FT3L core datasheet

Grid Asset Performance > Next Generation Transformers

Hitachi FT-3TL core uses nanocrystalline soft magnetic material FINEMET® suitable for medium frequency transformers, especially in high-power applications. It contributes to downsize and improves efficiency in transformers. Low core loss and high saturation flux density for effective power transforming.

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Fig. 1: Core under test.

Dimensions

Table 1: Core dimensions.

Description	Symbol	Finished dimension (mm)
Width of core	A	180
Height of core	В	240
Depth of core (or cast width)	D	30
Thickness or build	E	50
Width of core window	F	80
Height of core window	G	140



Fig. 2: Illustration of core dimensions.

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Magnetic Characteristics

Table 2: Core physical characteristics.

Description	Symbol	Typical value	Unit
Effective area	A_{e}	1,125	mm²
Mean magnetic path length	L _m	575	mm
Weight	Weight	4.7	kg
Permeance/inductance per turn	A_L	39.3 (±30%)	μH/N²
Max core loss @ 0.1T	P _C	2.9	W
Saturation flux density	B _{sat}	1.2	Т
Effective volume	V _e	646875	mm ³
Core stacking factor	k_{f}	0.75	Dimensionless

Measurement Setup





(a)









Fig. 4: Square waveform core loss test system (CLTS) (a) conceptual setup (b) actual setup.

Arbitrary and square waveform core loss test systems (CLTS) are utilized to characterize soft magnetic materials, which are shown in Fig. 3 and Fig. 4, respectively. Fig. 5 illustrates three different excitation voltage waveforms and corresponding flux density waveforms. In the arbitrary waveform CLTS, a function generator generates any arbitrary small signal, and the small signal is amplified and applied to a core under test (CUT) using a linear amplifier. The arbitrary waveform CLTS is advantageous in that any waveforms can be easily applied to characterize a CUT; however, the linear amplifier has limited electrical capabilities, such as ±75V & ±6A peak ratings and 400V/µs slew rate. Therefore, a full core characterization may not be possible in some cases, such as low permeability cores, high frequency, and/or large sized cores. The arbitrary waveform CLTS is utilized to perform various square waveform measurements with different duty cycles, as shown in Fig. 5(b) and (c). 1200V SiC MOSFET devices are utilized to extend the core characterization range.

Two windings are placed around the core under test. The amplifier excites the primary winding, and the current of the primary winding is measured, in which the current information is converted to the magnetic field strengths H as

$$H(t) = \frac{N_p \cdot i(t)}{l_m} , \qquad (1)$$

where N_p is the number of turns in the primary winding. A dc-biasing capacitor is inserted in series with the primary winding to provide zero average voltage applied to the primary winding.

The secondary winding is open, the voltage across the secondary winding is measured, in which the voltage information is integrated to derive the flux density B as

$$B(t) = \frac{1}{N_s \cdot A_e} \int_0^T v(\tau) d\tau , \qquad (2)$$

where N_s is the number of turns in the secondary winding, and T is the period of the excitation waveform.

In Fig. 5(a), the excitation voltage is sinusoidal, and its flux waveform is also a sinusoidal shape. In Fig. 5(b), the excitation voltage is a two-level square waveform with asymmetrical duty cycle between high-level and low-level voltages, and its flux waveform is a sawtooth shape. It is hereafter referred as asymmetrical waveform. Its duty cycle is defined as



Fig. 5: Excitation voltage waveforms and corresponding flux density waveforms (a) Sinusoidal excitation with sinusoidal flux, (b) Asymmetrical excitation with sawtooth flux, and (c) Symmetrical excitation with trapezoidal flux.

the ratio between the applied high voltage time and the period, and the duty cycle can range from 0% to 100%. Furthermore, the average excitation voltage is adjusted to be zero via the dc-biasing capacitor, and thus, the average flux is also zero. In Fig. 5 (c), the excitation voltage is a three-level square voltage with symmetrical duty cycle between high-level and low-level voltages, and its flux waveform is a trapezoidal shape. It is hereafter referred as symmetrical waveforms. Its duty cycle is defined as the ratio between the applied high-level voltage time and the period, and the duty cycle can range from 0% to 50%. At 50% duty cycles, both the asymmetrical and symmetrical waveforms become identical.

