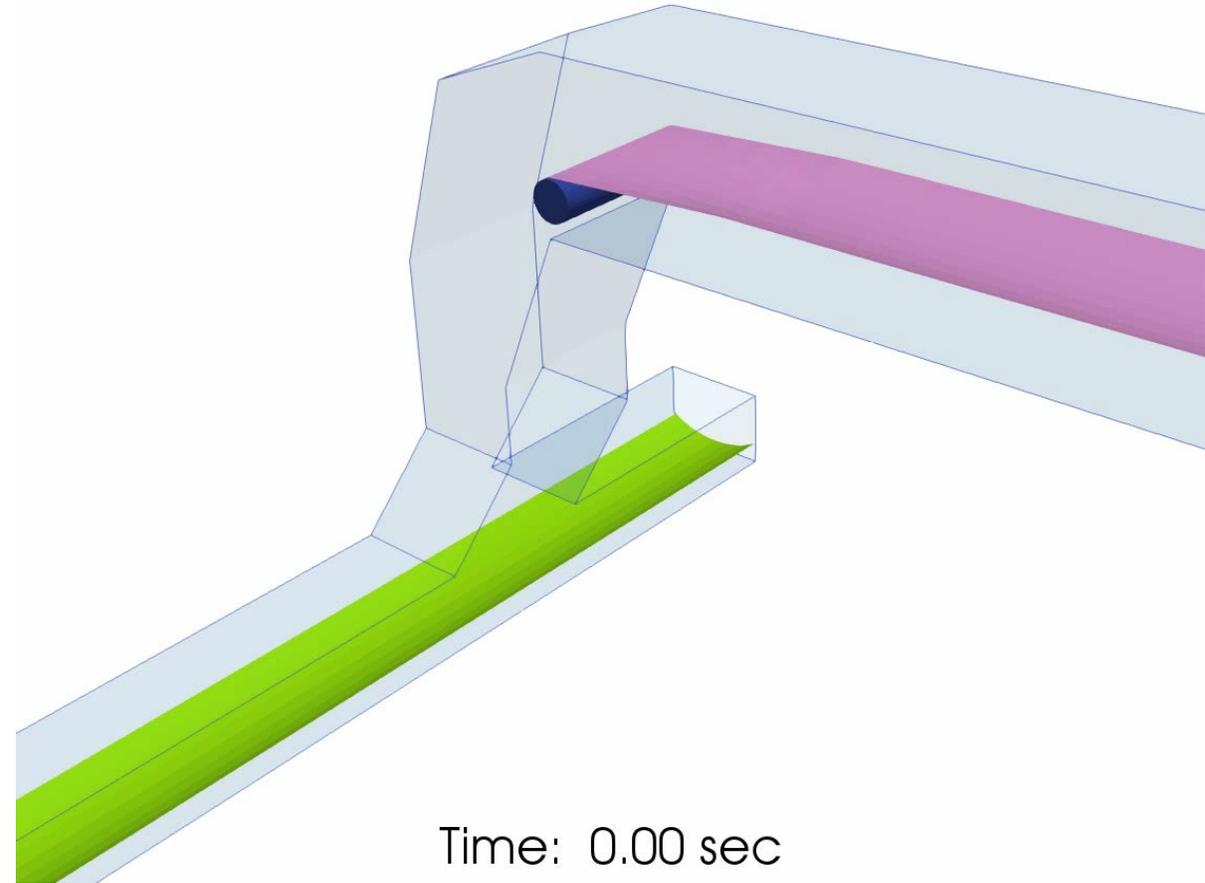
## Several options to represent moving geometry

Moving STL walls through tangential velocity

- Add Collection of UDFs and tutorials
- Rotating drum
- Conveyor belts



Time: 0.00 sec

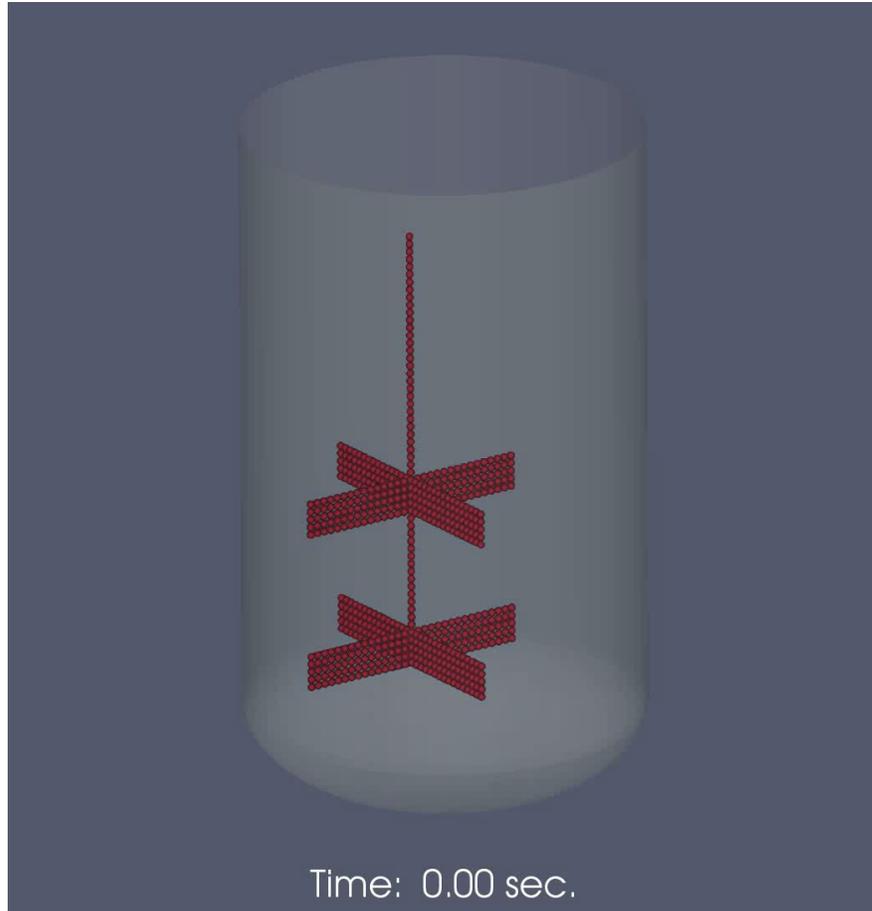


Time: 0.00 sec

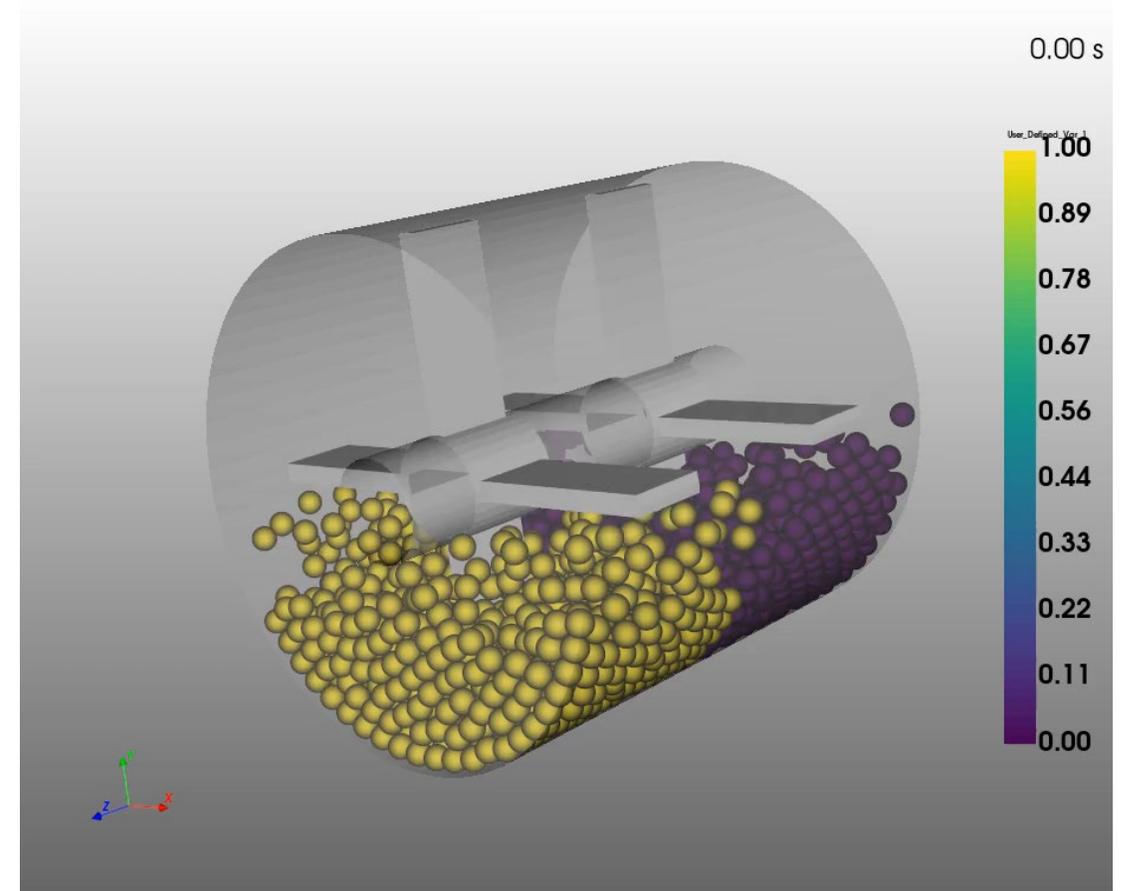
# Moving geometry

## Several options to represent moving geometry

Freeze or set particle velocity

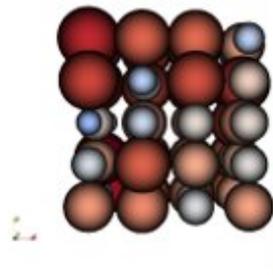
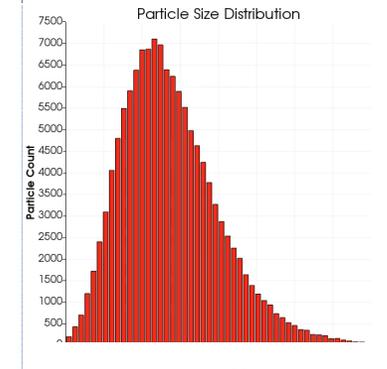
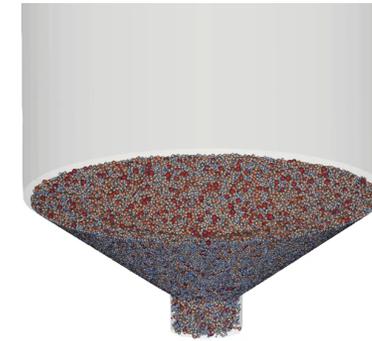
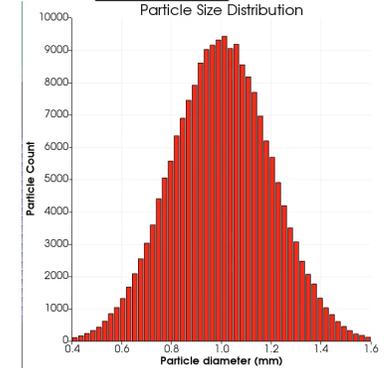


Move STL geometry (Granular DEM)

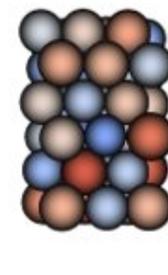


# Polydispersity (DEM)

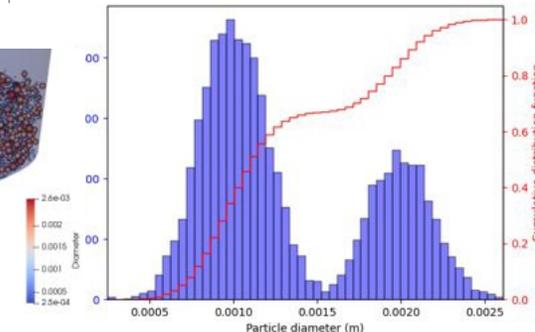
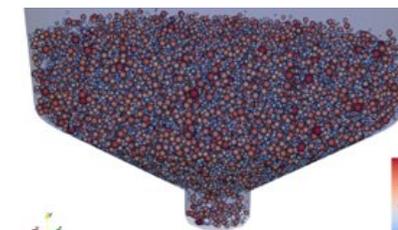
- Available in 20.3 Release (September 2020)
- Merge and complement ASU implementation
- Initial and Boundary (mass inflow) conditions
- DEM Particle size distribution
  - Normal
  - Log-normal
  - Custom (user-defined)
- Improvement in IC seeding
  - Robust
  - Lattice
  - Spacing
  - Flexibility in input
    - Volume fraction
    - Solid inventory
    - Particle count



Cubic lattice

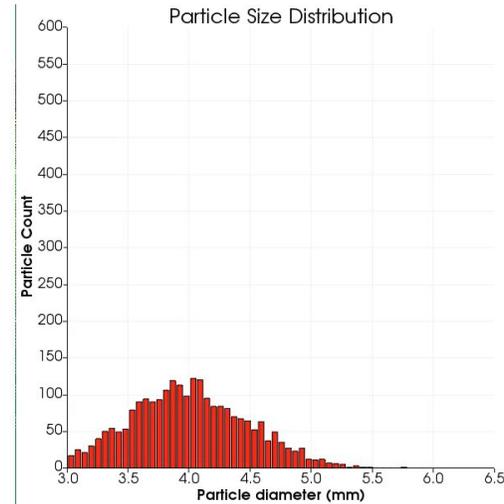
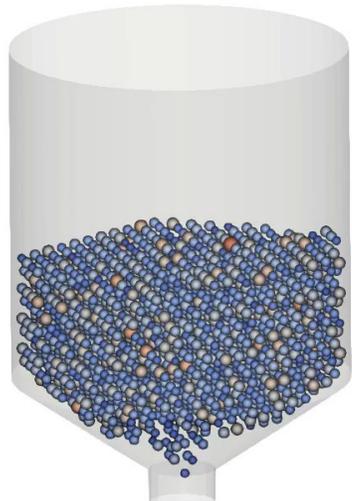
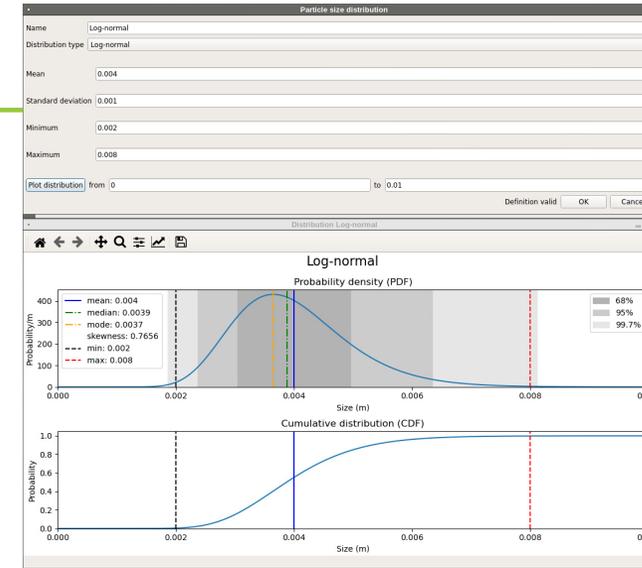


Hexagonal lattice

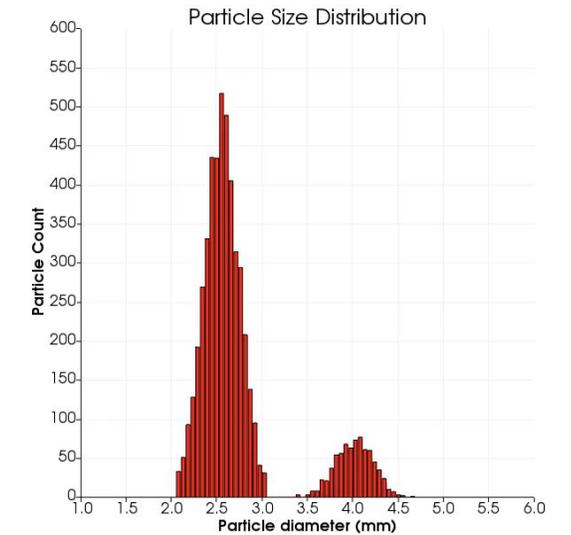
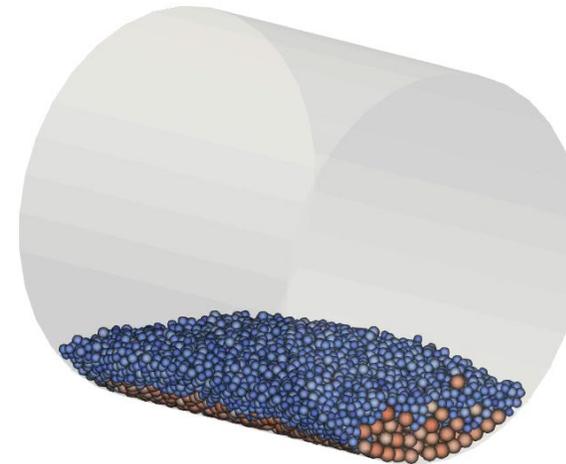


# Polydispersity (DEM)

## Polydispersity examples



Initial + Boundary Conditions



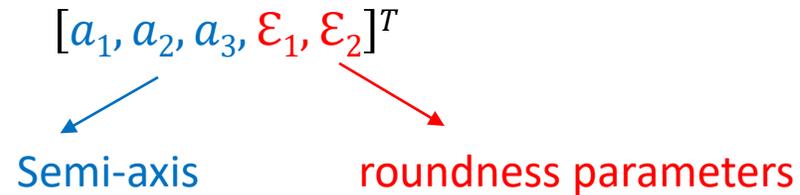
Particle coating

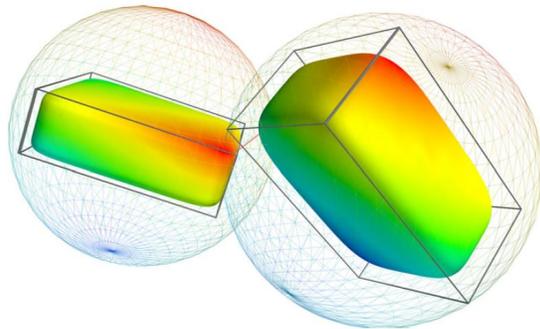
# Non-spherical particles (SuperDEM)

- Superquadrics are a family of geometric shapes defined as

$$\left[ \left( \frac{x}{a_1} \right)^{\frac{2}{\epsilon_2}} + \left( \frac{y}{a_2} \right)^{\frac{2}{\epsilon_2}} \right]^{\frac{\epsilon_1}{2}} + \left( \frac{z}{a_3} \right)^{\frac{2}{\epsilon_1}} = 1$$

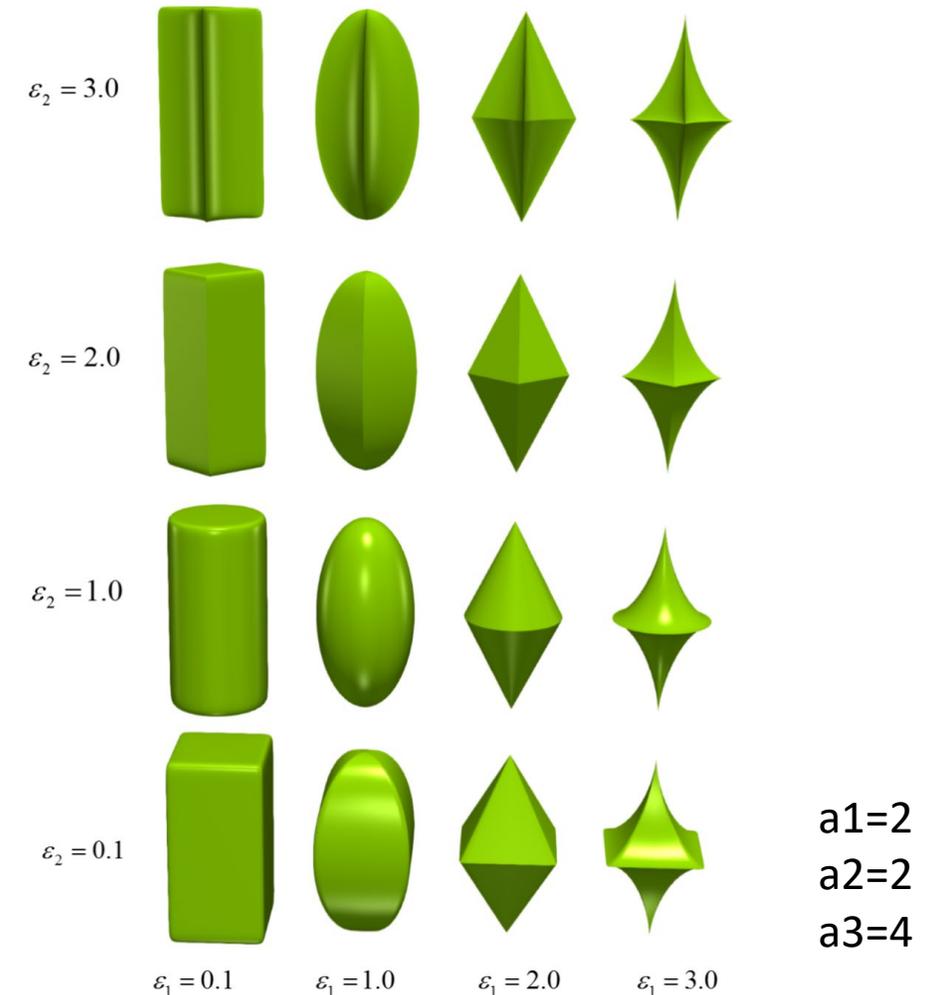
- Can represent ~ 80% of all shapes by varying **five parameters**

$[a_1, a_2, a_3, \epsilon_1, \epsilon_2]^T$   


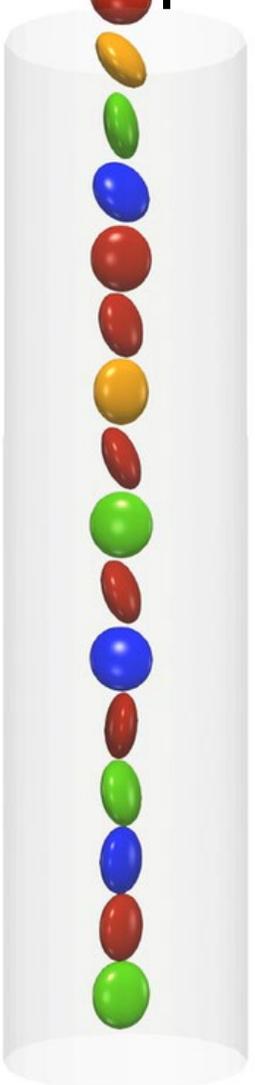


Bounding spheres and oriented bounding boxes

## Superquadric particles



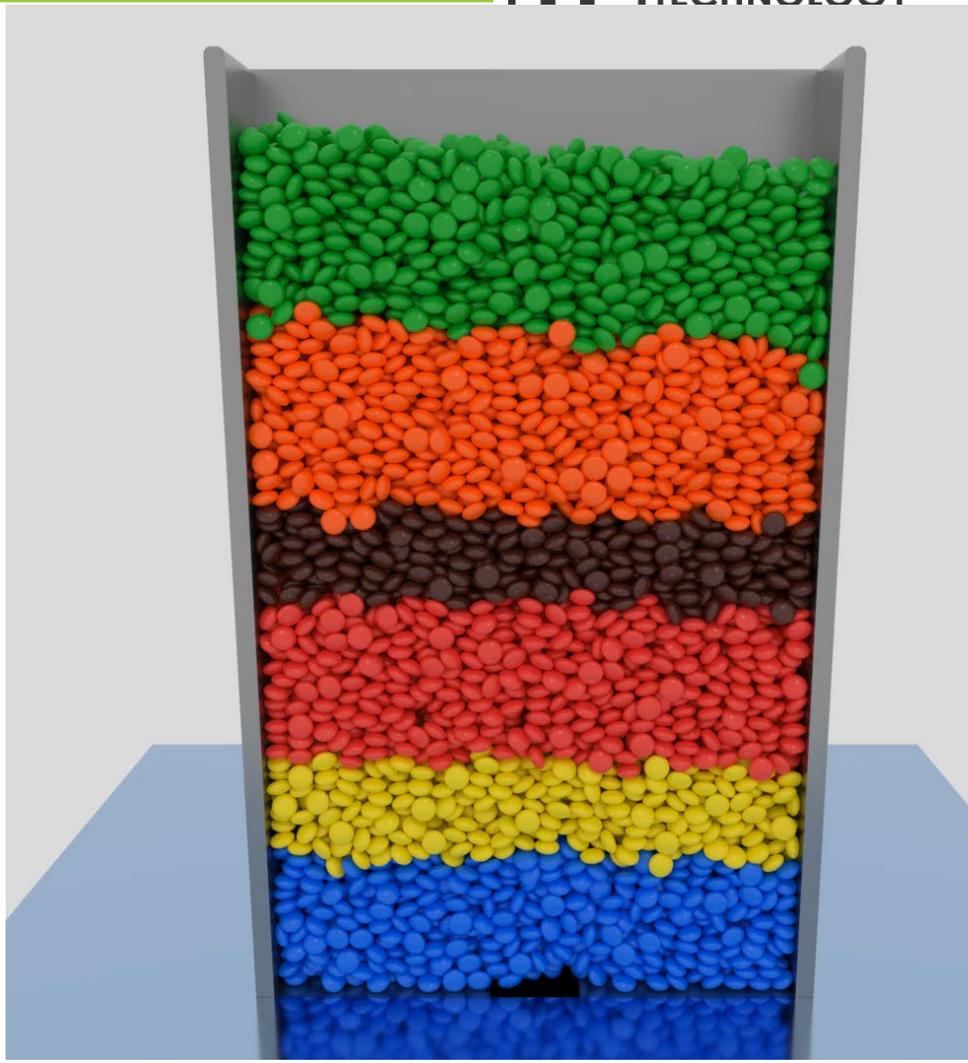
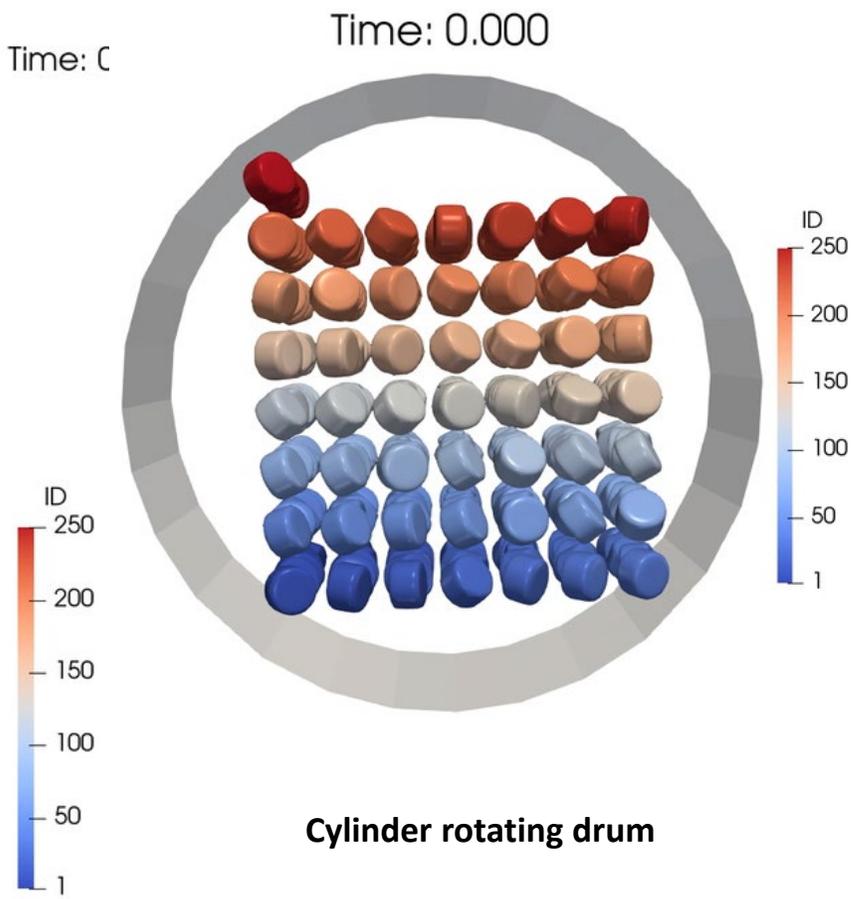
# SuperDEM examples