Core losses at various frequencies and induction levels are measured using various excitation waveforms. Based on measurements, the coefficients of the Steinmetz's equation are estimated. The Steinmetz's equation is given as

$$P_{w} = k_{w} \cdot \left(f / f_{0} \right)^{\alpha} \cdot \left(B / B_{0} \right)^{\beta} , \qquad (3)$$

where P_w is the core loss per unit weight, f_0 is the base frequency, B_0 is the base flux density, and k_w , α , and β are the Steinmetz coefficients from empirical data. In the computation of P_w , the weight before impregnation in Table 2 is used, the base frequency f_0 is 1 Hz, and the base flux density B_0 is 1 Tesla.



Fig. 6: BH curve as a function of frequency.

Fig. 6 illustrates the measured BH curve at different frequencies. The field strength *H* is kept near constant for all frequency. At 5 kHz and 10 kHz excitations, the BH curve is similar, which indicates that the hysteretic losses are the dominant factor at frequencies below 5 kHz. As frequency increases, the BH curves become thicker, which indicates that the eddy current and anomalous losses are becoming larger.

	k _w	A	β
sine	4.60301004642584e-05	1.39468034842719	2.05765721687426
Square 50% duty	9.22817131405644e-06	1.57895862291895	2.96808224330713
Asymmetrical 40% duty	6.10034128104189e-06	1.62277870937581	3.06411897778253
Asymmetrical 30% duty	6.74575303677176e-06	1.62030628410133	2.95418655971996
Asymmetrical 20% duty	5.35936922374620e-06	1.65495143286460	2.71055284641337
Asymmetrical 10% duty	1.41102085911408e-05	1.57499569290072	2.12321581274459
Symmetrical 40% duty	1.11185976069850e-05	1.57758004535130	2.71321994937254
Symmetrical 30% duty	1.01910427135361e-05	1.60598858605388	2.64722227688454
Symmetrical 20% duty	1.85663584584057e-05	1.56469000170295	2.28989365330761
Symmetrical 10% duty	2.69835756686002e-05	1.56153699791516	2.09658336758682

Table 3: Steinmetz coefficients.



Fig. 7: Estimated core losses of sine and square excitation at various flux density, frequency, and duty cycle.



Fig. 8: Core loss measurements and estimations via Steinmetz equation: (a) Sine (b) Square at 50% duty.



Fig. 9: Core loss measurements and estimations via Steinmetz equation of asymmetrical square waveform excitation: (a) 40% duty (b) 30% duty (c) 20% duty (d) 10% duty.



Fig. 10: Core loss measurements and estimations via Steinmetz equation of symmetrical square waveform excitation: (a) 40% duty (b) 30% duty (c) 20% duty (d) 10% duty.

The permeability of the core is measured as functions of flux density and frequency. Following figures illustrate the measured absolute relative permeability μ_r values, which is defined as

$$\mu_r = \frac{B_{peak}}{\mu_0 \cdot H_{peak}} \tag{4}$$

where B_{peak} and H_{peak} are the maximum flux density and field strength at each measurement point. Under certain excitation conditions, the core could not be saturated due to lack of available voltages. For example, the sine excitation is performed using the arbitrary CLTS, and its voltage is limited to ± 75 V. Furthermore, the square CLTS could not saturate the core during the highest frequency and 10% duty cycle.



Fig. 11 Sinusoidal excitation: relative permeability as a function of flux density and frequency (left column) and BH loop at the maximum B of the corresponding frequency (right column) (* could not saturate the core under the condition).



Fig. 12: Square excitation with 50% duty cycle: relative permeability as a function of flux density and frequency (left column) and BH loop at the maximum B of the corresponding frequency (right column).



Fig. 13: Asymmetrical excitation with various duty cycle: relative permeability as a function of flux density and frequency (left column) and BH loop at the maximum B of the corresponding frequency (right column) (a) 40% duty (b) 30% duty (c) 20% duty (d) 10% duty (* could not saturate the core under the condition).