M&M candy static packing

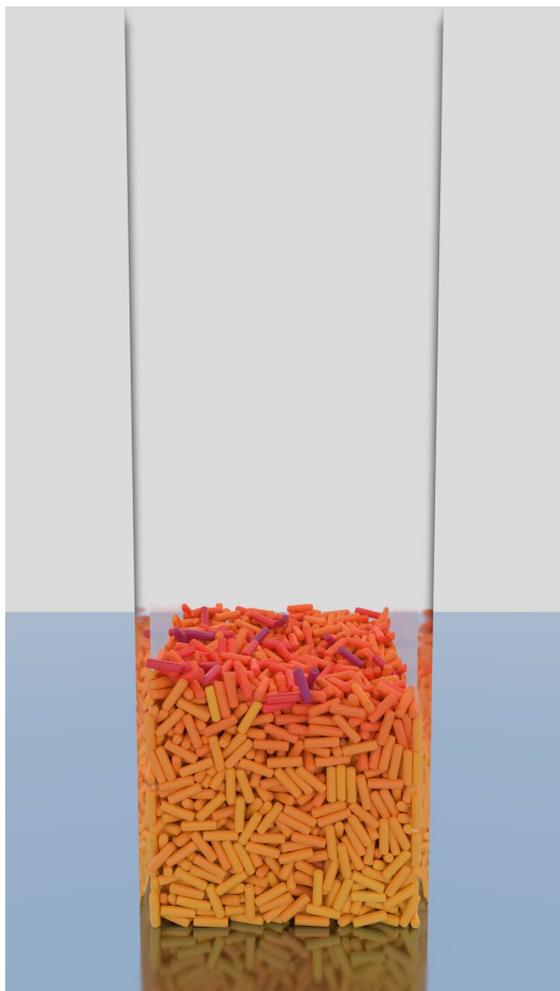
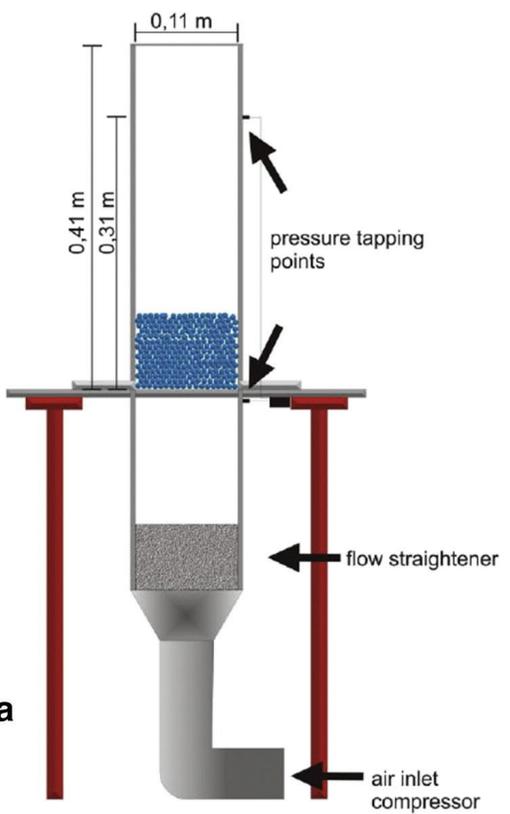


Cylinder candy static packing



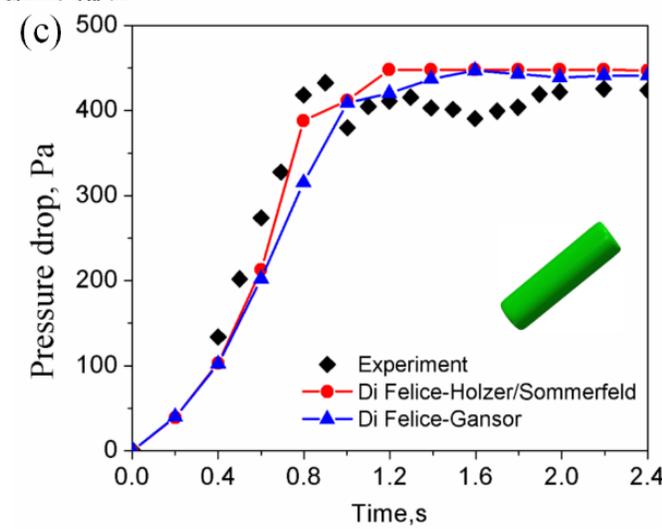
M&M candy discharging from a hopper

# Validation experiment



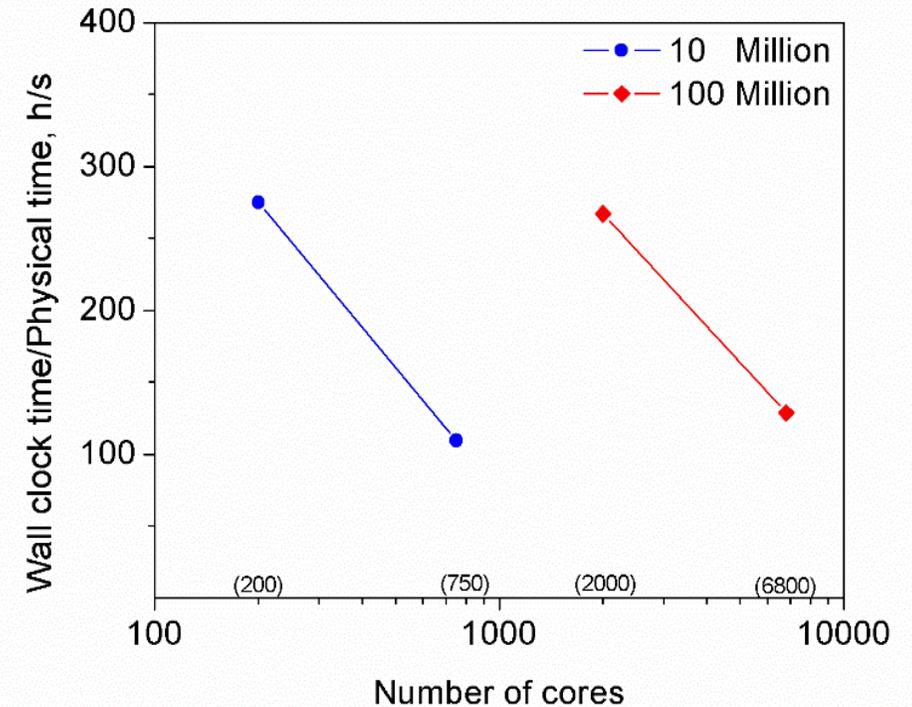
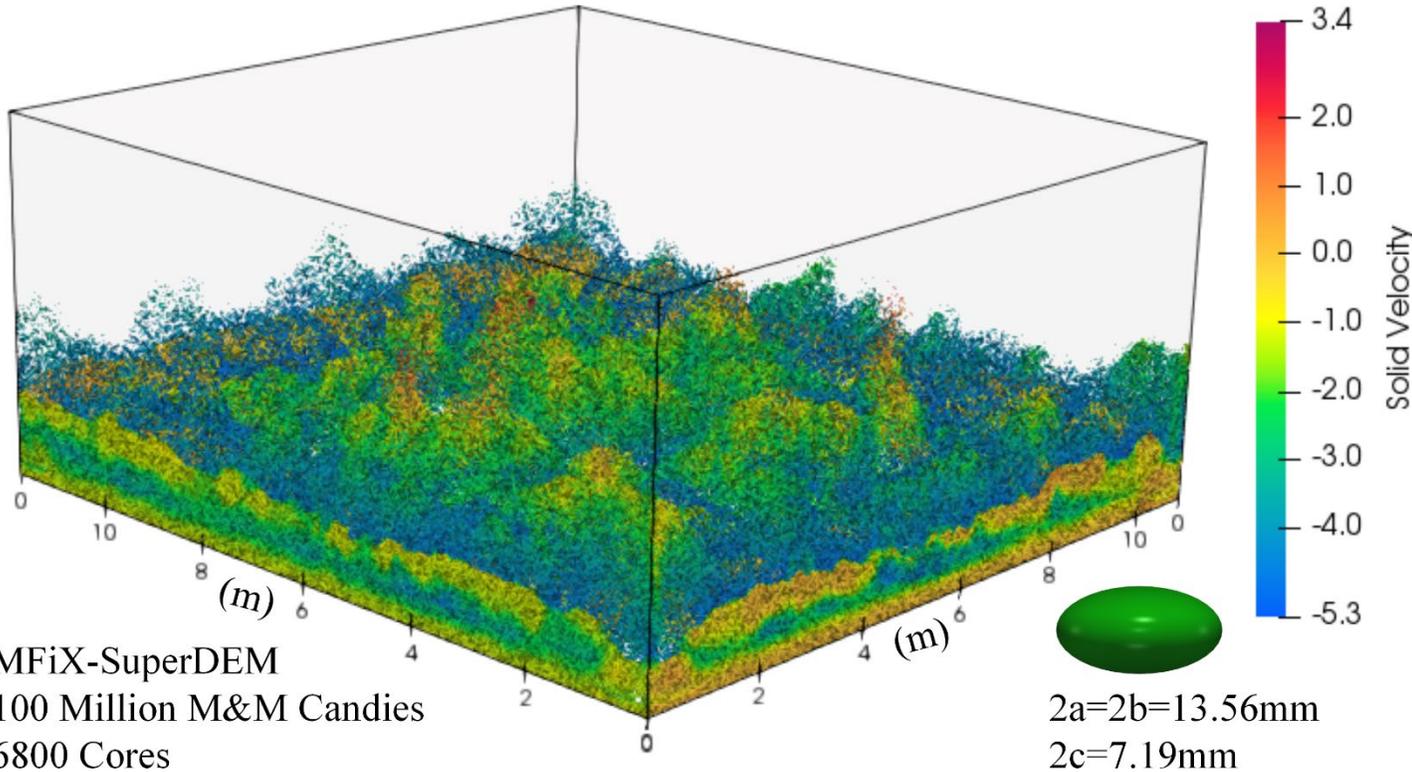
Particle properties including the volume equivalent diameter  $d_v$ -class, the particle dimensions, the sphericity  $\phi$ , the particle density  $\rho_p$ , the bed height  $L$  and the averaged porosity  $\epsilon$  for the initial, unfluidized setup.

Shape	Sphere	Sphere	Ideal Cylinder	Cube	Cube
$d_v$ -class [mm]	7	5	7	5	7
Size [mm]	7.2	5	6.1 6.2	4.2 4.3 4.5	5.2 6.3 6.3
$\phi$ [-]	1.00	1.00	0.87	0.81	0.80
$\rho_p$ [kg/m <sup>3</sup> ]	772.5	823.0	708.5	639.7	746.9
$L_{\text{th}}$ [mm]/ $\bar{\epsilon}$ [-]	95 0.40	88 0.40	98 0.36	98 0.37	103 0.43
Shape	Elongated Cylinder	Elongated Cuboid	Elongated Cuboid	Plate	Elongated Plate
$d_v$ -class [mm]	7	5	7	5	5
Size [mm]	3.9 14.0	3.0 3.0 7.1	4.2 4.2 11.4	2.0 4.9 6.0	2.0 4.0 8.0
$\phi$ [-]	0.75	0.75	0.73	0.71	0.69
$\rho_p$ [kg/m <sup>3</sup> ]	764.4	745.6	639.7	754.1	756.6
$L_{\text{th}}$ [mm]/ $\bar{\epsilon}$ [-]	103 0.44	103 0.42	115 0.40	102 0.43	108 0.46
Shape	Elongated Cuboid	Plate			
$d_v$ -class [mm]	5	7			
Size [mm]	2.0 3.0 11.0	2.2 9.0 9.8			
$\phi$ [-]	0.64	0.63			
$\rho_p$ [kg/m <sup>3</sup> ]	728.1	672.8			
$L_{\text{th}}$ [mm]/ $\bar{\epsilon}$ [-]	117 0.48	121 0.46			



Experiment: Vollmari K, Jasevičius R, Kruggel-Emden H. Experimental and numerical study of fluidization and pressure drop of spherical and non-spherical particles in a model scale fluidized bed. Powder Technology. 2016;291:506-521.

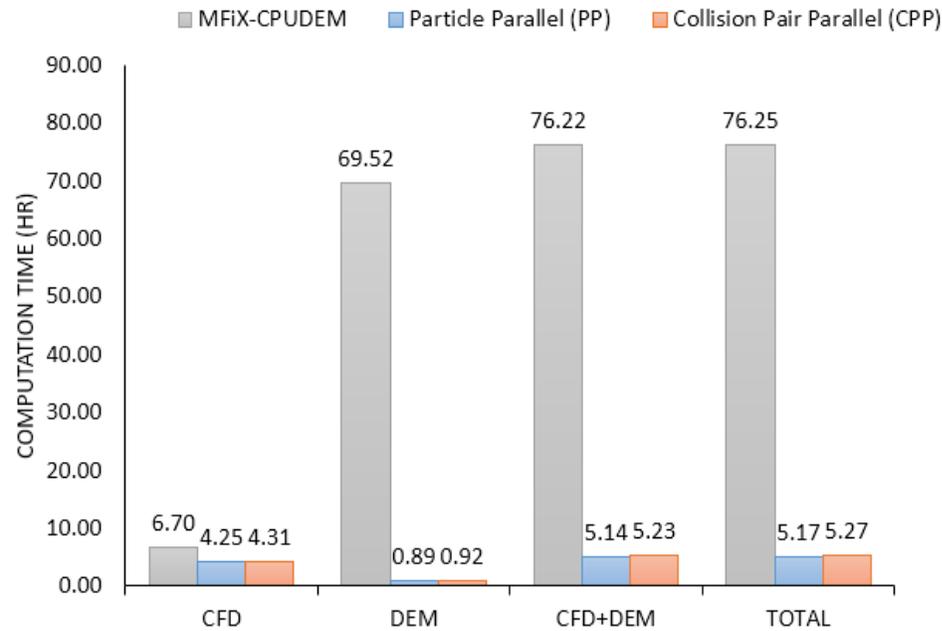
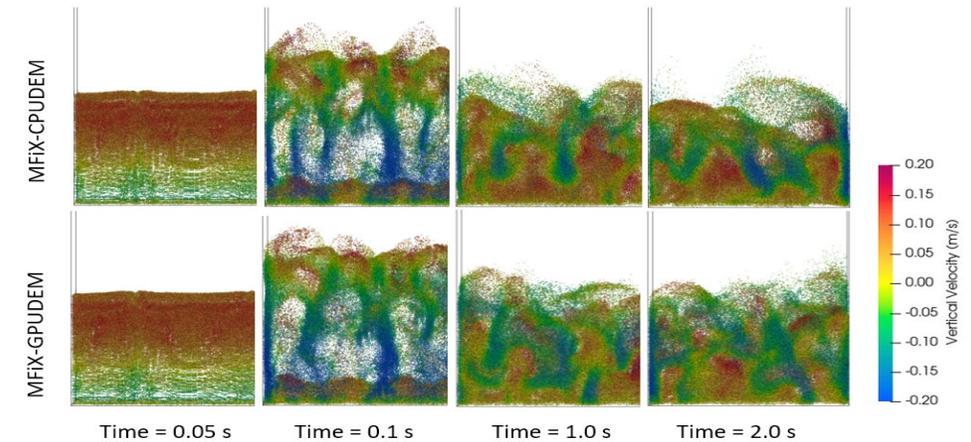
# Massively Parallel SuperDEM Simulation



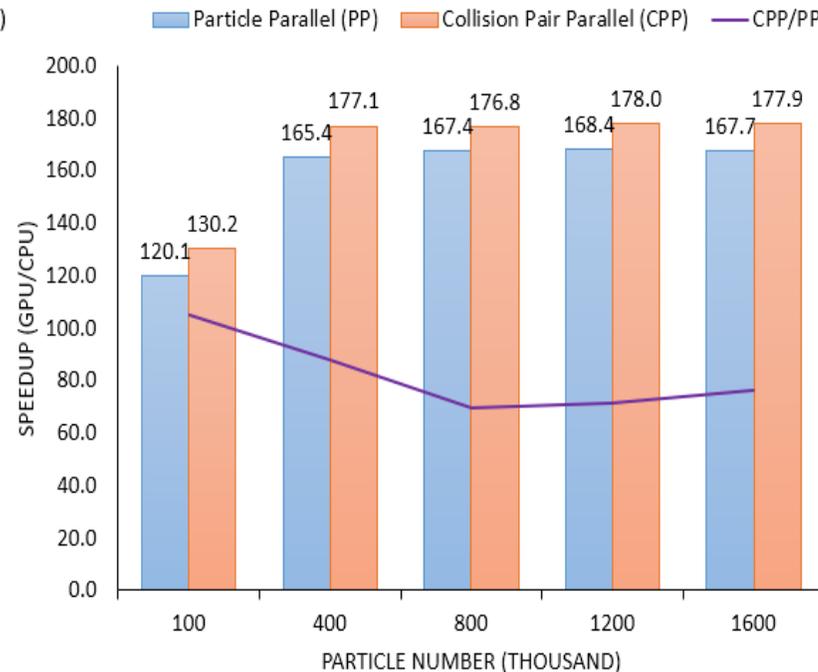
- The solver was parallelized using MPI.
- Simulation on NETL supercomputer Joule 2 (80K cores) , World Top 60, 2020
- Non-spherical particles fluidization simulation, **100 million (6800 cores)**

# Hundredfold Speedup of MFiX-DEM using GPU

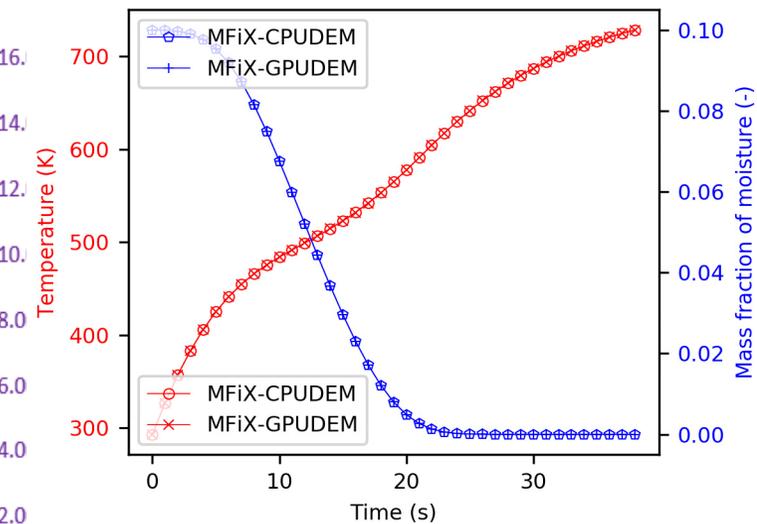
- DEM solver was ported to GPU (prototype)
- 170 fold speedup with double precision, 243 fold with single precision
- Re-use CFD, interphase coupling, and chemical reaction modules in MFiX



Fluidized bed Speedup



Particle packing Speedup



Heat transfer & chemical reactions (biomass drying)

# MFiX Quality Assurance

## Building Confidence in Simulation Results

- **Verification**

- Code verification – Does the code do what we expect?
- Solution verification – Is the answer any good?

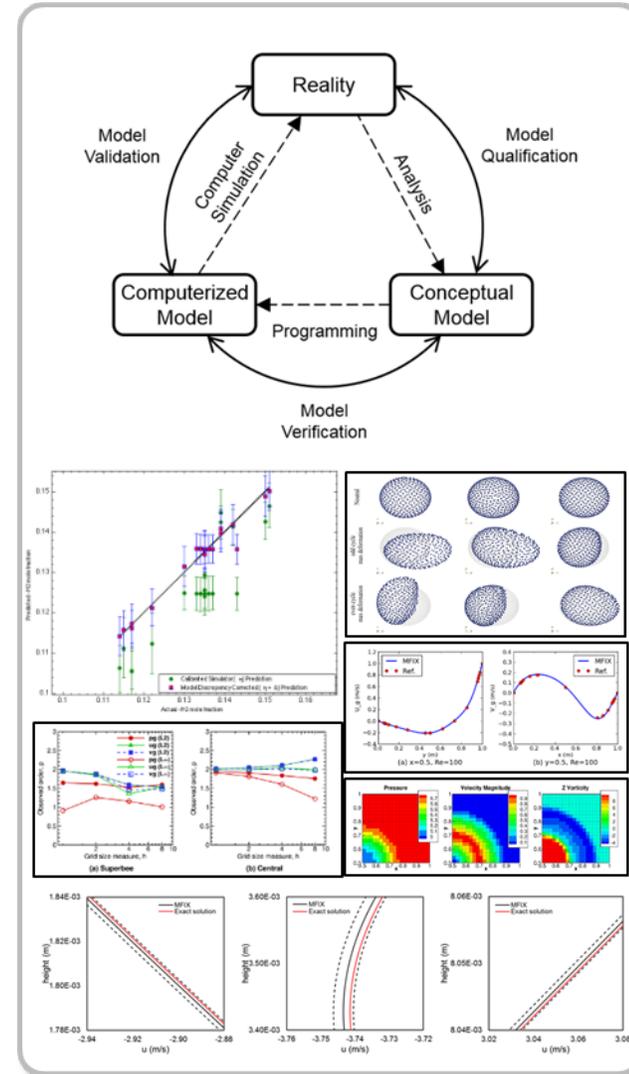
- **Validation** - How does the answer compare to the real world?

- **Uncertainty Quantification**

- Where is the error in my solution coming from?
- What happens to my answer when I change an input to my model?

### Accomplishments

- MFiX Verification and Validation Manual 2<sup>nd</sup> Ed. (PDF & html)
- PIC theory guide (May 2020)



# MFiX Quality Assurance

## Building Confidence in Simulation Results

- PIC parameter sensitivity and calibration
  - How sensitive are PIC simulations to PIC model parameters?
  - Recommend parameter values for a given type of application

### Cases selected to cover a broad range of flow conditions

- Particle Settling:  $U/U_{mf} < 1.0$  ( $P_0 \sim 1$ ) (Analytical solution)
- Bubbling Fluidized bed:  $U/U_{mf} \sim 1$  ( $P_0 \sim 10$ )
- Circulating Fluidized bed:  $U/U_{mf} \gg 1.0$  ( $P_0 \sim 100$ )

### Summary of model parameters used:

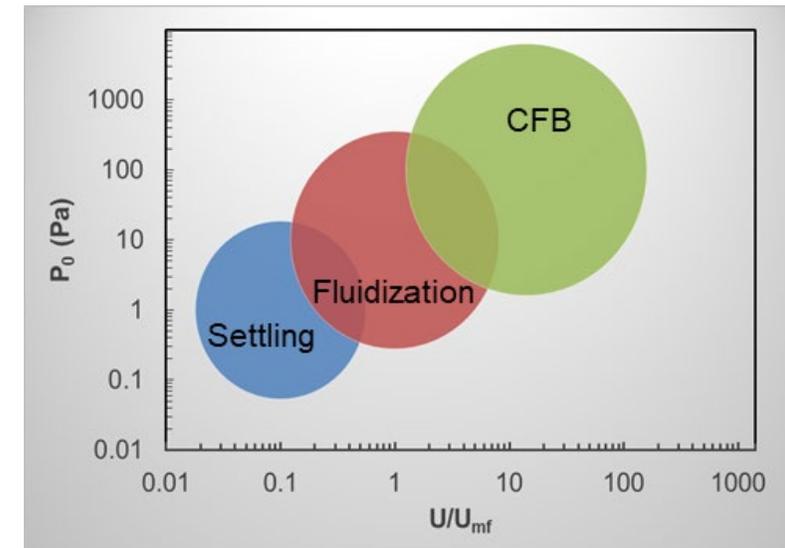
	t1 Pressure linear scale factor	t2 Volume fraction exponential scale factor	t3 Statistical weight	t4 Volume fraction at maximum packing	t5 Solid slip velocity factor
C1: Particle Settling	[1,20]	[2,5]	[3,20]	[0.35,0.5]	[0.5,1.0]
C2: Fluidization	[1,100]	[2,5]	[10,100]	[0.4,0.5]	[0.85,0.98]
C3: Circulating Fluidized Bed	[1,250]	[2,5]	[4]	[0.4,0.5]	[0.85,0.98]

\*Parameters selected based on prior sensitivity study

### Parcel momentum equation

$$\frac{d\vec{V}_p}{dt} = \beta(\vec{U}_g - \vec{V}_p) - \frac{1}{\rho_p} \nabla p - \frac{1}{\varepsilon_p \rho_p} \nabla \tau_p + \vec{g}$$

$$\tau_p = \frac{P_0 \varepsilon_p^\beta}{\max(\varepsilon_{cp} - \varepsilon_p, \delta(1 - \varepsilon_p))}$$



# C1: Particle settling

## Problem setup

Control variable: Initial solids concentration

Range: [0.05,0.25]

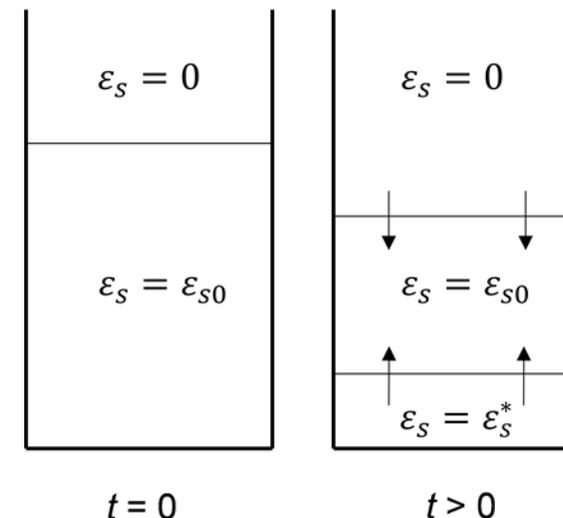
	x1 Initial solids concentration
C1: Particle Settling	[0.05,0.25]