Fig. 14: Symmetrical excitation with various duty cycle: relative permeability as a function of flux density and frequency (left column) and BH loop at the maximum B of the corresponding frequency (right column) (a) 40% duty (b) 30% duty (c) 20% duty (d) 10% duty (* could not saturate the core under the condition).



Fig. 15: Measured BH curve and fitted anhysteretic BH curve as functions of H and B

Table 4: Anhysteretic curve coefficients for B as a function of H.

k	1	2	3	4
$m_k^{}$	1.56515767341055	-0.0351169534483996	0.661161875122230	0.353567458458664
h_{k}	74.9868505793837	34.0980241013168	63.1435618320739	45.1082360733275
n _k	1	4.99999984973286	2.54267243853586	4.83318459475986

Table 5: Anhysteretic curve coefficients for H as a function of B.

k	1	2	3	4
μ_r	31643.8738416898			
α_k	0.590171287250857	0.590171287250857	0.590171287250857	0.590171287250857
β_k	78.0469534287607	78.0469534287607	78.0469534287607	78.0469534287607
γ_k	1.56539814076458	1.56539814076458	1.56539814076458	1.56539814076458
δ_k	0.00756174663229553	0.00756174663229553	0.00756174663229553	0.00756174663229553
ε_k	8.71494381444516e-54	8.71494381444516e-54	8.71494381444516e-54	8.71494381444516e-54
ζ_k	1	1	1	1



Fig. 16: Absolute relative permeability as function of field strength H.



Fig. 17: Absolute relative permeability as function of flux density B.



Fig. 18: Incremental relative permeability.

Fig. 15 illustrates the measured low frequency BH loops at 100 Hz. Using the outer most BH loop, the anhysteretic BH curve is fitted. The anhysteretic BH curves can be computed as a function of field intensity H using the follow formula.

$$B = \mu_{H}(H)H$$

$$\mu_{H}(H) = \mu_{0} + \sum_{k=1}^{K} \frac{m_{k}}{h_{k}} \frac{1}{1 + |H/h_{k}|^{n_{k}}}$$
(5)

Similarly, the anhysteretic BH curves can be computed as a function of flux density B using the follow formula. $P_{\text{res}}(B) U$

$$B = \mu_{B}(B)H$$

$$\mu_{B}(B) = \mu_{0} \frac{r(B)}{r(B)-1}$$

$$r(B) = \frac{\mu_{r}}{\mu_{r}-1} + \sum_{k=1}^{K} \alpha_{k} |B| + \delta_{k} \ln\left(\varepsilon_{k} + \zeta_{k} e^{-\beta_{k}|B|}\right)$$

$$\delta_{k} = \frac{\alpha_{k}}{\beta_{k}}, \varepsilon_{k} = \frac{e^{-\beta_{k}\gamma_{k}}}{1+e^{-\beta_{k}\gamma_{k}}}, \zeta_{k} = \frac{1}{1+e^{-\beta_{k}\gamma_{k}}}$$
(6)

Table 4 and Table 5 lists the anhysteretic curve coefficients for eqs. (5) and (6), respectively.

The core anhysteretic characteristic models in eqs. (5) and (6) are based on the following references.

Scott D. Sudhoff, "Magnetics and Magnetic Equivalent Circuits," in *Power Magnetic Devices: A Multi-Objective Design Approach*, 1, Wiley-IEEE Press, 2014, pp.488-

G. M. Shane and S. D. Sudhoff, "Refinements in Anhysteretic Characterization and Permeability Modeling," in *IEEE Transactions on Magnetics*, vol. 46, no. 11, pp. 3834-3843, Nov. 2010.

The estimation of the anhysteretic characteristic is performed using a genetic optimization program, which can be found in the following websites:

https://engineering.purdue.edu/ECE/Research/Areas/PEDS/go_system_engineering_toolbox

Core Characteristic Variation as a Function of Temperature

At this time, the core temperature is not monitored, and this version of data sheet does not have this information. However, in future editions, it is planned to be included.