Response variable: Location of filling shock (y2)

CFD results are compared with analytical solutions

Control variables: CFD (PIC parameters)

	t1 Pressure linear scale factor	t2 Vol. fraction exponential scale factor	t3 Statistical weight	t4 Vol. fraction at maximum packing	t5 Solid slip velocity factor
C1: Particle Settling	[1,20]	[2,5]	[3,20]	[0.35,0.5]	[0.5,1.0]



Analytical Solution:

Location of shock

$$x(t) = -t \left( \frac{\epsilon_s^* \epsilon_g^* u_r^* - \epsilon_{s0} \epsilon_{g0} u_{r0}}{\epsilon_s^* - \epsilon_{s0}} \right)$$

Rel. velocity  
(Stokes' drag)

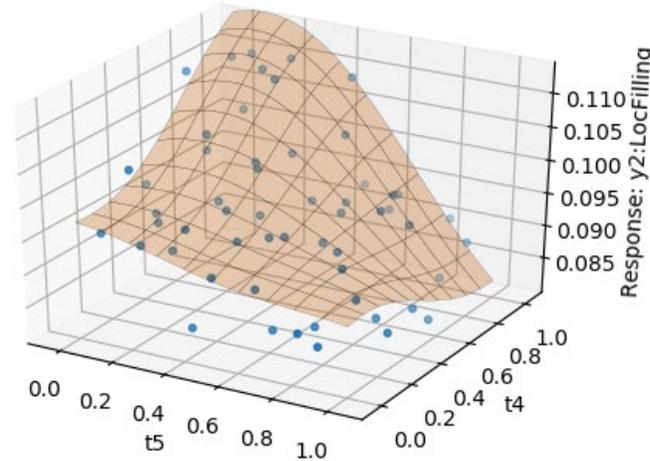
$$u_r = \frac{g \Delta \rho d_p^2}{18 \mu_g} \epsilon_g^{3.65}$$

# C1: Particle settling

## Sensitivity analysis and Deterministic calibration

Response surface constructed from 55 samples

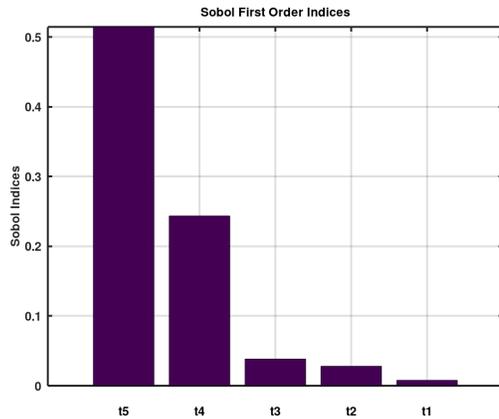
3D plot of the data-fitted surrogate model



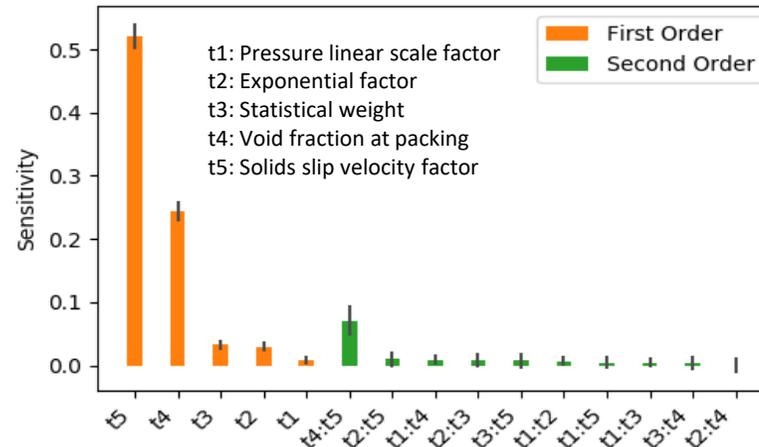
Sobol indices show the following:

- main effects (first order)
- interactive effects (second order)

Code-to-Code comparison with PSUADE



Sensitivity Analysis using Sobol Indices



Parameters obtained through deterministic calibration

Parameter	Default	Range	Calibrated
t1 Pressure linear scale factor	100	[1,20]	14.309
t2 Vol. fraction exponential scale factor	3.0	[2,5]	2.165
t3 Statistical weight	5.0	[3,20]	12.241
t4 Vol. fraction at maximum packing	0.42	[0.35,0.5]	0.399
t5 Solid slip velocity factor	1.0	[0.5,1.0]	0.828

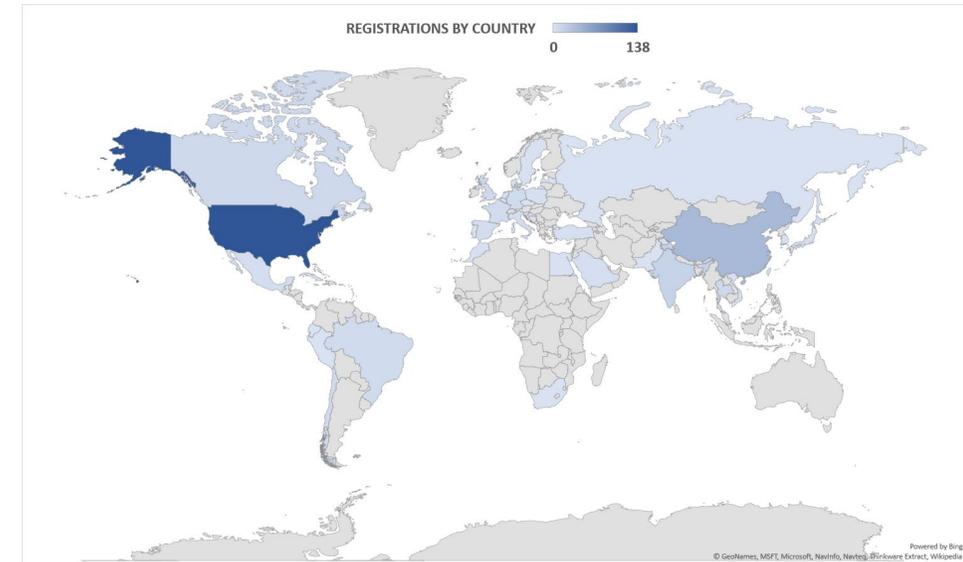
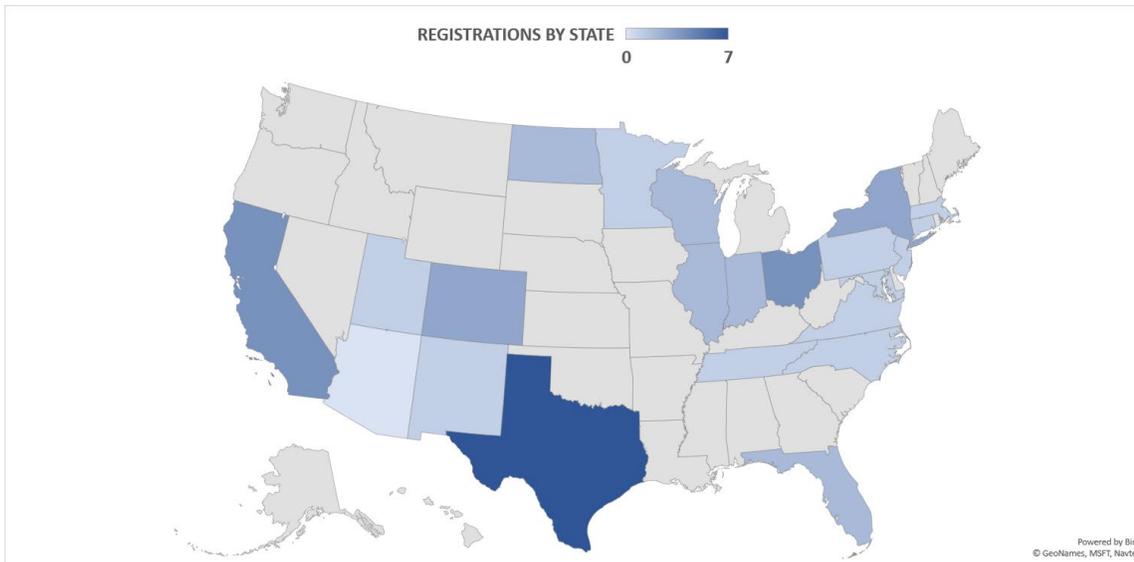
# Outreach: User base

## Still going strong amid pandemic crisis

Q2FY20 (Jan-March 2020) : 158 registrations, 831 MFiX Downloads

Q3FY20 (April-June 2020) : 161 registrations, 815 MFiX Downloads

All-time registrations = **6,264** (June 30<sup>th</sup> 2020)



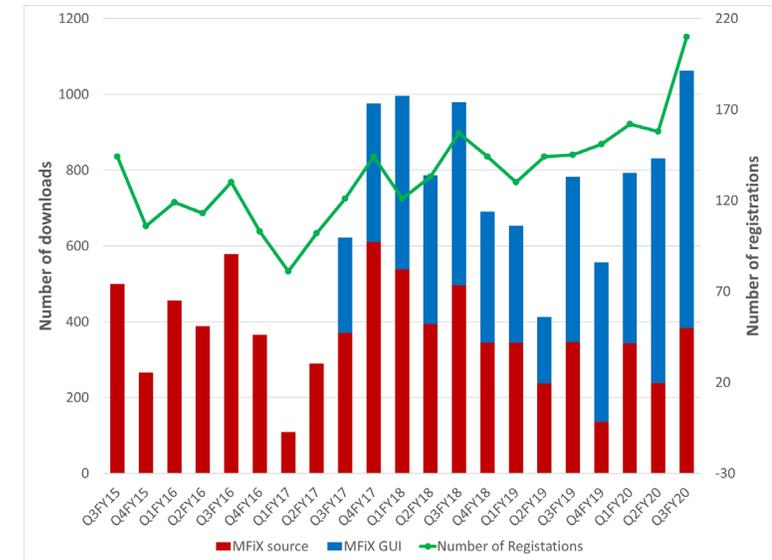
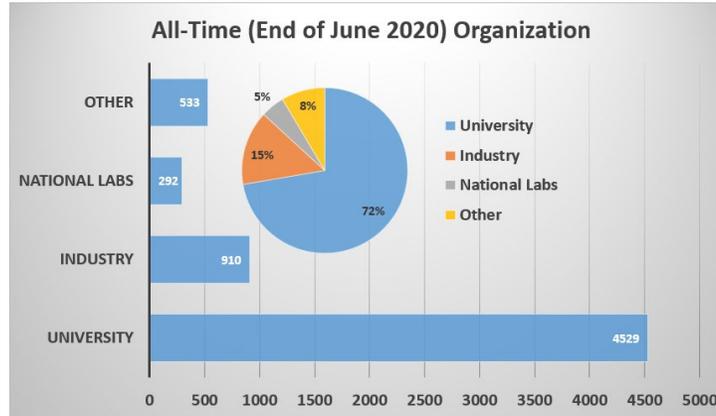
Registrations location (Q2FY20 + Q3FY20)

# Outreach: All-time MFiX Stats

## Stakeholders and Technology Transfer

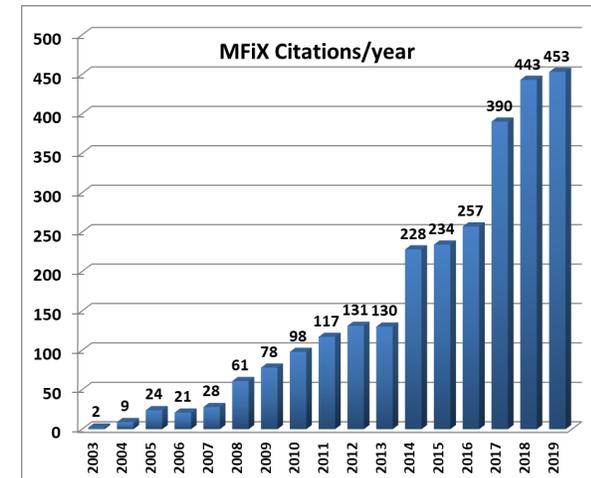
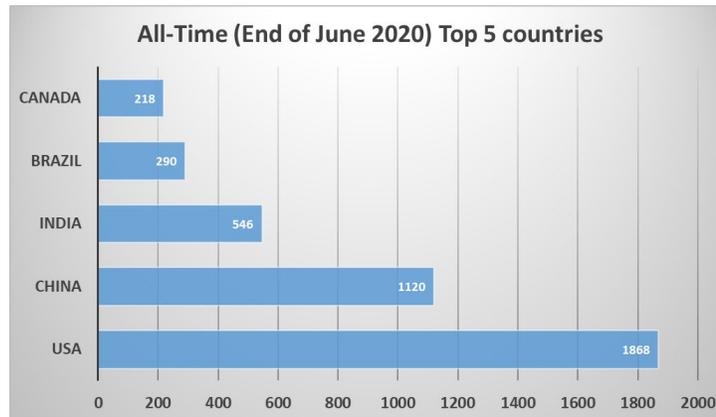
- All-time MFiX registrations = **6,264**

- University = 4,529
- Industry = 910
- Nat. Labs = 392
- Other = 533



- 81 countries, Top 5:**

- USA : 1,632
- China : 1,020
- India : 509
- Brazil : 268
- Canada : 196



# MFiX-How to get started?



- Website: <https://mfex.netl.doe.gov>
- Register
- Download / Install MFiX
- Read documentation
- Run tutorials / templates
- Decide best modeling approach for chosen application
- Review questions / Submit questions / report issues on the Forum
- New users are encouraged to use the GUI
- Advanced users/developers can use command line



User manual

V&V manual

Html and pdf

Text and video tutorials

3. Tutorials

- 3.1. Running First Tutorial
- 3.2. Two Dimensional Fluid Bed, Two Fluid Model (TFM)
- 3.3. Two Dimensional Fluid Bed, Discrete Element Model (DEM)
- 3.4. Three Dimensional Single phase flow over a sphere
- 3.5. Three Dimensional Fluidized Bed
- 3.6. Three Dimensional DEM Hopper
- 3.6.1. Create a new project
- 3.6.2. Select model parameters
- 3.6.3. Enter the geometry
- 3.6.4. Enter the mesh
- 3.6.5. Create regions for initial and boundary condition specification
- 3.6.6. Create a solid
- 3.6.7. Create Initial Conditions
- 3.6.8. Create Boundary Conditions
- 3.6.9. Select output options
- 3.6.10. Run the project
- 3.6.11. View results
- 3.7. DEM Granular Flow Chutes
- 4. Model Guide
- 5. Building the Solver
- 6. Running the Solver

Docs » 3. Tutorials » 3.6. Three Dimensional DEM Hopper [View page source](#)

## 3.6. Three Dimensional DEM Hopper



This tutorial shows how to create a three dimensional granular flow DEM simulation. The model setup is:

Property	Value
geometry	5 cm diameter hopper
mesh	10 x 25 x 10
solid diameter	0.003 m
solid density	2500 kg/m <sup>2</sup>

MFiX  
Second Edition

Search docs

VALIDATION AND VERIFICATION

1. Introduction
2. Method of Manufactured Solutions
3. Fluid Model Code Verification Test Cases
4. MFiX-DEM Code Verification Test Cases
  - 4.1. DEM01: Freely-falling particle
  - 4.2. DEM02: Bouncing particle
  - 4.3. DEM03: Two stacked, compressed particles
  - 4.4. DEM04: Slipping on a rough surface
  - 4.5. DEM05: Oblique particle collision
    - 4.5.1. Description
    - 4.5.2. Setup
    - 4.5.3. Results
  - 4.6. DEM06: Single particle, terminal velocity
5. Appendix
6. References

Docs » 4. MFiX-DEM Code Verification Test Cases » 4.5. DEM05: Oblique particle collision

[View page source](#)

## 4.5. DEM05: Oblique particle collision

This case serves to verify the normal and tangential components of both the linear spring-dashpot and Hertzian collision models in MFiX DEM. This case is based on the modeling work of Di Renzo and Di Maio [15] and utilizes the experimental data of Kharaz, Gorham, and Salman [10].

### 4.5.1. Description

In the experiments of Kharaz, Gorham, and Salman [10], a spherical particle is dropped from a fixed height such that it collides with a rigid surface at a known velocity. The angle of the ridged surface is varied to test impact angles ranging from normal to glancing. The rebound angle, post-collision angular velocity, and observed tangential restitution coefficient were reported.

In the experiment, the particle strikes an angled anvil as illustrated in Fig. 4.11 (a). Rather than modeling an angled surface, the wall is kept level (flat) and the particle is given an initial trajectory corresponding to the angle found in the experiment as shown in Fig. 4.11 (b). The particle is initially positioned close to the wall and gravity is suppressed in the simulations to eliminate the effects of the rotated geometry with respect to the experimental apparatus.

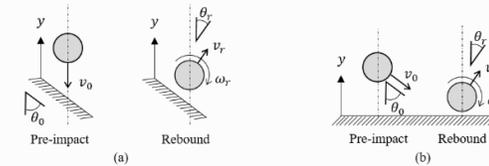


Fig. 4.11 Experimental setup of Kharaz, Gorham, and Salman [10] of a particle striking a fixed, angled anvil. (b) Simulation setup whereby the particle is given an initial velocity to replicate the particle striking an angled surface.

### 4.5.2. Setup

## User support

## Categories

- Installation
- How to
- Bug report
- Share

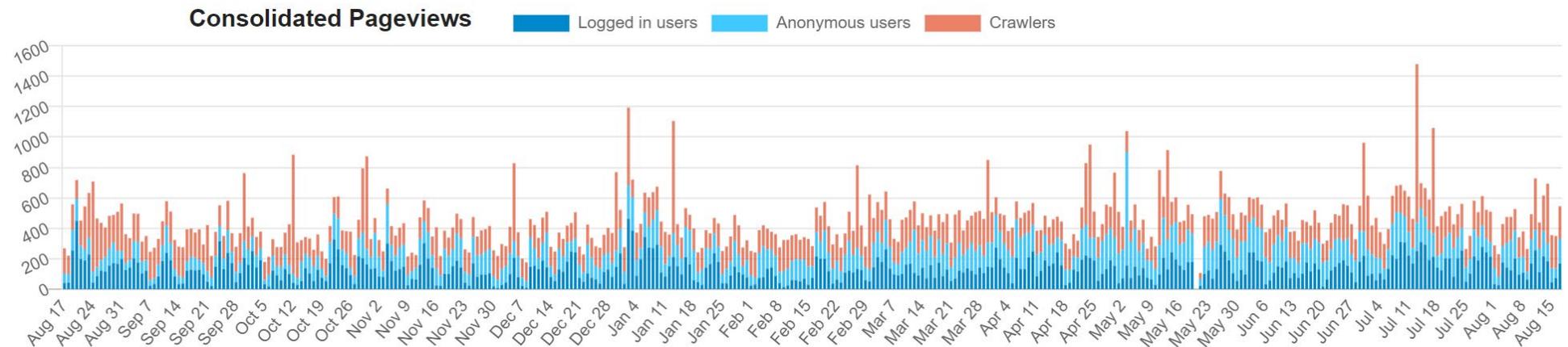
## Topics (threads)

## File attachment

## Searchable

The screenshot shows the MFiX Forum interface. At the top, there's a navigation bar with 'all categories', 'all', 'Categories', 'Latest', 'Unread (1)', and 'Top'. A search icon and a user profile icon are also present. Below the navigation, there's a table of categories:

Category	Topics	Latest
<b>Develop</b> This is a private category for developer's discussion. It is the equivalent of the develop mailing list.	4	
<b>MFiX</b> Ask questions, report bugs, and share what you are working on! Installation How to Bug report Share	179 1 unread	<b>E</b> Installation problem for MFiX-19.1 MFiX 4h <b>J</b> About vtk output! Bug report 3h <b>Z</b> Results of dem? MFiX 2h 14h
<b>Nodeworks</b> Ask questions, report bugs, and share what you are working on! Installation How to Bug report Share	2	<b>M</b> How i can track single particle trajectory in dem? MFiX 5h 1d <b>C</b> How to output the drag force particle by particle? 1h 2d



# Acknowledgment

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*This work was performed in support of the US Department of Energy's Fossil Energy Crosscutting Technology Research Program. The Research was executed through the NETL Research and Innovation Center's Advanced Reaction Systems. Research performed by Leidos Research Support Team staff was conducted under the RSS contract 89243318CFE000003.*

*This work was funded by the Department of Energy, National Energy Technology Laboratory, an agency of the United States Government, through a support contract with Leidos Research Support Team (LRST). Neither the United States Government nor any agency thereof, nor any of their employees, nor LRST, nor any of their employees, makes any warranty, expressed or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise, does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.*

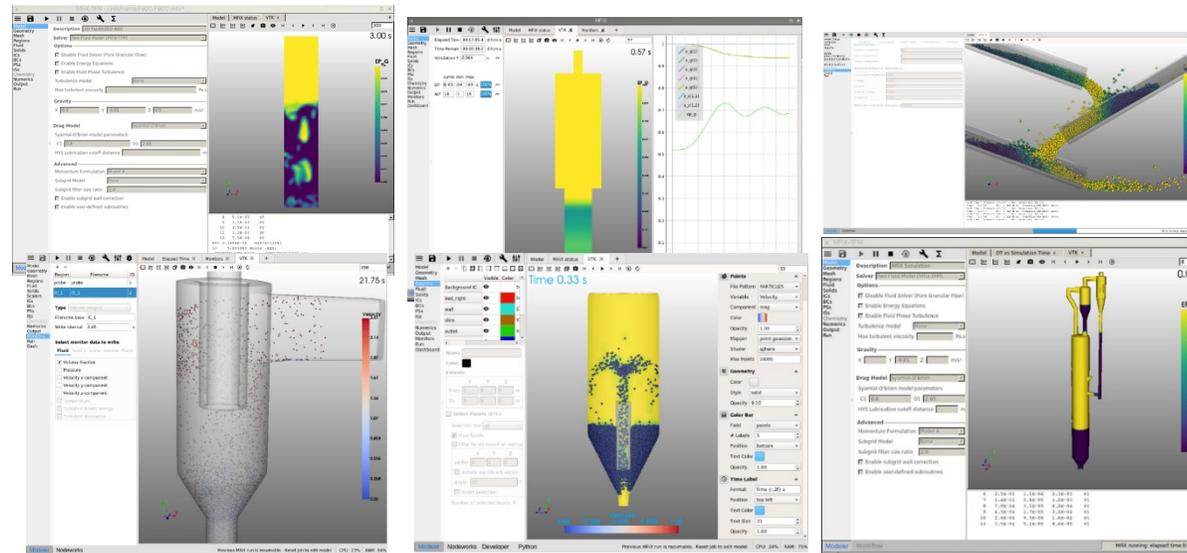
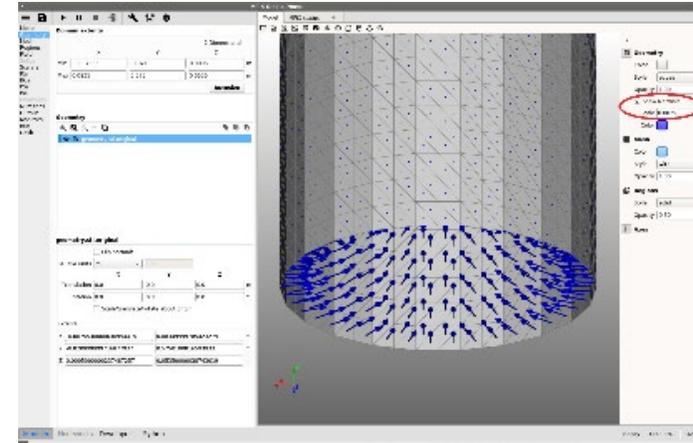
# Preprocessor development

User setup (.mfx file) greatly improved by GUI

Increased demand for complex geometry

Mesh generation

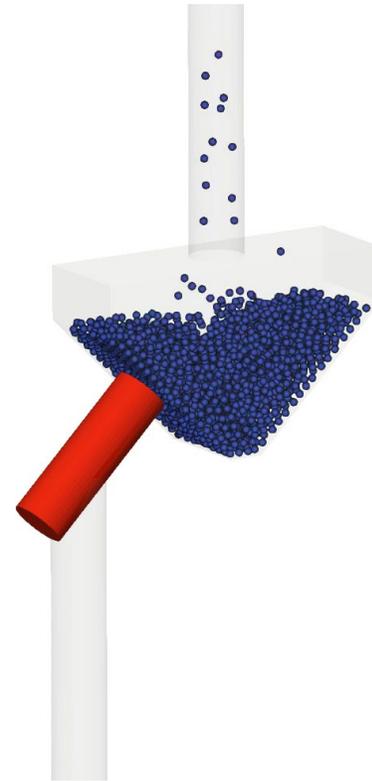
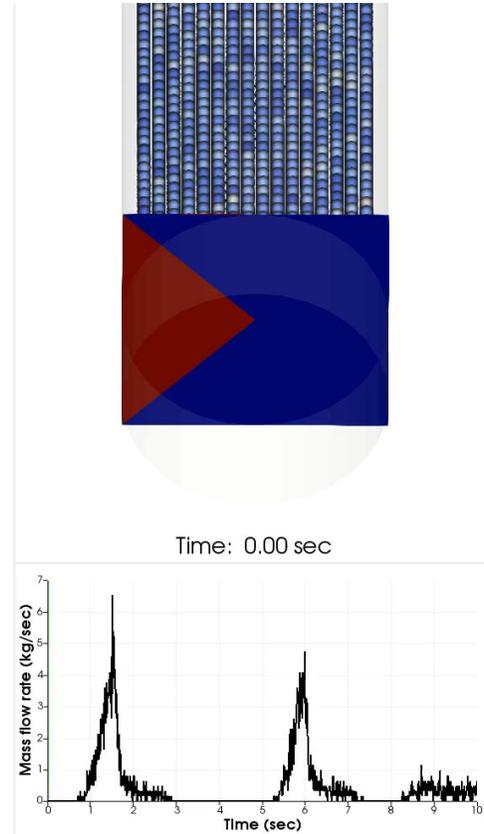
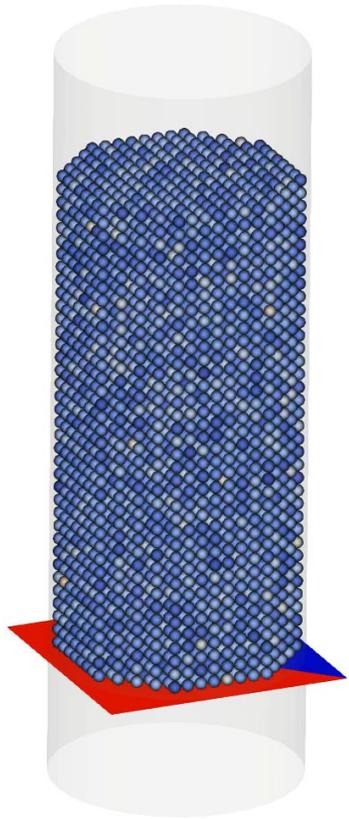
- Workflow challenge
- Geometry input (STL file)
- Preprocessing (cut cells)
- Mesh quality
- Difficult to troubleshoot
- Specific constrains for TFM, DEM and PIC



# Moving geometry

## Several options to represent moving geometry

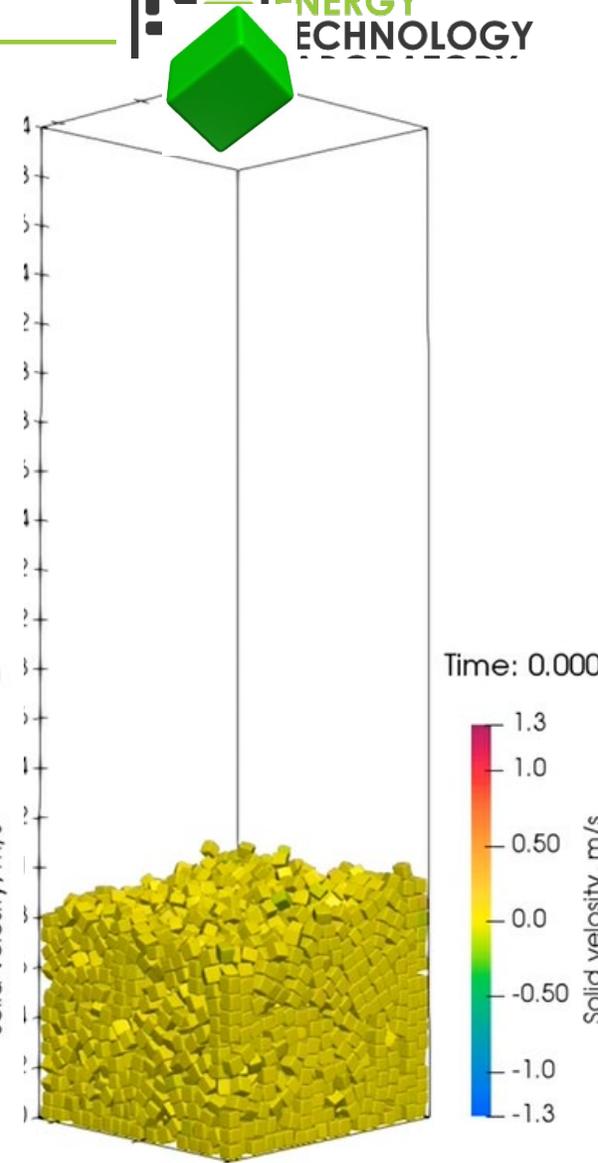
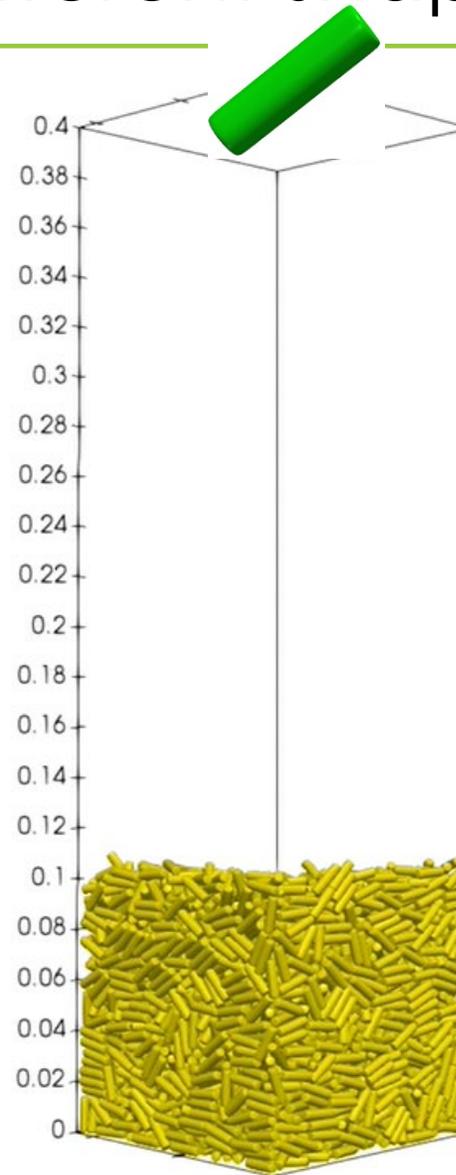
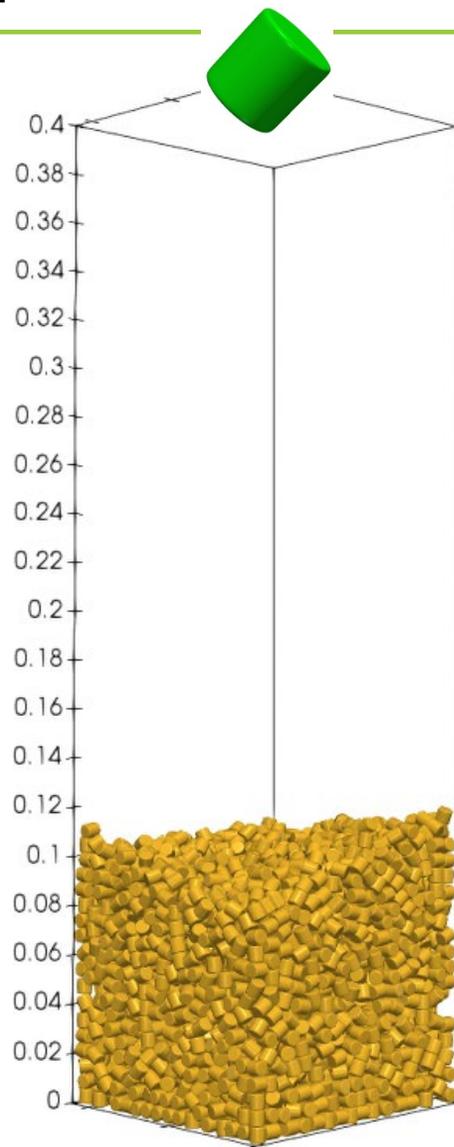
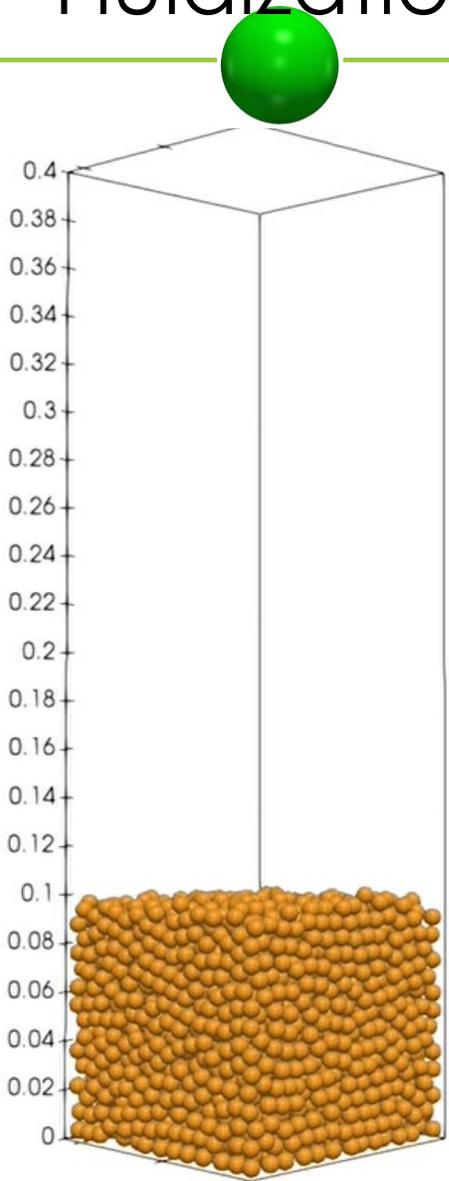
- Ability to control flow rate



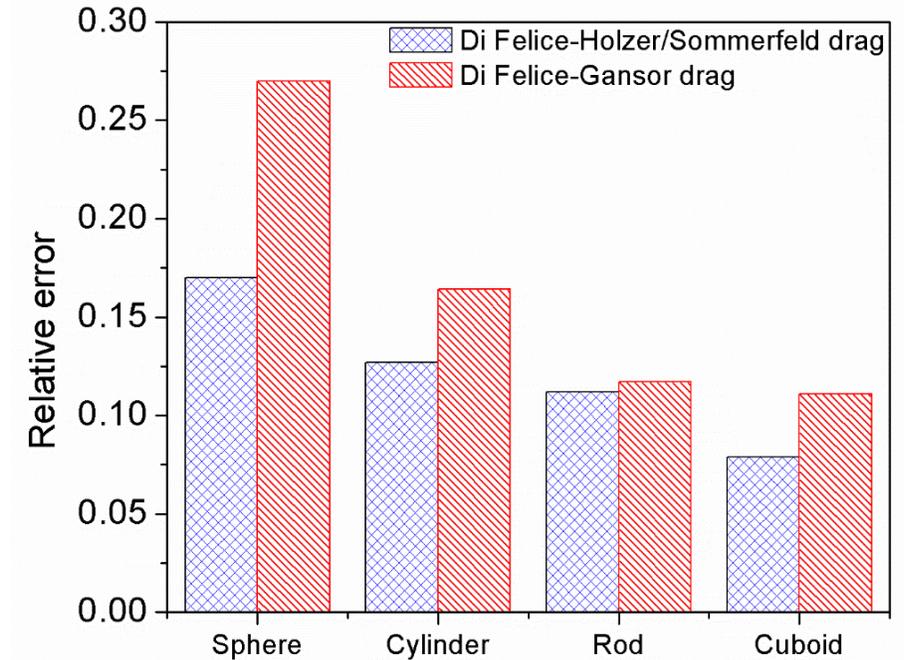
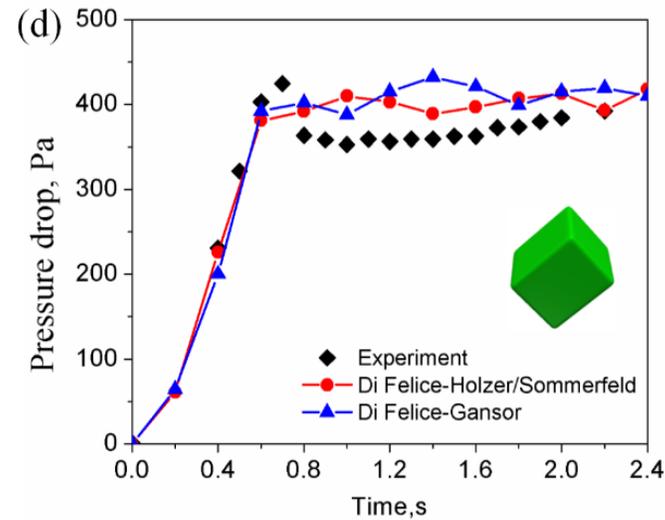
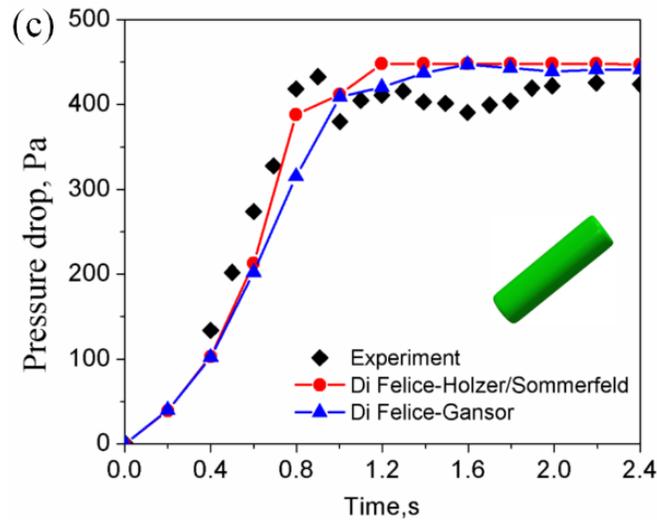
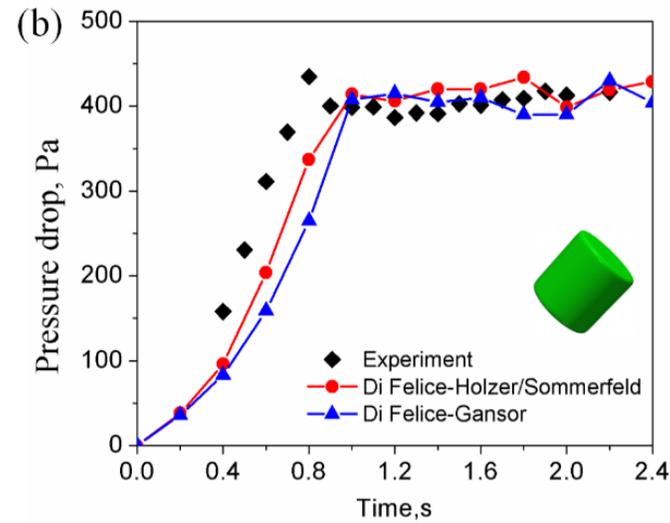
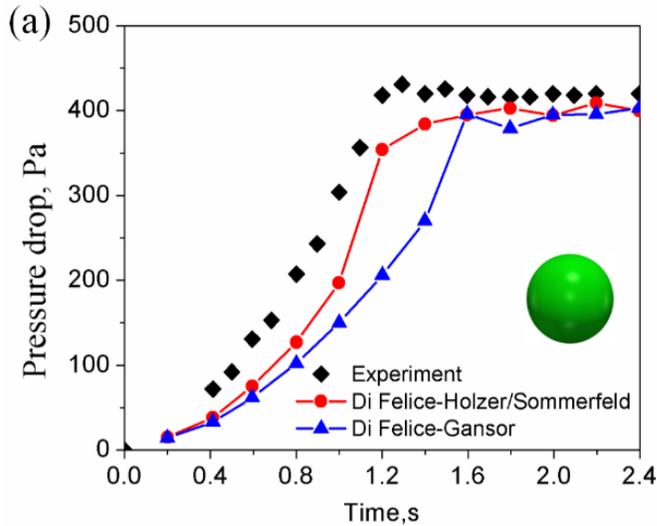
Time: 0.00 s

# Fluidization of particles with different shapes

$U_g = 1.6 \text{ m/s}$



# Validation-Pressure drop



- Both drag models consider the effects of particle orientation and cell voidage
- Di Felice-Holzer/Sommerfeld drag correctly capture the pressure in both fixed bed and fluidized bed regimes for each shape particles.
- Unresolved SuperDEM-CFD can not capture the channeling flow. Particle-resolved DEM-CFD may be tested in the future.

# SuperDEM development progress



## • Summary

- Oriented bounding box (OBB) algorithm has been implemented and verified
- Superquadric contact algorithm has been implemented and verified
- Quaternion theory for object orientation (rotation between local and global) has been implemented and verified
- VTP (xml) was modified to output tensor for superquadric particle visualization
- Superquadric particle collision with wall (plane, STL)
- Non-linear forces between superquadric particles
- Parallelization (MPI)
- 100 million non-spherical particles large scale simulation on 6800 cores
- A new interpolation scheme (DPVM-Satellites) was developed.
- Non-spherical drag models (Di Felice-Gansor and Di Felice Holzter/SommerFeld) considering particle orientation and cell voidage were implemented
- A new general scheme to calculate the projection area of non-spherical particle perpendicular to the flow was developed.
- 100 million non-spherical particles fluidization simulation on 6800 cores

## • Future work

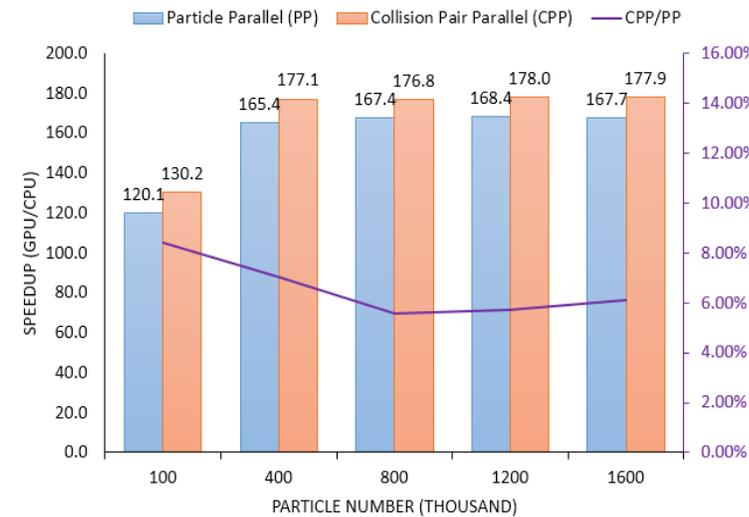
- Heat transfer, mass transfer, chemical reaction
- Coupling with other sub-models
- Multi-superquadric particles to model moving internals, such as baffle, moving wall, etc.
- Advanced superquadric contact algorithm

# Hundredfold Speedup of MFiX-DEM using GPU Computation

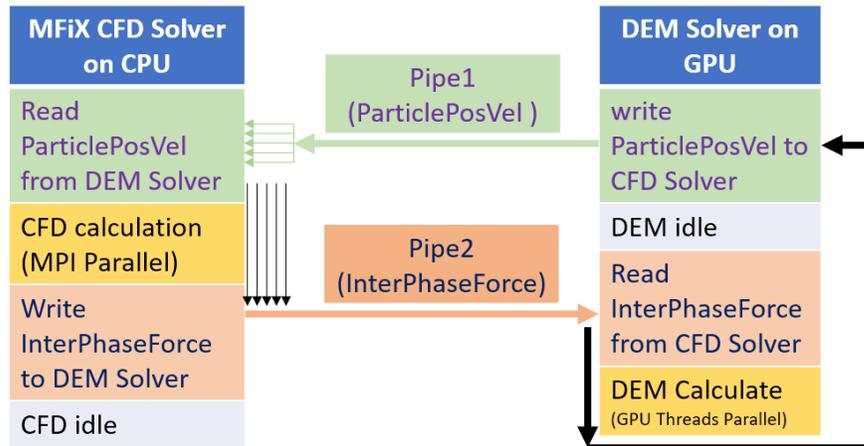
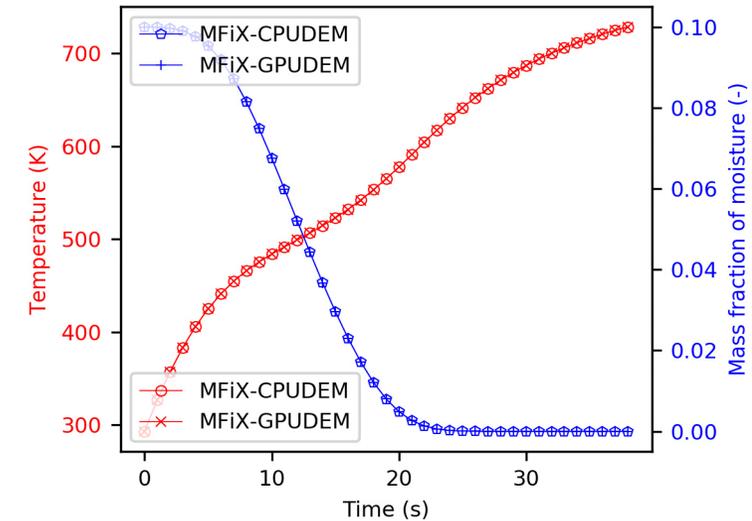
## GPU Solver & MFiX coupled solver

X	Start	Allocate memory, generate/read particles
Generate neighbor list	storeTOoverlapToUnsortedArray	Store tangential overlap based on unsorted particle ID
	calcHash	Map particles into searching cells
	sortParticles	Sort particles based on ID of cells.
	reorderDataAndFindCellStart	1) Rearranging particle data into sorted arrays. 2) Mark the first and last particles in each cell
	generateNeighborList	1) For each particle, calcBinPos, loop over particles in each neighbor bin, store neighbor particles 2) copy tangential overlaps
collide		1) collision with neighbor particles 2) collision with boundaries
	updatePosVelOmg	Update pos/vel/omega
X	End	Release memory

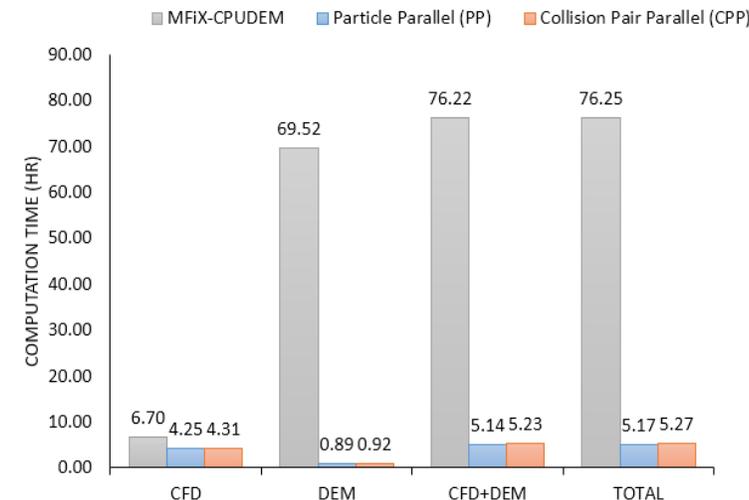
## Speedup in Simulations of particle packing (up) & Fluidized bed (bottom)



## Heat transfer & chemical reactions (biomass drying)



Algorithm of GPU-MFiX data exchange through pipes. Multiple small arrow lines on CPU side indicate MPI parallel processes. DEM is limited to one GPU card.



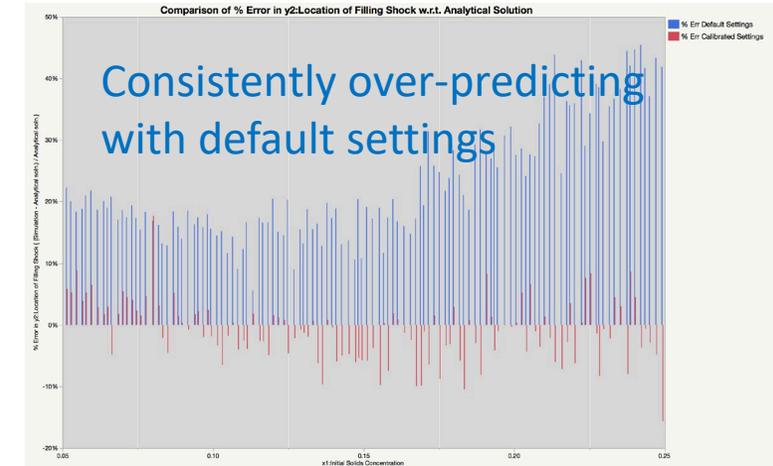
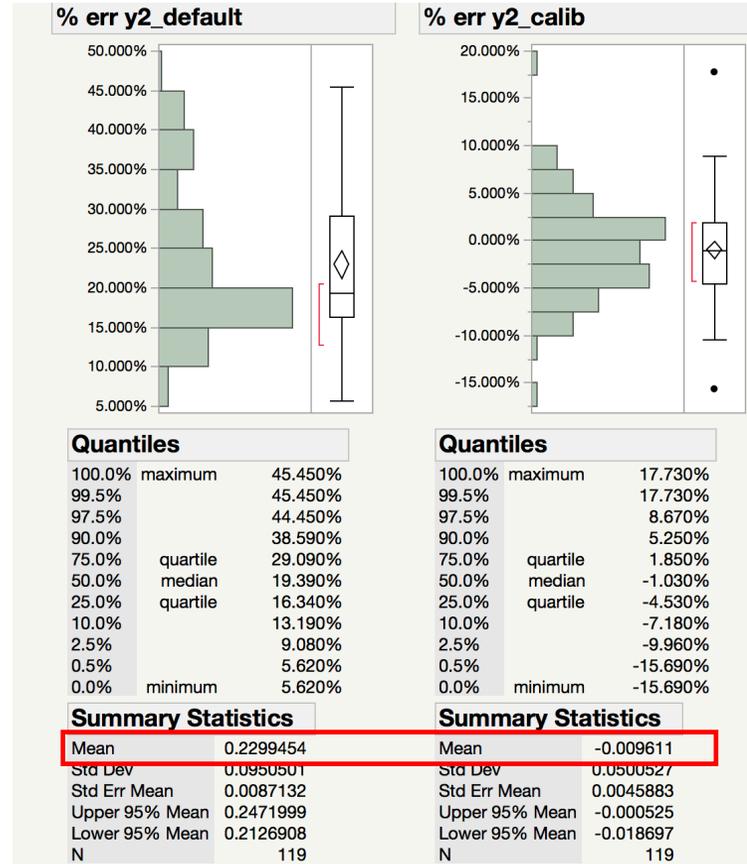
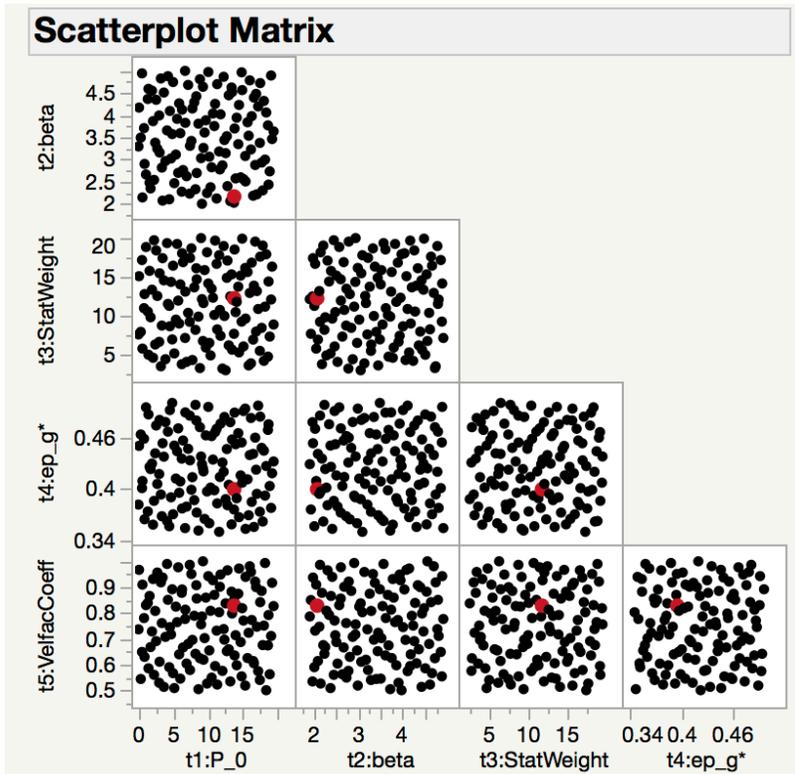
- DEM solver is ported to GPU
- 170 fold speedup with double precision, 243 fold with single precision
- Re-use CFD, interphase coupling, and chemical reaction modules in MFiX

# C1: Particle settling

## Deterministic calibration (using 120 samples and PSUADE)

Testing calibrated parameters at “unseen” settings

Comparing Distribution of % Error (Default vs Calibrated Settings)



22.99%  
vs  
-0.96%

With calibrated settings for all 5 parameters both over-predicting with default settings